]-7 MACHINE MODEL SERIAL No. PC600-7 20001 and up 20001 and up PC600LC-7

- This shop manual may contain attachments and optional equipment that are not available in your area. Please consult your local Komatsu distributor for those items you may require. Materials and specifications are subject to change without notice.
- PC600, 600LC-7 mount the KOMATSU SA6D140E-3 engine. For details of the engine, see the 140-3 Series Engine Shop Manual.

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SAFETY SAFETY NOTICE

IMPORTANT SAFETY NOTICE

Proper service and repair is extremely important for safe machine operation. The service and repair techniques recommended by Komatsu and described in this manual are both effective and safe. Some of these techniques require the use of tools specially designed by Komatsu for the specific purpose.

To prevent injury to workers, the symbol \bigwedge is used to mark safety precautions in this manual. The cautions accompanying these symbols should always be followed carefully. If any dangerous situation arises or may possibly arise, first consider safety, and take the necessary actions to deal with the situation.

GENERAL PRECAUTIONS

Mistakes in operation are extremely dangerous. Read the Operation and Maintenance Manual carefully BEFORE operating the machine.

- 1. Before carrying out any greasing or repairs, read all the precautions given on the decals which are fixed to the machine.
- When carrying out any operation, always wear safety shoes and helmet. Do not wear loose work clothes, or clothes with buttons missing.
 - Always wear safety glasses when hitting parts with a hammer.
 - Always wear safety glasses when grinding parts with a grinder, etc.
- If welding repairs are needed, always have a trained, experienced welder carry out the work. When carrying out welding work, always wear welding gloves, apron, hand shield, cap and other clothes suited for welding work.
- 4. When carrying out any operation with two or more workers, always agree on the operating procedure before starting. Always inform your fellow workers before starting any step of the operation. Before starting work, hang UNDER REPAIR signs on the controls in the operator's compartment.
- 5. Keep all tools in good condition and learn the correct way to use them.

6. Decide a place in the repair workshop to keep tools and removed parts. Always keep the tools and parts in their correct places. Always keep the work area clean and make sure that there is no dirt or oil on the floor. Smoke only in the areas provided for smoking. Never smoke while working.

PREPARATIONS FOR WORK

- Before adding oil or making any repairs, park the machine on hard, level ground, and block the wheels or tracks to prevent the machine from moving.
- 8. Before starting work, lower blade, ripper, bucket or any other work equipment to the ground. If this is not possible, insert the safety pin or use blocks to prevent the work equipment from falling. In addition, be sure to lock all the control levers and hang warning signs on them.
- When disassembling or assembling, support the machine with blocks, jacks or stands before starting work.
- 10.Remove all mud and oil from the steps or other places used to get on and off the machine. Always use the handrails, ladders or steps when getting on or off the machine. Never jump on or off the machine. If it is impossible to use the handrails, ladders or steps, use a stand to provide safe footing.

PRECAUTIONS DURING WORK

- 11. When removing the oil filler cap, drain plug or hydraulic pressure measuring plugs, loosen them slowly to prevent the oil from spurting out. Before disconnecting or removing components of the oil, water or air circuits, first remove the pressure completely from the circuit.
- 12. The water and oil in the circuits are hot when the engine is stopped, so be careful not to get burned.

Wait for the oil and water to cool before carrying out any work on the oil or water circuits.

- 13.Before starting work, remove the leads from the battery. Always remove the lead from the negative (–) terminal first.
- 14.When raising heavy components, use a hoist or crane.

Check that the wire rope, chains and hooks are free from damage.

Always use lifting equipment which has ample capacity.

Install the lifting equipment at the correct places. Use a hoist or crane and operate slowly to prevent the component from hitting any other part. Do not work with any part still raised by the hoist or crane.

- 15. When removing covers which are under internal pressure or under pressure from a spring, always leave two bolts in position on opposite sides. Slowly release the pressure, then slowly loosen the bolts to remove.
- 16.When removing components, be careful not to break or damage the wiring. Damaged wiring may cause electrical fires.
- 17. When removing piping, stop the fuel or oil from spilling out. If any fuel or oil drips onto the floor, wipe it up immediately. Fuel or oil on the floor can cause you to slip, or can even start fires.
- 18.As a general rule, do not use gasoline to wash parts. In particular, use only the minimum of gasoline when washing electrical parts.

19.Be sure to assemble all parts again in their original places.

Replace any damaged parts with new parts.

- When installing hoses and wires, be sure that they will not be damaged by contact with other parts when the machine is being operated.
- 20. When installing high pressure hoses, make sure that they are not twisted. Damaged tubes are dangerous, so be extremely careful when installing tubes for high pressure circuits. Also, check that connecting parts are correctly installed.
- 21. When assembling or installing parts, always use the specified tightening torques. When installing protective parts such as guards, or parts which vibrate violently or rotate at high speed, be particularly careful to check that they are installed correctly.
- 22. When aligning two holes, never insert your fingers or hand. Be careful not to get your fingers caught in a hole.
- 23. When measuring hydraulic pressure, check that the measuring tool is correctly assembled before taking any measurements.
- 24. Take care when removing or installing the tracks of track-type machines.

When removing the track, the track separates suddenly, so never let anyone stand at either end of the track.

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FOREWORD GENERAL

This shop manual has been prepared as an aid to improve the quality of repairs by giving the serviceman an accurate understanding of the product and by showing him the correct way to perform repairs and make judgements. Make sure you understand the contents of this manual and use it to full effect at every opportunity.

This shop manual mainly contains the necessary technical information for operations performed in a service workshop. For ease of understanding, the manual is divided into the following chapters; these chapters are further divided into the each main group of components.

STRUCTURE AND FUNCTION

This section explains the structure and function of each component. It serves not only to give an understanding of the structure, but also serves as reference material for troubleshooting.

In addition, this section may contain hydraulic circuit diagrams, electric circuit diagrams, and maintenance standards.

TESTING AND ADJUSTING

This section explains checks to be made before and after performing repairs, as well as adjustments to be made at completion of the checks and repairs.

Troubleshooting charts correlating "Problems" with "Causes" are also included in this section.

DISASSEMBLY AND ASSEMBLY

This section explains the procedures for removing, installing, disassembling and assembling each component, as well as precautions for them.

MAINTENANCE STANDARD

This section gives the judgment standards for inspection of disassembled parts. The contents of this section may be described in STRUCTURE AND FUNCTION.

OTHERS

This section mainly gives hydraulic circuit diagrams and electric circuit diagrams. In addition, this section may give the specifications of attachments and options together.

NOTICE

The specifications contained in this shop manual are subject to change at any time and without any advance notice. Use the specifications given in the book with the latest date.

HOW TO READ THE SHOP MANUAL

VOLUMES

Shop manuals are issued as a guide to carrying out repairs. They are divided as follows:

Chassis volume: Issued for every machine model Engine volume: Issued for each engine series

Electrical volume: Attachments volume: Each issued as one volume to cover all models

These various volumes are designed to avoid duplicating the same information. Therefore, to deal with all repairs for any model, it is necessary that chassis, engine, electrical and attachment volumes be available.

DISTRIBUTION AND UPDATING

Any additions, amendments or other changes will be sent to KOMATSU distributors. Get the most up-todate information before you start any work.

FILING METHOD

- 1. See the page number on the bottom of the page. File the pages in correct order.
- Following examples show how to read the page number.
 Example 1 (Chassis volume):



Item number (10. Structure and Function) Consecutive page number for each item.

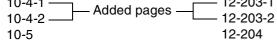
Example 2 (Engine volume):



- - ——Unit number (1. Engine) Item number (2. Testing and Adjust-
 - __ing)

Consecutive page number for each item.

Additional pages: Additional pages are indicated by a hyphen (-) and number after the page number. File as in the example.
 Example: 12-203
 10-4 1 12-203-1



REVISED EDITION MARK

When a manual is revised, an edition mark (123...) is recorded on the bottom of the pages.

REVISIONS

Revised pages are shown in the LIST OF REVISED PAGES next to the CONTENTS page.

SYMBOLS

So that the shop manual can be of ample practical use, important safety and quality portions are marked with the following symbols.

Symbol	Item	Remarks
A	Safety	Special safety precautions are necessary when per- forming the work.
*	Caution	Special technical precau- tions or other precautions for preserving standards are necessary when per- forming the work.
kg	Weight	Weight of parts of sys- tems. Caution necessary when selecting hoisting wire, or when working pos- ture is important, etc.
8	Tightening torque	Places that require special attention for the tightening torque during assembly.
~	Coat	Places to be coated with adhesives and lubricants, etc.
67	Oil, water	Places where oil, water or fuel must be added, and the capacity.
:	Drain	Places where oil or water must be drained, and quantity to be drained.

HOISTING INSTRUCTIONS

HOISTING

Heavy parts (25 kg or more) must be lifted with a hoist, etc. In the **DISASSEMBLY AND ASSEMBLY** section, every part weighing 25 kg or more is indicated clearly with the symbol

If a part cannot be smoothly removed from the machine by hoisting, the following checks should be made:

- 1) Check for removal of all bolts fastening the part to the relative parts.
- 2) Check for existence of another part causing interference with the part to be removed.

WIRE ROPES

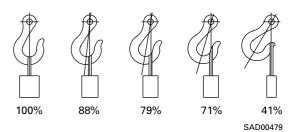
 Use adequate ropes depending on the weight of parts to be hoisted, referring to the table below:

> Wire ropes (Standard "Z" or "S" twist ropes without galvanizing)

Rope diameter	Allowa	Allowable load	
mm	kN	tons	
10	9.8	1.0	
11.5	13.7	1.4	
12.5	15.7	1.6	
14	21.6	2.2	
16	27.5	2.8	
18	35.3	3.6	
20	43.1	4.4	
22.4	54.9	5.6	
30	98.1	10.0	
40	176.5	18.0	
50	274.6	28.0	
60	392.2	40.0	

- ★ The allowable load value is estimated to be onesixth or one-seventh of the breaking strength of the rope used.
- 2) Sling wire ropes from the middle portion of the hook.

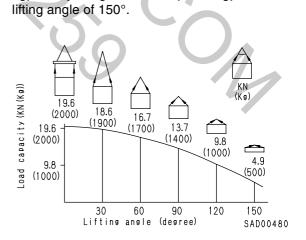
Slinging near the edge of the hook may cause the rope to slip off the hook during hoisting, and a serious accident can result. Hooks have maximum strength at the middle portion.



- Do not sling a heavy load with one rope alone, but sling with two or more ropes symmetrically wound onto the load.
 - Slinging with one rope may cause turning of the load during hoisting, untwisting of the rope, or slipping of the rope from its original winding position on the load, which can result in a dangerous accident.
- 4) Do not sling a heavy load with ropes forming a wide hanging angle from the hook.

When hoisting a load with two or more ropes, the force subjected to each rope will increase with the hanging angles. The table below shows the variation of allowable load kN {kg} when hoisting is made with two ropes, each of which is allowed to sling up to 9.8 kN {1000 kg} vertically, at various hanging angles.

When two ropes sling a load vertically, up to 19.6 kN {2000 kg} of total weight can be suspended. This weight becomes 9.8 kN {1000 kg} when two ropes make a 120° hanging angle. On the other hand, two ropes are subjected to an excessive force as large as 39.2 kN {4000 kg} if they sling a 19.6 kN {2000 kg} load at a



METHOD OF DISASSEMBLING, CONNECTING PUSH-PULL TYPE COUPLER

- Before carrying out the following work, release the residual pressure from the hydraulic tank. For details, see TESTING AND ADJUSTING, Releasing residual pressure from hydraulic tank.
- Even if the residual pressure is released from the hydraulic tank, some hydraulic oil flows out when the hose is disconnected. Accordingly, prepare an oil receiving container.

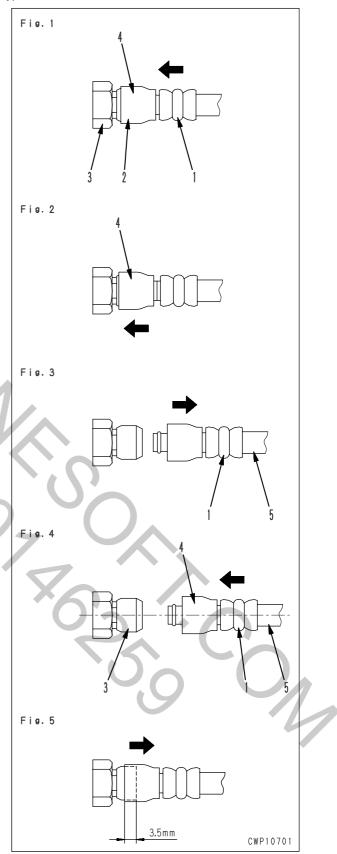
Disconnection

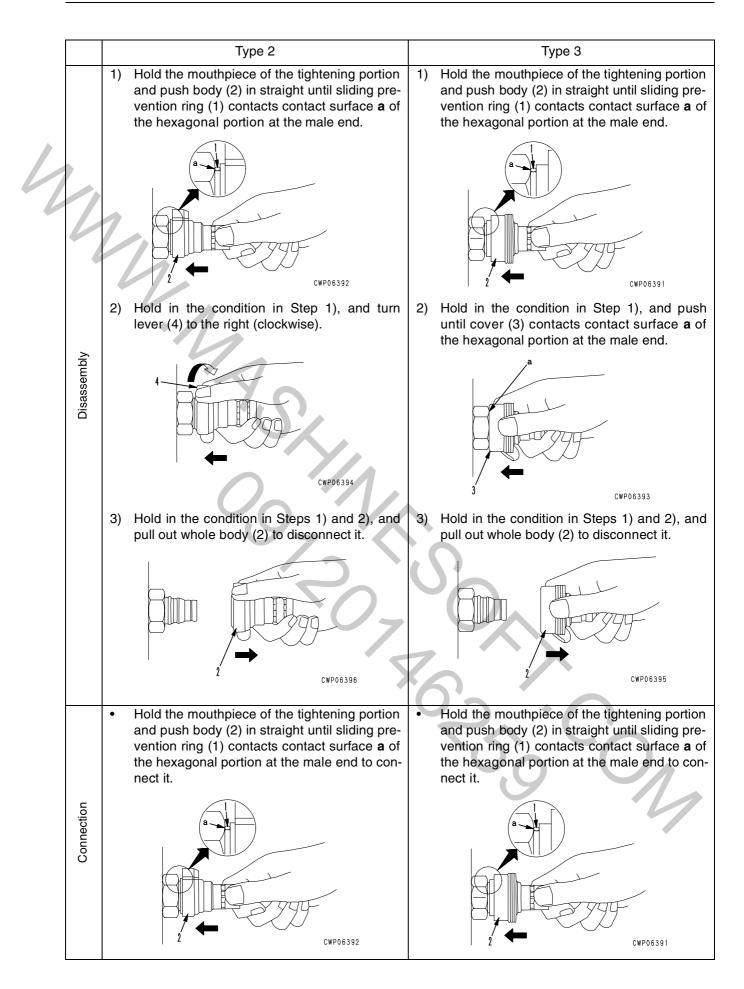
- Release the residual pressure from the hydraulic tank. For details, see TESTING AND ADJUSTING, Releasing residual pressure from hydraulic tank.
- Hold adapter (1) and push hose joint (2) into mating adapter (3). (See Fig. 1)
 - ★ The adapter can be pushed in about 3.5 mm.
 - ★ Do not hold rubber cap portion (4).
- After hose joint (2) is pushed into adapter (3), press rubber cap portion (4) against (3) until it clicks. (See Fig. 2)
- 4) Hold hose adapter (1) or hose (5) and pull it out. (See Fig. 3)
 - ★ Since some hydraulic oil flows out, prepare an oil receiving container.

Connection

- Hold hose adapter (1) or hose (5) and insert it in mating adapter (3), aligning them with each other. (See Fig. 4)
 - ★ Do not hold rubber cap portion (4).
- After inserting the hose in the mating adapter perfectly, pull it back to check its connecting condition. (See Fig. 5)
 - ★ When the hose is pulled back, the rubber cap portion moves toward the hose about 3.5 mm. This does not indicate abnormality, however.







COATING MATERIALS

- ★ The recommended coating materials such as adhesives, gasket sealants and greases used for disassembly and assembly are listed below.
- ★ For coating materials not listed below, use the equivalent of products shown in this list.

	Γ	Γ			
Category	Komatsu code	Part No.	Q'ty	Container	Main applications, featuresr
Y	LT-1A	790-129-9030	150 g	Tube	 Used to prevent rubber gaskets, rubber cushions, and cock plug from coming out.
	LT-1B	790-129-9050	20 g (2 pcs.)	Polyethylene container	 Used in places requiring an imme- diately effective, strong adhesive. Used for plastics (except polyeth- ylene, polyprophylene, tetrafluor- oethlene and vinyl chloride), rubber, metal and non-metal.
	LT-2	09940-00030	50 g	Polyethylene container	 Features: Resistance to heat and chemicals Used for anti-loosening and seal-ant purpose for bolts and plugs.
Adhesives	LT-3	790-129-9060 (Set of adhesive and hardening agent)	Adhesive: 1 kg Hardenin g agent: 500 g	Can	 Used as adhesive or sealant for metal, glass and plastic.
	LT-4	790-129-9040	250 g	Polyethylene container	 Used as sealant for machined holes.
	Holtz MH 705	790-126-9120	75 g	Tube	 Used as heat-resisting sealant for repairing engine.
	Three bond 1735	790-129-9140	50 g	Polyethylene container	 Quick hardening type adhesive Cure time: within 5 sec. to 3 min. Used mainly for adhesion of metals, rubbers, plastics and woods.
	Aron-alpha 201	790-129-9130	2 g	Polyethylene container	 Quick hardening type adhesive Quick cure type (max. strength after 30 minutes) Used mainly for adhesion of rubbers, plastics and metals.
	Loctite 648-50	79A-129-9110	50 cc	Polyethylene container	 Resistance to heat, chemicals Used at joint portions subject to high temperatures.
	LG-1	790-129-9010	200 g	Tube	 Used as adhesive or sealant for gaskets and packing of power train case, etc.
Gasket sealant	LG-5	790-129-9070	1 kg	Can	 Used as sealant for various threads, pipe joints, flanges. Used as sealant for tapered plugs, elbows, nipples of hydraulic piping.
	LG-6	790-129-9020	200 g	Tube	 Features: Silicon based, resistance to heat, cold Used as sealant for flange surface, tread. mab Used as sealant for oil pan, final drive case, etc.

-	Category	Komatsu code	Part No.	Q'ty	Container	Main applications, featuresr
	Adhesives	LG-7	790-129-9070	1 g	Tube	 Ftures: Silicon based, quick hard- ening type Used as sealant for flywheel housing, intake manifold, oil an, thermostat housing, etc.
1		Three bond 1211	790-129-9090	100 g	Tube	Used as heat-resisting sealant for repairing engine.
	Ч,	LM-G	09940-00051	60 g	Can	Used as lubricant for sliding por- tion (to prevent from squeaking).
	Molybdenum disulphide lubricant	LM-P	09940-00040	200 g	Tube	 Used to prevent seizure or scuf- fling of the thread when press fit- ting or shrink fitting. Used as lubricant for linkage, bearings, etc.
_		G2-LI	SYG2-400LI SYG2-350LI SYG2-400LI-A SYG2-160LI SYGA-160CNLI	Various	Various	General purpose type
	Grease	G2-CA	SYG2-400CA SYG2-350CA SYG2-400CA-A SYG2-160CA SYGA-160CNCA	Various	Various	 Used for normal temperature, light load bearing at places in con- tact with water or steam.
_		Molybdenum disulphide lubricant	SYG2-400M	400 g (10 per case)	Belows type	Used for places with heavy load

STANDARD TIGHTENING TORQUE

STANDARD TIGHTENING TORQUE TABLE (WHEN USING TORQUE WRENCH)

★ In the case of metric nuts and bolts for which there is no special instruction, tighten to the torque given in the table below.

Thread diameter of bolt	Width across flats		CDL00372
mm	mm	Nm	kgm
6	10	13.2 ± 1.4	1.35 ± 0.15
8	13	31 ± 3	3.2 ± 0.3
10	17	66 ± 7	6.7 ± 0.7
12	19	113 ± 10	11.5 ± 1
14	22	177 ± 19	18 ± 2
16	24	279 ± 30	28.5 ± 3
18	27	382 ± 39	39 ± 4
20	30	549 ± 59	56 ± 6
22	32	745 ± 83	76 ± 8.5
24	36	927 ± 103	94.5 ± 10.5
27	41	$1320 \pm 140 \\ 1720 \pm 190 \\ 2210 \pm 240 \\ 2750 \pm 290 \\ 3290 \pm 340$	135 ± 15
30	46		175 ± 20
33	50		225 ± 25
36	55		280 ± 30
39	60		335 ± 35
Thread diameter of bolt	Width across		

of bolt	flats		CDL00373
mm	mm	Nm	kgm
6	10	7.85 ± 1.95	0.8 ± 0.2
8	13	18.6 ± 4.9	1.9 ± 0.5
10	14	40.2 ± 5.9	4.1 ± 0.6
12	27	82.35 ± 7.85	8.4 ± 0.8

TABLE OF TIGHTENING TORQUES FOR FLARED NUTS

★ In the case of flared nuts for which there is no special instruction, tighten to the torque given in the table below.

 ∞ SAD00483

Sealing surface

Thread diameter	Width across flat	Tightenir	ng torque
mm	mm	Nm	kgm
14	19	24.5 ± 4.9	2.5 ± 0.5
18	24	49 ± 19.6	5 ± 2
22	27	78.5 ± 19.6	8 ± 2
24	32	137.3 ± 29.4	14 ± 3
30	36	176.5 ± 29.4	18 ± 3
33	41	196.1 ± 49	20 ± 5
36	46	245.2 ± 49	25 ± 5
42	55	294.2 ± 49	30 ± 5

1,

TABLE OF TIGHTENING TORQUES FOR SPLIT FLANGE BOLTS

★ In the case of split flange bolts for which there is no special instruction, tighten to the torque given in the table below.

 Thread diameter	Width across flat	Tighteni	ng torque
mm	mm	Nm	kgm
10 12	14 17	65.7 ± 6.8 112 ± 9.8	6.7 ± 0.7 11.5 ± 1
16	22	279 ± 29	28.5 ± 3

TABLE OF TIGHTENING TORQUES FOR O-RING BOSS PIPING JOINTS

★ Unless there are special instructions, tighten the O-ring boss piping joints to the torque below.

Norminal No.	Thread diameter	Width across flat	Tightenir	ng torque
Norminal No.	mm	mm	Nm	kgm
02	14		34.3 ± 4.9	3.5 ± 0.5
03, 04	20	Varies depending	93.1 ± 9.8	9.5 ± 1
05, 06	24	on type of	142.1 ± 19.6	14.5 ± 2
10, 12	33	connector.	421.4 ± 58.8	43 ± 6
14	42		877.1 ± 132.3	89.5 ± 13.5

TABLE OF TIGHTENING TORQUES FOR O-RING BOSS PLUGS

★ Unless there are special instructions, tighten the O-ring boss plugs to the torque below.

No	Thread diameter	nread diameter Width across flat		Tightening torque	
Norminal No.	mm	mm	Nm	kgm	
08	08	14	7.35 ± 1.47	0.75 ± 0.15	
10	10	17	11.27 ± 1.47	1.15 ± 0.15	
12	12	19	17.64 ± 1.96	1.8 ± 0.2	
14	14	22	22.54 ± 1.96	2.3 ± 0.2	
16	16	24	29.4 ± 4.9	3 ± 0.5	
18	18	27	39.2 ± 4.9	4 ± 0.5	
20	20	30	49 ± 4.9	5 ± 0.5	
24	24	32	68.6 ± 9.8	7 ± 1	
30	30	32	107.8 ± 14.7	11 ± 1.5	
33	33	n	127.4 ± 19.6	13 ± 2	
36	36	36	151.9 ± 24.5	15.5 ± 2.5	
42	42	n	210.7 ± 29.4	21.5 ± 3	
52	52	n	323.4 ± 44.1	33 ± 4.5	

TIGHTENING TORQUE FOR 102 ENGINE SERIES

1) BOLT AND NUTS

Use these torques for bolts and nuts (unit: mm) of Cummins Engine.

Thread diameter	Tightening	g torque
mm	Nm	kgm
6 8 10 12	10 ± 2 24 ± 4 43 ± 6 77 ± 12	$1.02 \pm 0.20 \\ 2.45 \pm 0.41 \\ 4.38 \pm 0.61 \\ 7.85 \pm 1.22$

2) EYE JOINTS

Use these torques for eye joints (unit: mm) of Cummins Engine.

Thread diameter	Tightenin	g torque
mm	Nm	kgm
6	8 ± 2	0.81 ± 0.20
8	10 ± 2	1.02 ± 0.20
10	12 ± 2	1.22 ± 0.20
12	24 ± 4	2.45 ± 0.41
14	36 ± 5	3.67 ± 0.51

3) TAPERED SCREWS

Use these torques for tapered screws (unit: inch) of Cummins Engine.

Thread diameter	Tightenin	g torque
inch	Nm	kgm
1/16	3 ± 1	0.31 ± 0.10 0.81 ± 0.20
1 / 8 1 / 4	8 ± 2 12 ± 2	0.81 ± 0.20 1.22 ± 0.20
3/8 1/2	15 ± 2 24 ± 4	1.53 ± 0.41 2.45 ± 0.41
3/4	36 ± 5	3.67 ± 0.51
1	60 ± 9	6.12 ± 0.92

TIGHTENING TORQUE TABLE FOR HOSES (TAPER SEAL TYPE AND FACE SEAL TYPE)

- Tighten the hoses (taper seal type and face seal type) to the following torque, unless otherwise specified. \star Apply the following torque when the threads are coated (wet) with engine oil.
- ★

Newsinglains		Tightening torque (Nm	{kgm})	Taper seal type	Face seal type			
of hose	Width across flats	Range	Target	Thread size (mm)	Nominal thread size - Threads per inch, Thread series	Root diameter (mm) (Reference)		
02	19	35 - 63 {3.5 - 6.5}	44 {4.5}	14	9 16 - 18UNF	14.3		
03	22	54 - 93 {5.5 - 9.5}	74 {4.5}	-	11 16 - 16UN	17.5		
	24	59 - 98 {6.0 - 10.0}	78 {8.0}	18		-		
04	27	84 - 132 {8.5 - 13.5}	103 {10.5}	22	13 16 - 16UN	20.7		
05	32	128 - 186 {13.0 - 19.0}	157 {16.0}	24	1 - 14UNS	25.4		
06	36	177 - 245 {18.0 - 25.0}	216 {22.0}	30	1	30.3		
(10)	41	177 - 245 {18.0 - 25.0}	216 {22.0}	33	-	_		
(12)	46	197 - 294 {20.0 - 30.0}	245 {25.0}	36	-	_		
(14)	55	246 - 343 {25.0 - 35.0}	294 {30.0}	42	_	_		

ELECTRIC WIRE CODE

In the wiring diagrams, various colors and symbols are employed to indicate the thickness of wires. This wire code table will help you understand WIRING DIAGRAMS.

Example: 5WB indicates a cable having a nominal number 5 and white coating with black stripe.

CLASSIFICATION BY THICKNESS

Norminal		Copper wire		Cable O.D.	Current	
number	Number of strands	Dia. of strands (mm²)	Cross section (mm²)	(mm)	rating (A)	Applicable circuit
0.85	11	0.32	0.88	2.4	12	Starting, lighting, signal etc.
2	26	0.32	2.09	3.1	20	Lighting, signal etc.
5	65	0.32	5.23	4.6	37	Charging and signal
15	84	0.45	13.36	7.0	59	Starting (Glow plug)
40	85	0.80	42.73	11.4	135	Starting
60	127	0.80	63.84	13.6	178	Starting
100	217	0.80	109.1	17.6	230	Starting
CLASSIFIC	ATION BY CO	DLOR AND CO	DDE			

CLASSIFICATION BY COLOR AND CODE

Priori- ty	Classi- fication		Charging	Ground	Starting	Lighting	Instrument	Signal	Other
	Pri-	Code	W	В	в	R	Y	G	L
1	mary	Color	White	Black	Black	Red	Yellow	Green	Blue
2		Code	WR		BW	RW	YR	GW	LW
2		Color	White & Red	_	White & Black	Red & White	Rellow & Red	Green & White	Blue & White
3		Code	WB		BY	RB	YB	GR	LR
3		Color	White & Black		Black & Yellow	Red & Black	Yellow & Black	Green & Red	Blue & Yellow
	Auxi-	Code	WL		BR	RY	YG	GY	LY
4	liary	Color	White & Blue		Black & Red	Red & Yellow	Yellow & Green	Green & Yellow	Blue & Yellow
5		Code	WG		_	RG	YL	GB	LB
Э		Color	White & Green		_	Red & Green	Yellow & Blue	Green & Black	Blue & Black
6		Code	—		_	RL	YW	GL	_
6		Color	—			Red & Blue	Yellow & White	Green & Blue	

CONVERSION TABLE

METHOD OF USING THE CONVERSION TABLE

The Conversion Table in this section is provided to enable simple conversion of figures. For details of the method of using the Conversion Table, see the example given below.

EXAMPLE

- Method of using the Conversion Table to convert from millimeters to inches
- 1. Convert 55 mm into inches.
 - (1) Locate the number 50 in the vertical column at the left side, take this as (A), then draw a horizontal line from (A).
 - (2) Locate the number 5 in the row across the top, take this as (B), then draw a perpendicular line down from (B).
 - (3) Take the point where the two lines cross as \bigcirc . This point \bigcirc gives the value when converting from millimeters to inches. Therefore, 55 mm = 2.165 inches.
- 2. Convert 550 mm into inches.
 - (1) The number 550 does not appear in the table, so divide by 10 (move the decimal point one place to the left) to convert it to 55 mm.
 - (2) Carry out the same procedure as above to convert 55 mm to 2.165 inches.
 - (3) The original value (550 mm) was divided by 10, so multiply 2.165 inches by 10 (move the decimal point one place to the right) to return to the original value. This gives 550 mm = 21.65 inches.

_										1 mm =	0.03937 in
		0	1	2	3	4	5	6	7	8	9
	0	0	0.039	0.079	0.118	0.157	0.197	0.236	0.276	0.315	0.354
	10	0.394	0.433	0.472	0.512	0.551	0.591	0.630	0.669	0.709	0.748
	20	0.787	0.827	0.866	0.906	0.945	0.984	1.024	1.063	1.102	1.142
	30	1.181	1.220	1.260	1.299	1.339	1.378	1.417	1.457	1.496	1.536
	40	1.575	1.614	1.654	1.693	1.732	1.772	1.811	1.850	1.890	1.929
							©				
A	50	1.969	2.008	2.047	2.087	2.126	2.165	2.205	2.244	2.283	2.323
0	60	2.362	2.402	2.441	2.480	2.520	2.559	2.598	2.638	2.677	2.717
	70	2.756	2.795	2.835	2.874	2.913	2.953	2.992	3.032	3.071	3.110
	80	3.150	3.189	3.228	3.268	3.307	3.346	3.386	3.425	3.465	3.504
	90	3.543	3.583	3.622	3.661	3.701	3.740	3.780	3.819	3.858	3.898
l											

Millimeters to inches

Millimeters to Inches

1 mm = 0.03937 in

	0	1	2	3	4	5	6	7	8	9
0	0	0.039	0.079	0.118	0.157	0.197	0.236	0.276	0.315	0.354
10	0.394	0.433	0.472	0.512	0.551	0.591	0.630	0.669	0.709	0.748
20	0.787	0.827	0.866	0.906	0.945	0.984	1.024	1.063	1.102	1.142
30	1.181	1.220	1.260	1.299	1.339	1.378	1.417	1.457	1.496	1.536
40	1.575	1.614	1.654	1.693	1.732	1.772	1.811	1.850	1.890	1.929
50	1.969	2.008	2.047	2.087	2.126	2.165	2.205	2.244	2.283	2.323
60	2.362	2.402	2.441	2.480	2.520	2.559	2.598	2.638	2.677	2.717
70	2.756	2.795	2.835	2.874	2.913	2.953	2.992	3.032	3.071	3.110
80	3.150	3.189	3.228	3.268	3.307	3.346	3.386	3.425	3.465	3.504
90	3.543	3.583	3.622	3.661	3.701	3.740	3.780	3.819	3.858	3.898
	10 20 30 40 50 60 70 80	0 0 10 0.394 20 0.787 30 1.181 40 1.575 50 1.969 60 2.362 70 2.756 80 3.150	0 0 0.039 10 0.394 0.433 20 0.787 0.827 30 1.181 1.220 40 1.575 1.614 50 1.969 2.008 60 2.362 2.402 70 2.756 2.795 80 3.150 3.189	0 0 0.039 0.079 10 0.394 0.433 0.472 20 0.787 0.827 0.866 30 1.181 1.220 1.260 40 1.575 1.614 1.654 50 1.969 2.008 2.047 60 2.362 2.402 2.441 70 2.756 2.795 2.835 80 3.150 3.189 3.228	0 0 0.039 0.079 0.118 10 0.394 0.433 0.472 0.512 20 0.787 0.827 0.866 0.906 30 1.181 1.220 1.260 1.299 40 1.575 1.614 1.654 1.693 50 1.969 2.008 2.047 2.087 60 2.362 2.402 2.441 2.480 70 2.756 2.795 2.835 2.874 80 3.150 3.189 3.228 3.268	0 0 0.039 0.079 0.118 0.157 10 0.394 0.433 0.472 0.512 0.551 20 0.787 0.827 0.866 0.906 0.945 30 1.181 1.220 1.260 1.299 1.339 40 1.575 1.614 1.654 1.693 1.732 50 1.969 2.008 2.047 2.087 2.126 60 2.362 2.402 2.441 2.480 2.520 70 2.756 2.795 2.835 2.874 2.913 80 3.150 3.189 3.228 3.268 3.307	0 0 0.039 0.079 0.118 0.157 0.197 10 0.394 0.433 0.472 0.512 0.551 0.591 20 0.787 0.827 0.866 0.906 0.945 0.984 30 1.181 1.220 1.260 1.299 1.339 1.378 40 1.575 1.614 1.654 1.693 1.732 1.772 50 1.969 2.008 2.047 2.087 2.126 2.165 60 2.362 2.402 2.441 2.480 2.520 2.559 70 2.756 2.795 2.835 2.874 2.913 2.953 80 3.150 3.189 3.228 3.268 3.307 3.346	0 0 0.039 0.079 0.118 0.157 0.197 0.236 10 0.394 0.433 0.472 0.512 0.551 0.591 0.630 20 0.787 0.827 0.866 0.906 0.945 0.984 1.024 30 1.181 1.220 1.260 1.299 1.339 1.378 1.417 40 1.575 1.614 1.654 1.693 1.732 1.772 1.811 50 1.969 2.008 2.047 2.087 2.126 2.165 2.205 60 2.362 2.402 2.441 2.480 2.520 2.559 2.598 70 2.756 2.795 2.835 2.874 2.913 2.953 2.992 80 3.150 3.189 3.228 3.268 3.307 3.346 3.386	0 0 0.039 0.079 0.118 0.157 0.197 0.236 0.276 10 0.394 0.433 0.472 0.512 0.551 0.591 0.630 0.669 20 0.787 0.827 0.866 0.906 0.945 0.984 1.024 1.063 30 1.181 1.220 1.260 1.299 1.339 1.378 1.417 1.457 40 1.575 1.614 1.654 1.693 1.732 1.772 1.811 1.850 50 1.969 2.008 2.047 2.087 2.126 2.165 2.205 2.244 60 2.362 2.402 2.441 2.480 2.520 2.559 2.598 2.638 70 2.756 2.795 2.835 2.874 2.913 2.953 2.992 3.032 80 3.150 3.189 3.228 3.268 3.307 3.346 3.386 3.425	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$

Kilogram to Pound

90	3.543	3.583	3.622	3.661	3.701	3.740	3.780	3.819	3.858	3.898
Kilogram to F	Pound	7	S		1				1 kg =	= 2.2046 lb
	0	1	2	3	4	5	6	7	8	9
0	0	2.20	4.41	6.61	8.82	11.02	13.23	15.43	17.64	19.84
10	22.05	24.25	26.46	28.66	30.86	33.07	35.27	37.48	39.68	41.89
20	44.09	46.30	48.50	50.71	51.91	55.12	57.32	59.53	61.73	63.93
30	66.14	68.34	70.55	72.75	74.96	77.16	79.37	81.57	83.78	85.98
40	88.18	90.39	92.59	94.80	97.00	99.21	101.41	103.62	105.82	108.03
50	110.23	112.44	114.64	116.85	119.05	121.25	123.46	125.66	127.87	130.07
60	132.28	134.48	136.69	138.89	141.10	143.30	145.51	147.71	149.91	152.12
70	154.32	156.53	158.73	160.94	163.14	165.35	167.55	169.76	171.96	174.17
80	176.37	178.57	180.78	182.98	185.19	187.39	189.60	191.80	194.01	196.21
90	198.42	200.62	202.83	205.03	207.24	209.44	211.64	213.85	216.05	218.26
	1	1	1	1	1		9	,		1

Liter to U.S. Gallon

1*l* = 0.2642 U.S. Gal

	0	1	2	3	4	5	6	7	8	9
0	0	0.264	0.528	0.793	1.057	1.321	1.585	1.849	2.113	2.378
10	2.642	2.906	3.170	3.434	3.698	3.963	4.227	4.491	4.755	5.019
20	5.283	5.548	5.812	6.076	6.340	6.604	6.869	7.133	7.397	7.661
30	7.925	8.189	8.454	8.718	8.982	9.246	9.510	9.774	10.039	10.303
40	10.567	10.831	11.095	11.359	11.624	11.888	12.152	12.416	12.680	12.944
50	13.209	13.473	13.737	14.001	14.265	14.529	14.795	15.058	15.322	15.586
60	15.850	16.115	16.379	16.643	16.907	17.171	17.435	17.700	17.964	18.228
70	18.492	18.756	19.020	19.285	19.549	19.813	20.077	20.341	20.605	20.870
80	21.134	21.398	21.662	21.926	22.190	22.455	22.719	22.983	23.247	23.511
90	23.775	24.040	24.304	24.568	24.832	25.096	25.361	25.625	25.889	26.153

Liter to U.K. Gallon

			7,	S						
iter to U.K. (Gallon		0		1			1	ℓ = 0.2199	17 U.K. Ga
	0	1	2	3	4	5	6	7	8	9
0	0	0.220	0.440	0.660	0.880	1.100	1.320	1.540	1.760	1.980
10	2.200	2.420	2.640	2.860	3.080	3.300	3.520	3.740	3.950	4.179
20	4.399	4.619	4.839	5.059	5.279	5.499	5.719	5.939	6.159	6.379
30	6.599	6.819	7.039	7.259	7.479	7.969	7.919	8.139	8.359	8.579
40	8.799	9.019	9.239	9.459	9.679	9.899	10.119	10.339	10.559	10.778
50	10.998	11.281	11.438	11.658	11.878	12.098	12.318	12.528	12.758	12.978
60	13.198	13.418	13.638	13.858	14.078	14.298	14.518	14.738	14.958	15.178
70	15.398	15.618	15.838	16.058	16.278	16.498	16.718	16.938	17.158	17.378
80	17.598	17.818	18.037	18.257	18.477	18.697	18.917	19.137	19.357	19.577
90	19.797	20.017	20.237	20.457	20.677	20.897	21.117	21.337	21.557	21.777

kgm to ft. Ib

1 kgm = 7.233 ft. lb

	0	1	2	3	4	5	6	7	8	9
0	0	7.2	14.5	21.7	28.9	36.2	43.4	50.6	57.9	65.1
10	72.3	79.6	86.8	94.0	101.3	108.5	115.7	123.0	130.2	137.4
20	144.7	151.9	159.1	166.4	173.6	180.8	188.1	195.3	202.5	209.8
30	217.0	224.2	231.5	238.7	245.9	253.2	260.4	267.6	274.9	282.1
40	289.3	296.6	303.8	311.0	318.3	325.5	332.7	340.0	347.2	354.4
50	361.7	368.9	376.1	383.4	390.6	397.8	405.1	412.3	419.5	426.8
60	434.0	441.2	448.5	455.7	462.9	470.2	477.4	484.6	491.8	499.1
70	506.3	513.5	520.8	528.0	535.2	542.5	549.7	556.9	564.2	571.4
80	578.6	585.9	593.1	600.3	607.6	614.8	622.0	629.3	636.5	643.7
90	651.0	658.2	665.4	672.7	679.9	687.1	694.4	701.6	708.8	716.1
100	723.3	730.5	737.8	745.0	752.2	759.5	766.7	773.9	781.2	788.4
	795.6	802.9	810.1	817.3	824.6	831.8	839.0	846.3	853.5	860.7
	868.0			889.7	896.9	904.1		918.6	925.8	933.1
										1005.4
140	1012.6	1019.9	1027.1	1034.3	1041.5	1048.8	1056.0	1063.2	1070.5	1077.7
					\wedge					
				•						1150.0
										1222.4
										1294.7
										1367.0
190	1374.3	1381.5	1388.7	1396.0	1403.2	1410.4	1417.7	1424.9	1432.1	1439.4
	10 20 30 40 50 60 70 80 90	0 0 10 72.3 20 144.7 30 217.0 40 289.3 50 361.7 60 434.0 70 506.3 80 578.6 90 651.0 100 723.3 110 795.6 120 868.0 130 940.3 140 1012.6 150 1084.9 160 1157.3 170 1129.6 180 1301.9	$\begin{array}{ c c c c c c c c c c c c c c c c c c c$	$\begin{array}{ c c c c c c c c c c c c c c c c c c c$	$\begin{array}{ c c c c c c c c c c c c c c c c c c c$	$\begin{array}{ c c c c c c c c c c c c c c c c c c c$	$\begin{array}{ c c c c c c c c c c c c c c c c c c c$	$\begin{array}{ c c c c c c c c c c c c c c c c c c c$	$\begin{array}{ c c c c c c c c c c c c c c c c c c c$	$\begin{array}{ c c c c c c c c c c c c c c c c c c c$



kg/cm² to lb/in²

1kg/cm² = 14.2233 lb/in²

					I				/CIII = 14.2	
	0	1	2	3	4	5	6	7	8	9
0	0	14.2	28.4	42.7	56.9	71.1	85.3	99.6	113.8	128.0
10	142.2	156.5	170.7	184.9	199.1	213.4	227.6	241.8	256.0	270.2
20	284.5	298.7	312.9	327.1	341.4	355.6	369.8	384.0	398.3	412.5
30	426.7	440.9	455.1	469.4	483.6	497.8	512.0	526.3	540.5	554.7
40	568.9	583.2	597.4	611.6	625.8	640.1	654.3	668.5	682.7	696.9
50	711.2	725.4	739.6	753.8	768.1	782.3	796.5	810.7	825.0	839.2
60	853.4	867.6	881.8	896.1	910.3	924.5	938.7	953.0	967.2	981.4
70	995.6	1010	1024	1038	1053	1067	1081	1095	1109	1124
80	1138	1152	1166	1181	1195	1209	1223	1237	1252	1266
90	1280	1294	1309	1323	1337	1351	1365	1380	1394	1408
100	1422	1437	1451	1465	1479	1493	1508	1522	1536	1550
110	1565	1579	1593	1607	1621	1636	1650	1664	1678	1693
120	1707	1721	1735	1749	1764	1778	1792	1806	1821	1835
130	1849	1863	1877	1892	1906	1920	1934	1949	1963	1977
140	1991	2005	2020	2034	2048	2062	2077	2091	2105	2119
150	2134	2148	2162	2176	2190	2205	2219	2233	2247	2262
160	2276	2290	2304	2318	2333	2347	2361	2375	2389	2404
170	2418	2432	2446	2460	2475	2489	2503	2518	2532	2546
180	2560	2574	2589	2603	2617	2631	2646	2660	2674	2688
190	2702	2717	2731	2745	2759	2773	2788	2802	2816	2830
								$\langle \cdot \rangle$		
200	2845	2859	2873	2887	2901	2916	2930	2944	2958	2973
210	2987	3001	3015	3030	3044	3058	3072	3086	3101	3115
220	3129	3143	3158	3172	3186	3200	3214	3229	3243	3257
230	3271	3286	3300	3314	3328	3343	3357	3371	3385	3399
240	3414	3428	3442	3456	3470	3485	3499	3513	3527	3542
								19		

1°C = 33.8°F

Temperature

Fahrenheit-Centigrade Conversion ; a simple way to convert a Fahrenheit temperature reading into a Centigrade temperature reading or vice versa is to enter the accompanying table in the center or boldface column of figures.

These figures refer to the temperature in either Fahrenheit or Centigrade degrees.

If it is desired to convert from Fahrenheit to Centigrade degrees, consider the center column as a table of Fahrenheit temperatures and read the corresponding Centigrade temperature in the column at the left.

If it is desired to convert from Centigrade to Fahrenheit degrees, consider the center column as a table of Centigrade values, and read the corresponding Fahrenheit temperature on the right.

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-25.6-146.8-6.12169.813.356132.832.891195.8-25.0-138.6-5.62271.613.957134.633.392197.6-24.4-1210.4-5.02373.414.458136.433.993199.4-23.9-1112.2-4.42475.215.059138.234.494201.2-23.3-1014.0-3.92577.015.60140.035.095203.0-22.8-915.8-3.32678.816.161141.835.696204.8-22.2-817.6-2.82780.616.762143.636.197206.6-21.7-719.4-2.22882.417.263145.436.798208.4-21.1-621.2-1.72984.217.864147.237.299210.2-20.6-523.0-1.13086.018.365149.037.8100212.0-20.0-424.8-0.63187.818.966150.840.6105221.0-19.4-326.603289.619.467152.643.3110230.0-18.9-228.40.63391.420.068154.4
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-22.8 -9 15.8 -3.3 26 78.8 16.1 61 141.8 35.6 96 204.8 -22.2 -8 17.6 -2.8 27 80.6 16.7 62 143.6 36.1 97 206.6 -21.7 -7 19.4 -2.2 28 82.4 17.2 63 145.4 36.7 98 208.4 -21.1 -6 21.2 -1.7 29 84.2 17.8 64 147.2 37.2 99 210.2 -20.6 -5 23.0 -1.1 30 86.0 18.3 65 149.0 37.8 100 212.0 -20.0 -4 24.8 -0.6 31 87.8 18.9 66 150.8 40.6 105 221.0 -19.4 -3 26.6 0 32 89.6 19.4 67 152.6 43.3 110 230.0 -18.9 -2 28.4 0.6 33 91.4 20.0 68 154.4 46.1 115 239.0 -18.3 -1 30.2 1.1 34 93.2 20.6 69 156.2 48.9 120 248.0 -17.8 0 32.0 1.7 35 95.0 21.1 70 158.0 51.7 125 257.0 -17.2 1 33.8 2.2 36 96.8 21.7 71 159.8 54.4 130 266.0 -16.7
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-18.3 -1 30.2 1.1 34 93.2 20.6 69 156.2 48.9 120 248.0 -17.8 0 32.0 1.7 35 95.0 21.1 70 158.0 51.7 125 257.0 -17.2 1 33.8 2.2 36 96.8 21.7 71 159.8 54.4 130 266.0 -16.7 2 35.6 2.8 37 98.6 22.2 72 161.6 57.2 135 275.0 -16.1 3 37.4 3.3 38 100.4 22.8 73 163.4 60.0 140 284.0 -15.6 4 39.2 3.9 39 102.2 23.3 74 165.2 62.7 145 293.0
-17.8 0 32.0 1.7 35 95.0 21.1 70 158.0 51.7 125 257.0 -17.2 1 33.8 2.2 36 96.8 21.7 71 159.8 54.4 130 266.0 -16.7 2 35.6 2.8 37 98.6 22.2 72 161.6 57.2 135 275.0 -16.1 3 37.4 3.3 38 100.4 22.8 73 163.4 60.0 140 284.0 -15.6 4 39.2 3.9 39 102.2 23.3 74 165.2 62.7 145 293.0
-17.2 1 33.8 2.2 36 96.8 21.7 71 159.8 54.4 130 266.0 -16.7 2 35.6 2.8 37 98.6 22.2 72 161.6 57.2 135 275.0 -16.1 3 37.4 3.3 38 100.4 22.8 73 163.4 60.0 140 284.0 -15.6 4 39.2 3.9 39 102.2 23.3 74 165.2 62.7 145 293.0
-16.7235.62.83798.622.272161.657.2135275.0-16.1337.43.338100.422.873163.460.0140284.0-15.6439.23.939102.223.374165.262.7145293.0
-16.7235.62.83798.622.272161.657.2135275.0-16.1337.43.338100.422.873163.460.0140284.0-15.6439.23.939102.223.374165.262.7145293.0
-16.1 3 37.4 3.3 38 100.4 22.8 73 163.4 60.0 140 284.0 -15.6 4 39.2 3.9 39 102.2 23.3 74 165.2 62.7 145 293.0
-15.6 4 39.2 3.9 39 102.2 23.3 74 165.2 62.7 145 293.0
-15.0 5 41.0 4.4 40 104.0 23.9 75 167.0 65.6 150 302.0
- 14.4 6 42.8 5.0 41 105.8 24.4 76 168.8 68.3 155 311.0
-13.9 7 44.6 5.6 42 107.6 25.0 77 170.6 71.1 160 320.0
-13.3 8 46.4 6.1 43 109.4 25.6 78 172.4 73.9 165 329.0
-12.8 9 48.2 6.7 44 111.2 26.1 79 174.2 76.7 170 338.0
-12.2 10 50.0 7.2 45 113.0 26.7 80 176.0 79.4 175 347.0

SN

UNITS

In this manual, the measuring units are indicated with Internatinal System of units (SI). As for reference, conventionally used Gravitational System of units are indicated in parentheses { }.

Example:

N {kg} Nm {kgm} MPa {kg/cm²} kPa {mmH₂O} kPa {mmHg} kW/rpm {HP/rpm} g/kWh {g/HPh}

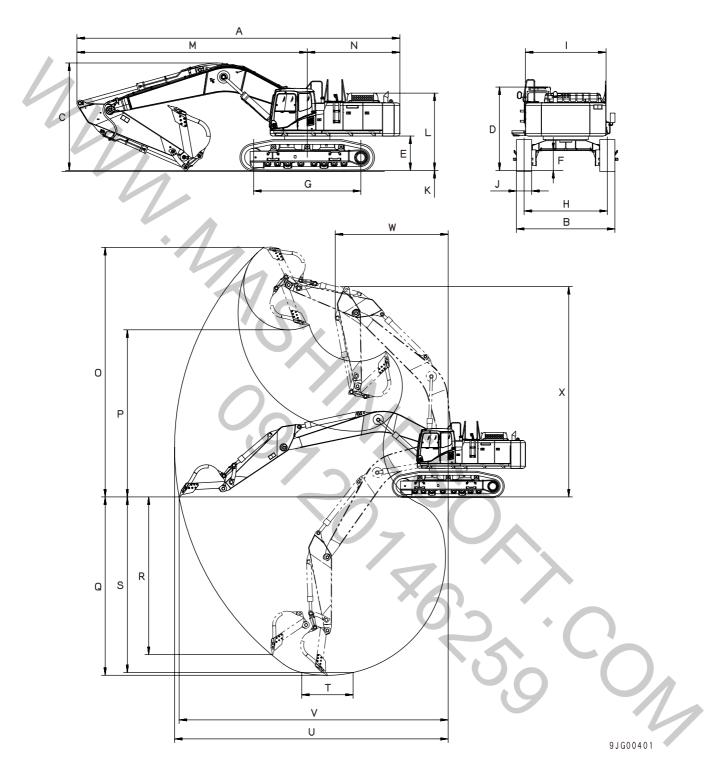
01 GENERAL

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SPECIFICATIONS	01-	4
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4

SPECIFICATION DRAWINGS

BACKHOE SPECIFICATION



Machine model	PC600-7	PC600LC-7
Serial Number	20001 and up	20001 and up
A	12,810	12,810
В	3,900	3,900
С	4,300	4,300
D	3,290	3,290
E	1,365	1,365
F	780	780
G	4,250	4,600
Ĥ	3,300	3,300
	3,195	3,195
J	600	600
К	37	37
L	3,070	3,070
М	9,135	9,135
N	3,675	3,675
0	11,880	11,880
Р	7,960	7,960
Q C	8,490	8,490
R	7,510	7,510
S	8,360	8,360
Т	2,440	2,440
U	13,020	13,020
V	12,800	12,800
W	5,370	5,370
X	10,020	10,020

Unit: mm

SPECIFICATIONS

PC600-7

		Machine model		PC600-7	
	Serial Number			20001 and up	
	1	Bucket capacity	m³	2.7	
		Weight of machine	kg	56,600	
		Max. digging depth	mm	8,490	
	ges	Max. vertical wall depth	mm	7,510	
	Working ranges	Max. digging reach	mm	13,020	
	king	Max. reach at ground level	mm	12,800	
	Norl	Max. digging height	mm	11,880	
	-	Max. dumping height	mm	7,960	
Performance	Ма	ax. digging force	kN {kg}	294.3 {30,000}	
rma	(1	using power max. function)		(316.9 {32,300})	
Perfo	Sw	ving speed	rpm	8.3	
ш.	Sw	ving max. slope angle	deg.	17	
	Tra	avel speed	km/h	Low speed: 3.0	
				High speed: 4.9	
	Gr	adeability	deg.	35	
	Gr	round pressure (standard triple	kPa {kg/cm ² }	100 {1.02}	
	g	rouser shoe width: 600 mm)	4		
	٥v	verall length (for transport)	mm	12,810	
	Ov	verall width	mm	3,195	
	Ov	verall width of track	mm	3,900	
	Ov	verall height (for transport)	mm	4,300	
	Ov	verall height to top of cab	mm	3,290	
	Gr	ound clearance of	mm	1,365	
s	с	counterweight		XO	
Dimension	Mi	n. ground clearance	mm	780	
	Та	il swing radius	mm	3,800	
	Mi	n. swing radius of work	mm	5,370	
	е	equipment			
	He	eight of work equipment	mm	10,020	
	а	t min. swing radius			
	Le	ngth of track on ground	mm	4,250	
	Tra	ack gauge	mm	3,300	
	He	eight of machine cab	mm	3,070	

		Machine model			PC600-7	
	Serial Number			20001 and up		
Engine	Ty No	odel pe o. of cylinders – bore × stroke ston displacement	mm ℓ {cc}	4-cycle, water-c	OMATSU SA6D140E ooled, in-line, vertical rger and aftercooler (6 – 140 × 165 15.24 {15,240}	, direct injection,
	Performance	Flywheel horsepower Max. torque Max. speed at no load Min. speed at no load Min. fuel consumption	kW/rpm {HP/rpm} Nm/rpm {kgm/rpm} rpm g/kW•h {g/HP•h}	} 287/1,800 {384/1,800} 1,755/1,400 {179/1,400} 1,950 825		
	Alt	arting motor ternator ttery		24V, 11 kW 24V, 50A 12V, 175 Ah × 2		
	Ra	adiator core type			CWX-5	
age	Ca	arrier roller			3 on each side	
Undercarriage	Tra	ack roller	0		8 on each side	
Unde	Tra	ack shoe		Assembly-ty	pe triple grouser, 49	on each side
	dwnd	Туре			le displacement pisto 5 × 2, gear type: SAL(
	Hydraulic pump	Delivery			type: 410 × 2, gear ty	
		Set pressure	MPa {kg/cm ² }		e: 34.3 {350}, gear typ spool + 5-spool type :	
	Control valve	Control method	2		Hydraulic	
	tor	Travel motor		KMV335ADT, Piston type		
Hydraulic system	Hydraulic motor	Swing motor	<	KMF90ABE-3, Pis	rake valve, shaft brak ston type (with safety erse prevention valve)	valve, shaft brake,
Hydr	der	Туре		Boom Double-acting piston	Arm Double-acting piston	Bucket Double-acting piston
	cylinder	Inside diameter of cylinder	mm	185	200	185
	aulic	Diameter of piston rod	mm	120	140	120
	Hydraulic	Stroke	mm	1,725	2,045	1,425
	-	Max. distance between pins	mm	4,182	4,933	3,577
		Min. distance between pins	mm	2,457	2,888	2,152
	Hy	/draulic tank /draulic filter /draulic cooler			Box-shaped, sealed Tank return side Air cooled	

PC600LC-7

	Machine model		PC600LC-7	
	Serial Number		20001 and up	
	Bucket capacity	m³	2.7	
7	Weight of machine	kg	57,600	
	Max. digging depth	mm	8,490	
	Max. vertical wall depth	mm	7,510	
	Max. digging reach	mm	13,020	
	Max. vertical wall depth Max. digging reach Max. reach at ground level Max. digging height	mm	12,800	
	Max. digging height	mm	11,880	
	Max. dumping height	mm	7,960	
nce	Max. digging force	kN {kg}	294.3 {30,000}	
Performance	(using power max. function)		(316.9 {32,300})	
Perf	Swing speed	rpm	8.3	
	Swing max. slope angle	deg.	17	
	Travel speed	km/h	Low speed: 3.0	
			High speed: 4.9	
	Gradeability	deg.	35	
	Ground pressure (standard triple	kPa {kg/cm²}	95 {0.97}	
	grouser shoe width: 600 mm)	0		
	Overall length (for transport)	mm	12,810	
	Overall width	mm	3,195	
	Overall width of track	mm	3,900	
	Overall height (for transport)	mm	4,300	
	Overall height to top of cab	mm	3,290	
	Ground clearance of counter-	mm	1,365	
S	weight		6	
Ision	Min. ground clearance	mm	780	*
Dimensions	Tail swing radius	mm	3,800	
	Min. swing radius of work	mm	5,370	\cap $()_{\wedge}$
	equipment			9
	Height of work equipment	mm	10,020	
	at min. swing radius			
	Length of track on ground	mm	4,600	
	Track gauge	mm	3,300	
	Height of machine cab	mm	3,070	

_	Machine model Serial Number				PC600LC-7	
				20001 and up		
1	Tyj No	odel be . of cylinders – bore × stroke ston displacement	mm ℓ {cc}	4-cycle, water-c	OMATSU SA6D140E ooled, in-line, vertical irger and aftercooler (6 – 140 × 165 15.24 {15,240}	, direct injection,
Engine	Performance	Flywheel horsepower Max. torque Max. speed at no load Min. speed at no load Min. fuel consumption	kW/rpm {HP/rpm} Nm/rpm {kgm/rpm} rpm rpm g/kW•h {g/HP•h}		287/1,800 {384/1,800 ,755/1,400 {179/1,400 1,950 825 214 {160}	
	Alt	arting motor ernator ttery		24V, 11 kW 24V, 50A 12V, 175 Ah × 2		
	Ra	diator core type			CWX-5	
Undercarriage		rrier roller ack roller			3 on each side 9 on each side	
Underd		ack shoe	52	Assembly-ty	vpe triple grouser, 52 o	on each side
	bump	Туре	\sim		le displacement pisto 5 × 2, gear type: SAL(
	Hydraulic	Delivery Set pressure	ℓ /min MPa {kg/cm²}		type: 410 × 2, gear ty e: 34.3 {350}, gear typ	-
		Type × No.			spool + 5-spool type >	
	Control valve	Control method	2		Hydraulic	
	otor	Travel motor			MV335ADT, Piston ty prake valve, shaft brak	
Hydraulic system	Hydraulic motor	Swing motor	<	KMF90ABE-3, Pis	ston type (with safety erse prevention valve)	valve, shaft brake
Hydr	ir	Туре		Boom Double-acting	Arm Double-acting	Bucket Double-acting
	cylinder			piston 185	piston 200	piston 185
		Inside diameter of cylinder Diameter of piston rod	mm mm	120	140	120
	Hydraulic	Stroke	mm	1,725	2,045	1,425
	Нy	Max. distance between pins	mm	4,182	4,933	3,577
		Min. distance between pins	mm	2,457	2,888	2,152
	Нy	draulic tank draulic filter draulic cooler			Box-shaped, sealed Tank return side Air cooled	1

WEIGHT TABLE

A This weight table is a guide for use when transporting or handling components

		Unit: kg
Machine model	PC600-7	PC600LC-7
Serial Number	20001 and up	20001 and up
Engine assembly	2,305	2,305
• Engine	1,720	1,720
PTO (incl. lubricating piping)	258	258
Hydraulic pump	327	327
Radiator, oil cooler assembly	306	306
Hydraulic tank filter assembly (excl. hydraulic oil)	493	493
Fuel tank (excl. fuel)	503	503
Revolving frame	4,345	4,345
Operator's cab	293	293
Operator's seat	35	35
Counterweight	10,750	10,750
Swing machinery	724	724
Control valve	304	304
Swing motor	61 × 2	61 × 2
Travel motor	268 × 2	268 × 2
Center swivel joint	43	43
Track frame assembly	15,152	15,664
(Excluding step, roller guard, shoe assembly, and		
lower piping)	\cup_{τ}	\wedge
Center frame	3,998	3,998
Track frame	2,207 × 2	2,355 × 2
Swing circle	1136	1,136
• Idler	342 × 2	342 × 2
Idler cushion	452 × 2	452 × 2
Carrier roller	50 × 6	50 × 6
Track roller	108 × 16	108 × 18
 Final drive (incl. travel motor) 	994 × 2	994 × 2

		0
Machine model	PC600-7	PC600LC-7
Serial Number	20001 and up	20001 and up
Track shoe assembly		
Standard triple grouser shoe (600 mm)	5,930	6,290
• Wide triple grouser shoe (750 mm)	6,750	7,170
Boom assembly	4,820	4,820
Arm assembly	3,240	3,240
Bucket assembly	2,510	2,510
Boom cylinder assembly	522 × 2	522 × 2
Arm cylinder assembly	770	770
Bucket cylinder assembly	469	469
Link assembly (large)	584	584
Link assembly (small)	-	_
Boom pin	149 + 26 × 2 + 76 + 104 + 36	149 + 26 × 2 + 76 + 104 + 36
Arm pin	32 + 55	32 + 55
Bucket pin	55 + 62	55 + 62
Link pin	45 × 2	45 × 2

Unit: kg

FUEL, COOLANT AND LUBRICANTS

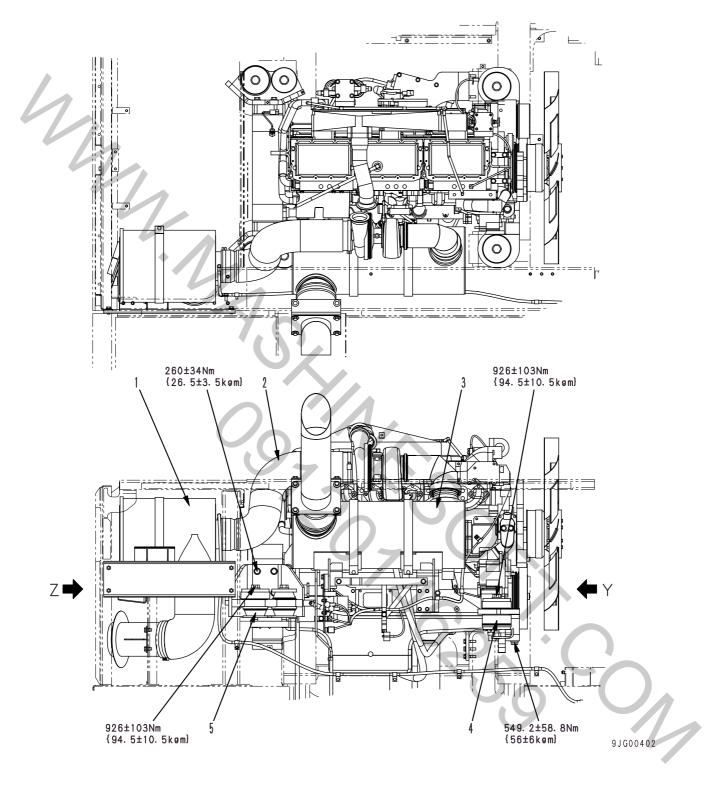
	KIND OF	AMBIENT TEMPERATURE CAPACI	ITY (l)			
RESERVOIR	FLUID	-22 -4 14 32 50 68 86 104°F -30 -20 -10 0 10 20 30 40°C Specified	Refill			
1		SAE 30				
Engine oil pan		SAE 10W 42 SAE 10W – 30 42	37			
		SAE 15W – 40				
PTO case	Engine oil	SAE 10W 6	6			
Swing machinery case (each)	1		13			
Final drive case (each)		SAE 30 10.5	10			
Hydraulic system	7,0	SAE 10W 520	360			
Fuel tank	Diesel fuel	ASTM D975 No.1 880	_			
Cooling system	Water	Add antifreeze 57	_			

July 2

10 STRUCTURE, FUNCTION AND MAINTENANCE STANDARD

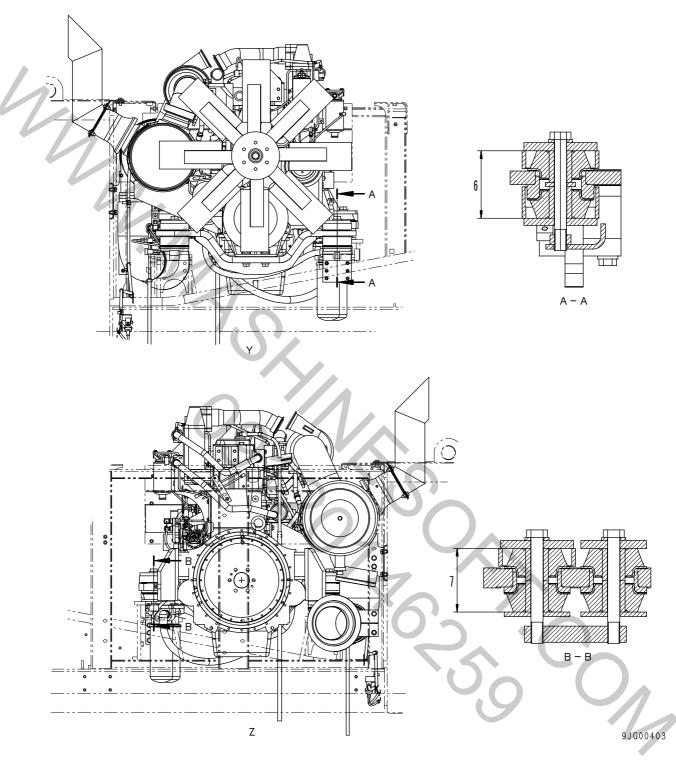
PARTS RELATED TO ENGINE	10-	2
PTO		
CONTROL AND PTO LUBRICATION PUMP	10-	6
RADIATOR, OIL COOLER		
POWER TRAIN		
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SWING CIRCLE		
SWING MACHINERY		
TRACK FRAME, RECOIL SPRING		
IDLER		
CARRIER ROLLER		
TRACK ROLLER		
TRACK SHOE		
HYDRAULIC PIPING DRAWING		
HYDRAULIC TANK, HYDRAULIC FILTER		
HYDRAULIC PUMP (PISTON PUMP)		
LINE OIL FILTER		
CONTROL VALVE	10-	64
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WORK EQUIPMENT. SWING PPC VALVE	10-1	106
TRAVEL PPC VALVE	10-	110
SERVICE PPC VALVE	10-	112
PPC ACCUMULATOR		
PPC SHUTTLE VALVE		
SOLENOID VALVE		
BOOM HOLDING VALVE		
BOOM LOWER REGENERATION VALVE		
HYDRAULIC CYLINDER	10-1	128
WORK EQUIPMENT	10-1	130
DIMENSIONS OF WORK EQUPMENT		
AIR CONDITIONER		
ENGINE CONTROL		
MACHINE CONTROL SYSTEM		
MONITOR SYSTEM		
SENSORS	10-1	184

PARTS RELATED TO ENGINE



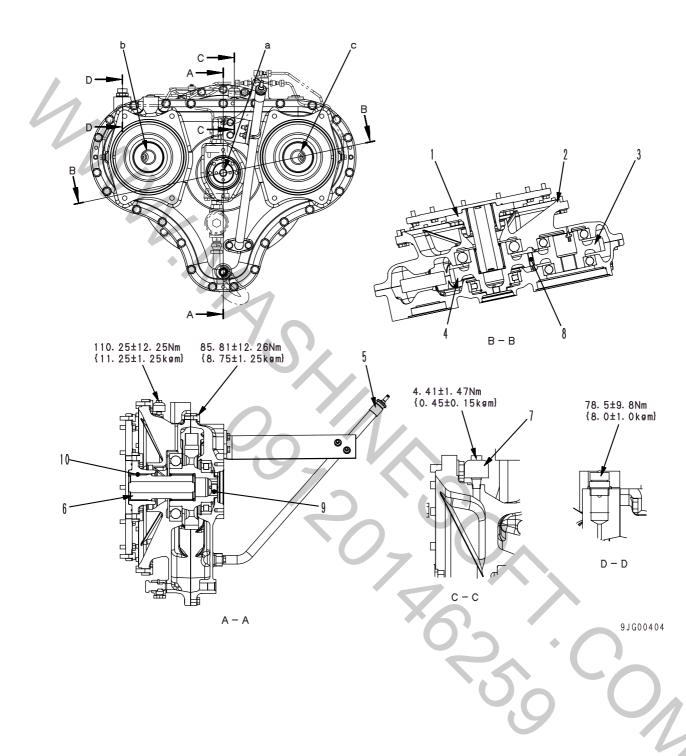
- 1. Air cleaner
- 2. Intake connector
- 3. Muffler

- 4. Front engine mount
- 5. Rear engine mount



No.	Check item	Criteria		Remedy
6	Free height of front mount	Standard size	Repair limit	
0	rubber	bber 126	—	Replace
7	Free height of rear mount rubber	134	_	

ΡΤΟ



- 1. Connection plate
- 2. PTO case
- 3. Driven gear (No. of teeth: 40)
- 4. Drive gear (No. of teeth: 36)
- 5. Oil level gauge
- 6. Main shaft
- 7. Breather

- a. Center of crankshaft (Center of SAL56 shaft)
- b. Center of HPV95+95 shaft
- c. Center of HPV95+95 shaft

Specifications

Lubricating oil: 6 ℓ Reducation ratio: Input shaft (SAL56 shaft) = 1

HPV95+95 shaft =
$$\frac{36}{40}$$
 = 0.9

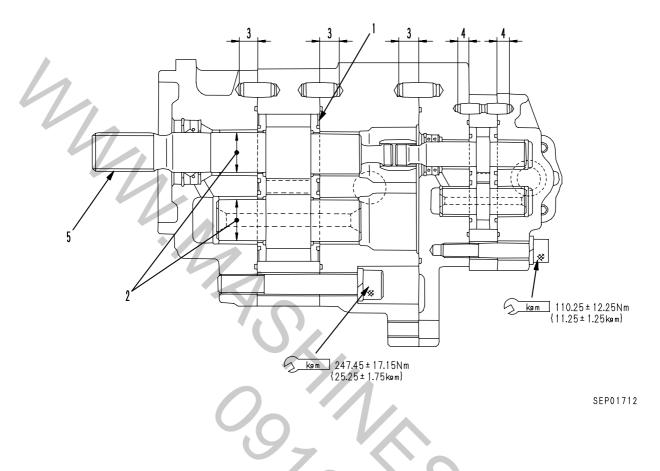
hung.

No.	Check item	Crit	Remedy	
Backlash between drive gear		Standard clearance	Clearance limit	
	and driven gear	0.23 – 0.74		
9	Backlash of SAL56 pump input shaft	0.273 – 0.374	_	Adjust
10	Backlash between main shaft and plate 0.081 – 0.226		_]

ΡΤΟ

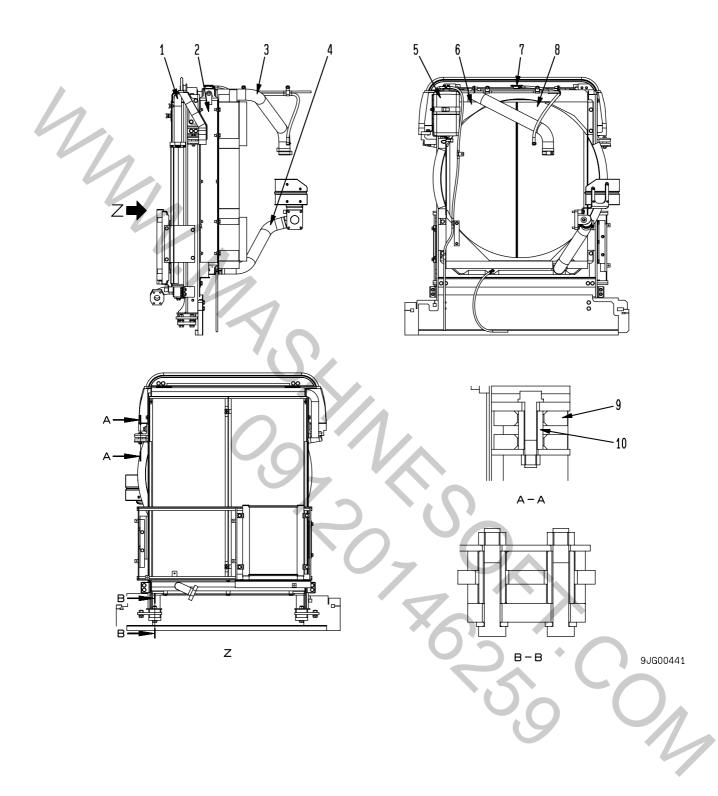
CONTROL AND PTO LUBRICATION PUMP

SAL56 + 8



No.	Check item	I	Criteria					Remedy	
	Clearance between	Standard	cleara	ance	C	earance limi	t		
1	gear case and side	SAL56	0.13 -	- 0.18		7	0.22	$\boldsymbol{\lambda}$	
	plate	SAL8	0.10 -	- 0.15		C	0.19		
2	Clearance between bearing inner dia.	SAL56	0.067 – 0.125			Si	0.20	• (
	and gear shaft outer dia.	SAL8	0.067 -	- 0.12	0.125		0.20		Replace
				ard size Toler		ance	Repair	limit	
3	Pin insertion depth		12		0 0.5				
4			12			0 — -0.5 —			
5	Spline shaft rotation to	orque			_	_			
	Delivery Oil: EO10-CD	il: EO10-CD SAL56		Delivery pressure (MPa {kg/cm²})		Standar deliver (ℓ/min.	y I	elivery limit /min.)	_
	Oil temp.: 45 – 55°C		2,500	2	2.9 {30}	134		124	Ī
		SAL8	2,500	2	2.9 {30}	19		17	I

RADIATOR, OIL COOLER

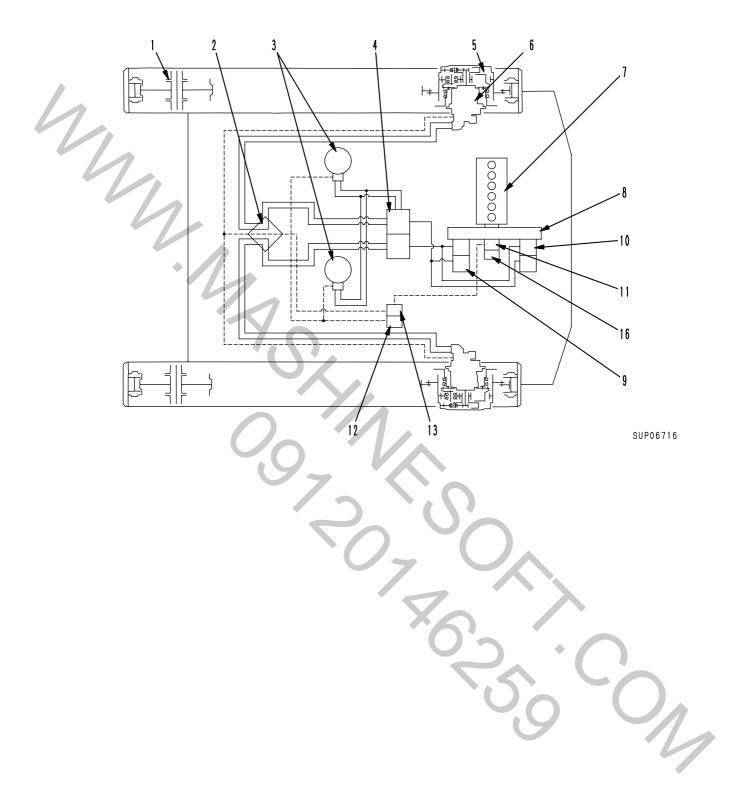


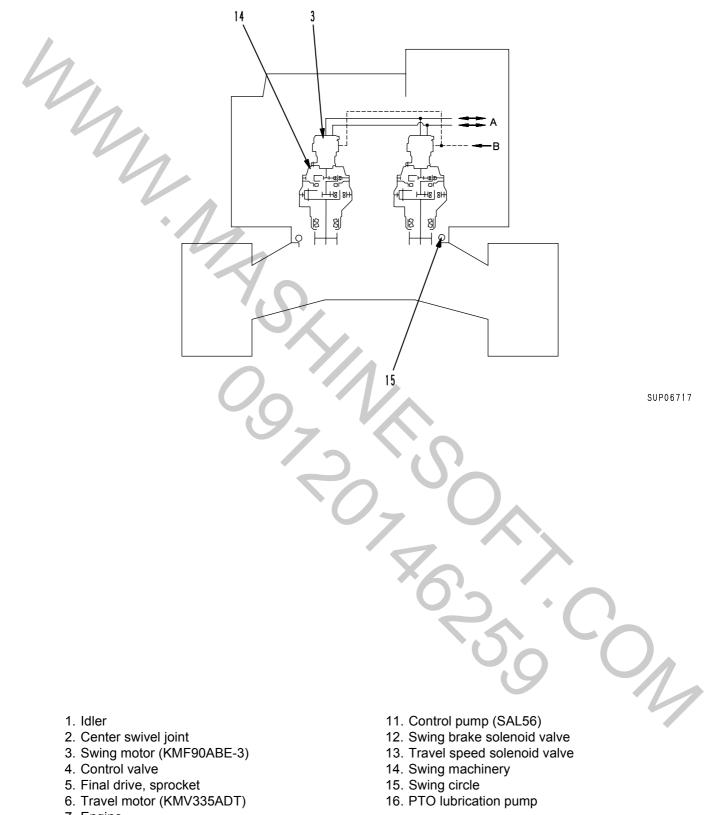
- 1. Oil cooler
- 2. Radiator
- 3. Radiator inlet hose
- 4. Radiator outlet hose
- 5. Reservoir tank
- 6. Shroud

- 7. Radiator cap
- 8. Fan
- 9. Cushion
- 10. Collar

Specifications Radiator: CWX-5 Oil cooler: J-5

POWER TRAIN

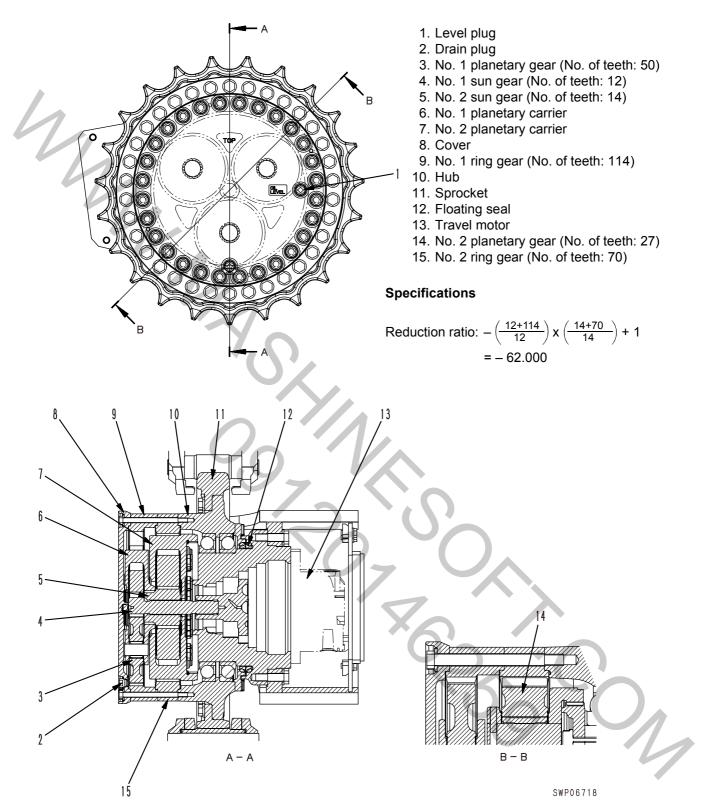




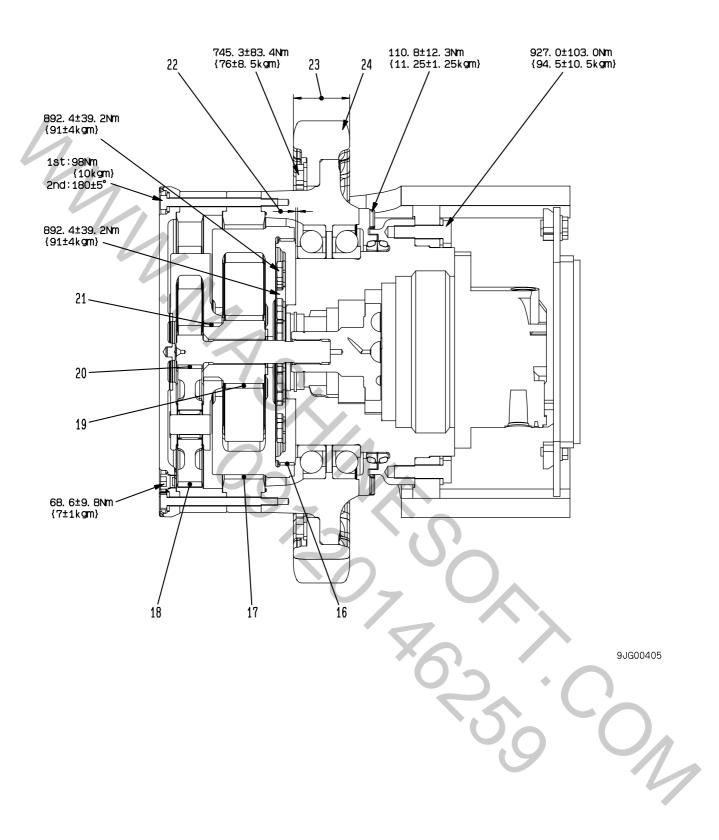
- 7. Engine
- 8. PTO
- 9. No. 1 pump (HPV95+95)
- 10. No. 2 pump (HPV95+95)

- A. Control valve
- B. Swing brake solenoid valve

FINAL DRIVE



MMM MASHINGOTATION



10-12

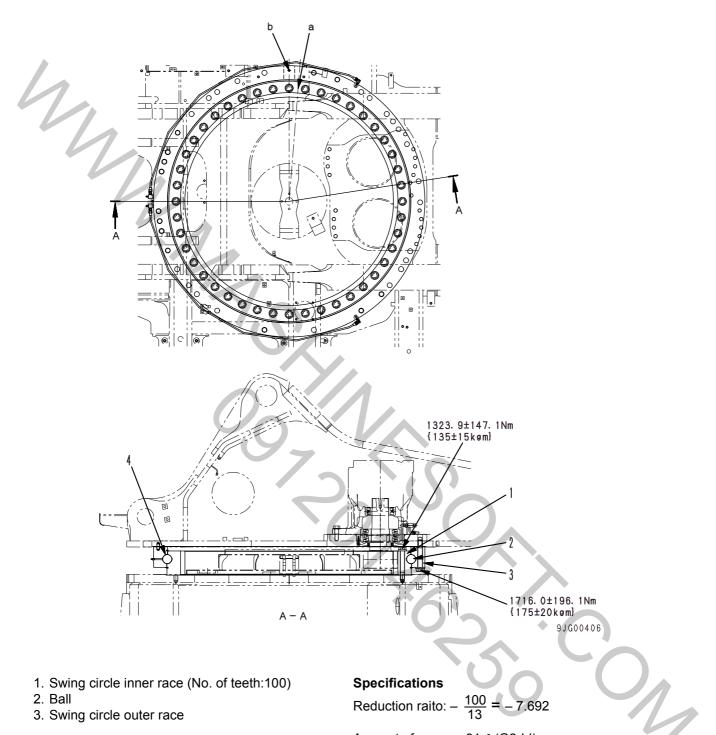
hung

Unit: mm

No.	Check item	Crit	eria	Remedy
16	Backlash between No. 2	Standard clearance	Clearance limit	
	planet carrier and motor	0.06 – 0.21	-	
17	Backlash between No. 2 planet gear and No. 2 ring gear	0.21 – 0.69	1.10	
18	Backlash between No. 1 planet gear and No. 1 ring gear	0.18 – 0.63	1.10	\mathbf{D}
19	Backlash between No. 2 sun gear and No. 2 planet gear	0.17 – 0.62	1.00	Replace
20	Backlash between No. 1 sun gear and No. 1 planet gear	0.14 – 0.45	1.00	1
21	Backlash between No. 1 planet carrier and No. 2 sun gear	0.16 – 0.56	1.00	
22	End play of sprocket shaft	0.10 – 0.15	—	
		Standard size	Repair limit	Rebuild or
23	Sprocket tooth width	104	101.5	replace
24	Wear of sprocket teeth	Repair	Replace	

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SWING CIRCLE



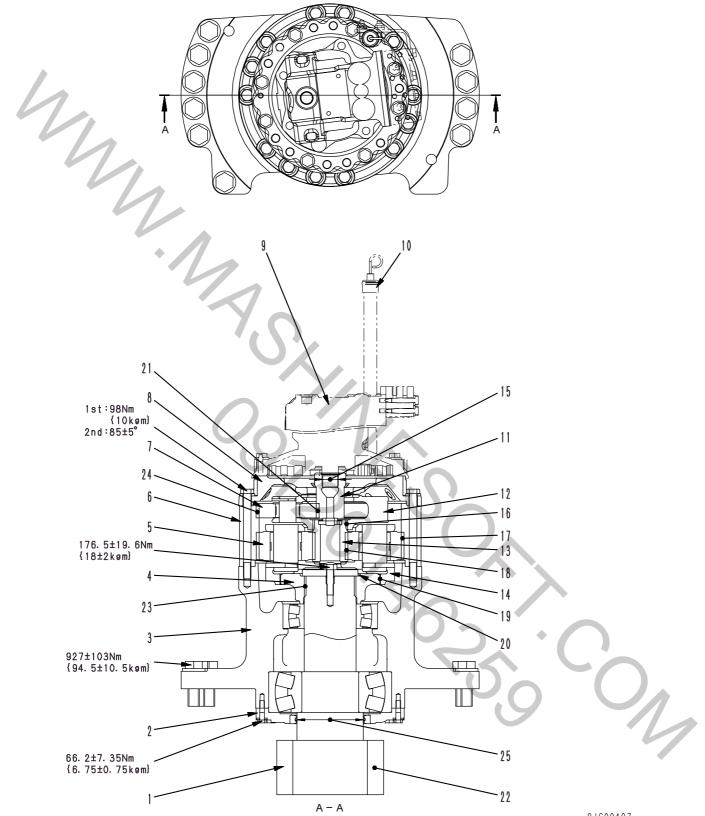
- a. Inner race soft zone "S" position
- b. Outer rae soft zone "S" position

Amount of grease: 31 ℓ (G2-LI)

No.	Check item	Crit	Remedy	
	Clearance of bearing in axial	Standard clearance	Clearance limit	
4	4 direction (when mounted on machine)	0.10 – 0.25	3.2	Replace

MMM MASHINGOTATION

SWING MACHINERY



9JG00407

1. Swing pinion (No. of teeth: 13) **Specifications** 2. Cover 3. Case 4. Coupling 5. No. 2 planetary gear (No. of teeth: 36) 6. Ring gear (No. of teeth: 95) 7. No. 1 planetary gear (No. of teeth: 39) 8. Cover 9. Swing motor

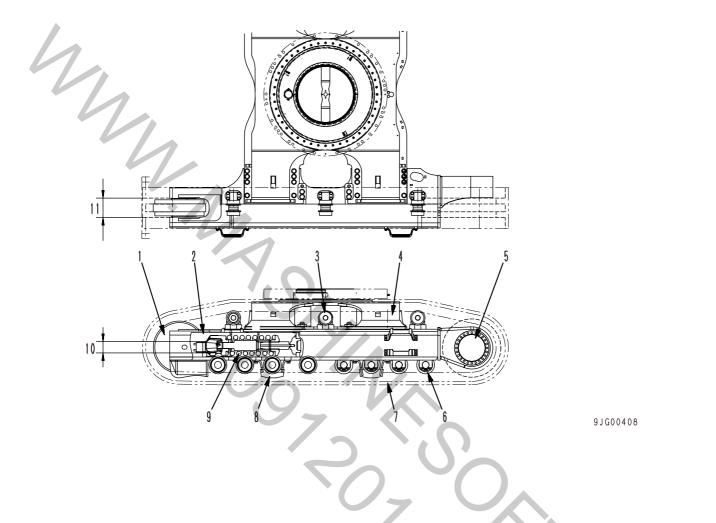
- 10. Oil level gauge
- 11. No. 1 sun gear (No. of teeth: 16)
- 12. No. 1 planetary carrier
- 13. No. 2 sun gear (No. of teeth: 21)
- 14. No. 2 planetary carrier

Reduction raito:
$$\frac{-16+95}{16} \times \frac{-21+95}{21}$$

= 38.321

	o. 2 sun gear (No. of teeth: 2 o. 2 planetary carrier	1)		
				Unit: mm
No.	Check item	Crit	eria	Remedy
15	Backlash between swing motor shaft and No. 1 sun gear	Standard clearance 0.15 – 0.49	Clearance limit	
16	Backlash between No. 1 planet carrier and No. 2 sun gear	0.38 – 0.66	1.20	
17	Backlash between No. 2 planet gear and ring gear	0.17 – 0.57	1.00	
18	Backlash between No. 2 sun gear and No. 2 planet gear	0.15 – 0.49	0.90	
19	Backlash between No. 2 planet carrier and coupling	0.06 – 0.25	P_{-}	Replace
20	Clearance between plate and coupling	0.38 – 0.82	00 (
21	Backlash between No. 1 sun gear and No. 1 planet gear	0.15 – 0.49	1.00	1
22	Backlash between swing pinion and swing circle	0 – 0.126	2.00	
23	Backlash between coupling and swing pinion	0.07 – 0.23	_	
24	Backlash between No. 1 planet gear and ring gear	0.15 – 0.57	1.10	
25	Wear of swing pinion oil seal	Standard size	Repair limit	Repair hard
25	contact surface	140.3 _{_0.100}	_	chrome plat- ing replace

TRACK FRAME, RECOIL SPRING



- 1. Idler
- 2. Track frame
- 3. Carrier roller
- 4. Center frame
- 5. Final drive
- 6. Track roller
- 7. Track shoe
- 8. Center guard

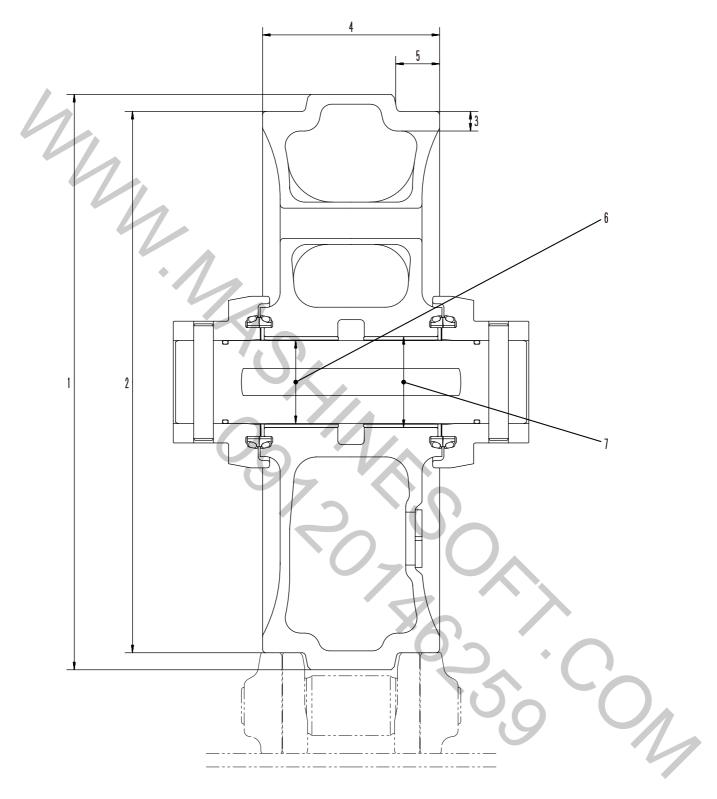
- The dimensions and number of track rollers may differ according to the model, but the basic structure is the same.
- No. of track rollers.

Model	No. of rollers (each side)
PC600-7	8
PC600LC-7	9
	4

hung

							Onit. min	
No.	Check item		Criteria					
			Standard size		Repa			
9	Recoil spring	Free length x OD	Installed length	Installed load	Free length	Installed load	Replace	
		859 x 299	715	292 kN {29,770 kg}	Ą	233.6 kN {23,816 kg}		
		Track frame		Standard size	Tolerance	Repair limit	9	
10	Top-to-bottom width of idler guide			163.5	163.5 ⁺⁴	167.5	·	
		Idler support		161	161 ⁺¹ 0	159	Rebuild or replace	
11	Left-to-right width of idler guide	Track frame		329	329 ⁺⁴ ₀	334		
		Idler support		324	_	322		

IDLER

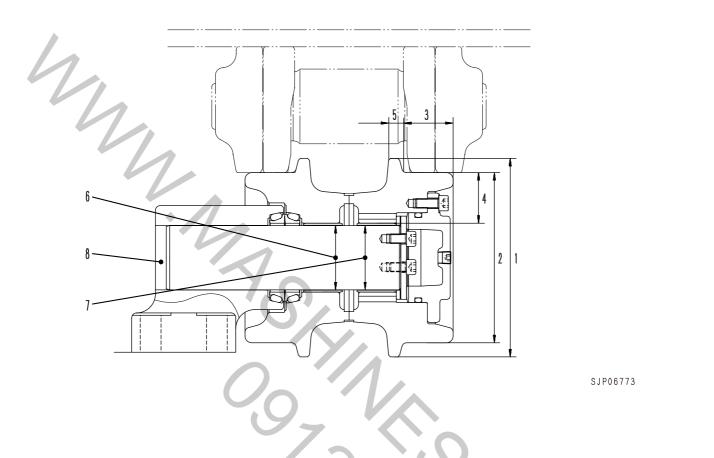


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hung

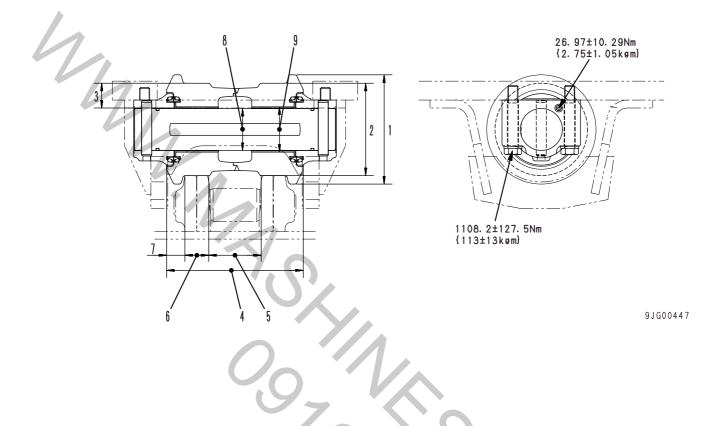
No.	Check item		Criteria					
1	Outside diameter of	Standard size				Repair lir	nit	
I	protruding part		761			_		
2	Outside diameter of tread surface	716			704			Rebuild or replace
3	Thickness of tread	22.5			Un (
4	Overall width	234						
5	Width of tread	56			_			
		Standard Tolerand		ance		Standard	Clearance	
6	Clearance between shaft and	size	Shaft	Ho	ole	clearance	limit	
	bushing	110	-0.120 -0.207	+0.480 +0.420		0.540 – 0.687	1.5	Replace bushing
		Standard	Toler	ance		Standard Interfer-		5
7	Interference between idler and bushing	size	Shaft	Ho	ole	interference	ence limit	
		120	+0.067 +0.037	-0.036 -0.136		0.073 – 0.203	_	

CARRIER ROLLER



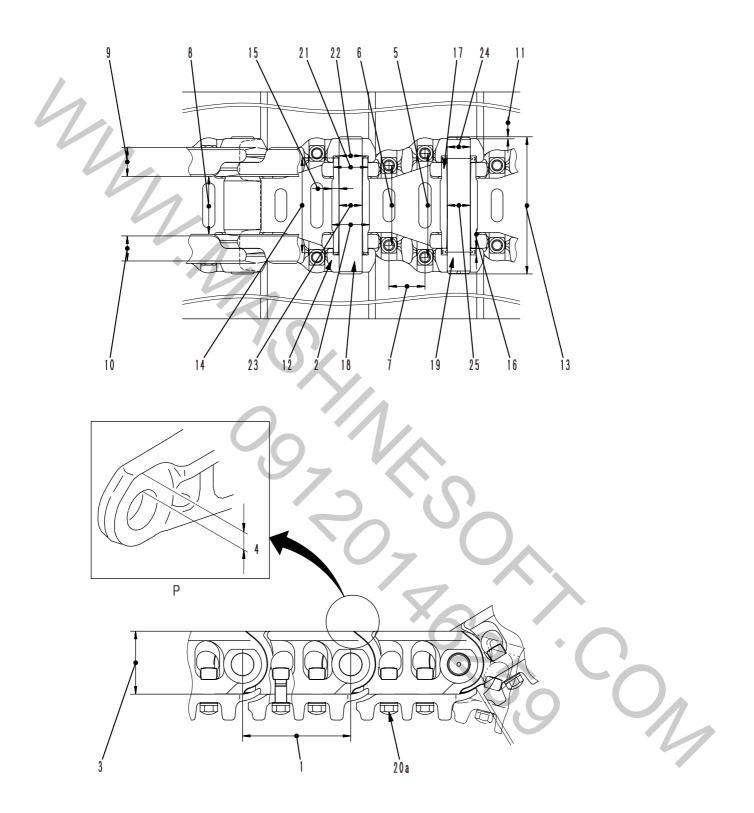
No.	Check item		Criteria					
4	Outside dismeter of flores	Sta	Standard size			Repair lir		
1	Outside diameter of flange	210				_		1
2	Outside diameter of tread		180			170		
3	Width of tread		53			—	+	
4	Thickness of tread		53.5			A		
5	Width of flange	15				Ū,		
	Clearance between shaft and bushing	Standard	ard Tolerance			Standard	Clearance	
6		size	Shaft	Ho	ble	clearance	limit	Replace
Ŭ		68	+0.09 +0.07	-	.43 .18	0.09 – 0.36	_	
		Standard Tolerance			Standard Inte			
7	Interference between roller	size	Shaft	Ho	ble	interference	ence limit	
	and bushing	73	+0.38 +0.33	-	.24 .21	0.09 – 0.17	_	
8	Play of rollor in avial direction	Standard clearance			Clearance limit			1
0	Play of roller in axial direction	0.62 – 0.93			—			1

TRACK ROLLER



No.	Check item		Criteria					
1	Outside diameter of flange	Sta	ndard size	2	Repair limit			
I	Outside diameter of flange	260				-		
2	Outside diameter of tread surface	220			208			
3	Thickness of tread		56.2					Rebuild or replace
4	Overall width	325				<u> </u>	Teplace	
5	Inside width	120						
6	Width of tread	63			19			
7	Width of flange		39.5					
		Standard	Tolerance			Standard	Clearance	
8	Clearance between shaft and	size	Shaft	Ho	ole	clearance	limit	
	bushing	100	-0.140 -0.207		390 330	0.470 – 0.597	1.5	Replace
		Standard	Toler	ance		Standard	Interfer-	bushing
9	Interference between roller and bushing	size	Shaft	Ho	ole	interference	ence limit	
_		107.6	+0.067 +0.037		020 015	0.017 – 0.082		

TRACK SHOE



SJP06775

 \star P Portion shows the link of buhing press fitting end.

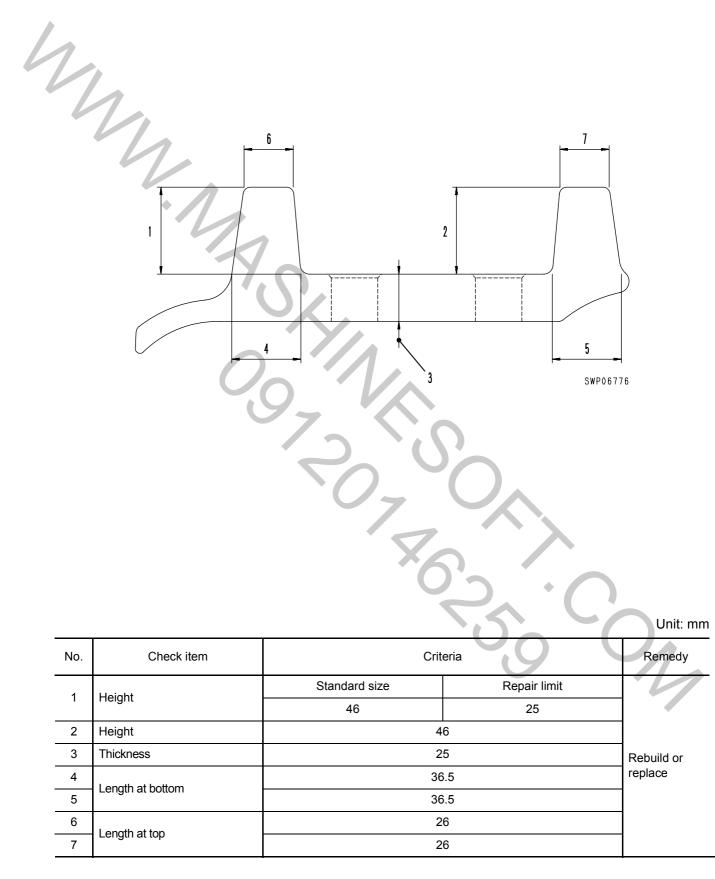
2	h	h				Unit: mm
No.	Check	item	Cr	iteria		Remedy
1	Link pitch		Standard size	R	epair limit	
			228.6	231.6		Reverse or
2	Bushing outside diameter		Standard size	When tu nal load	Impact load	replace
	<u>j</u>			7.5	_	-
3	Link height		Standard size	R	epair limit	Rebuild or
	<u> </u>		133		123	replace
4	Thickness of link (bushing press-fit		33.75	Replace		
5			2.			
6	Shoe bolt pitch					
7			7			
8		Inside width	12			
9	Link	Overall width	6	61.4		
10		Tread width	5	4.5		
11	Protrusion of pin		:	3.7	0	
12	Protrusion of reg	ular bushing	(9.6	\mathbf{O}	
13	Overall length of	pin	2	290		Adjust or
14	Overall length of	bushing	20	replace		
15	Thickness of bus	hing metal	1	Ť		
16	Thickness of spa	cer		1		
17		Bushing	127.4 – 274.4			
18	Press-fitting force	Regular pin	254.8 – 303.8	kN {26 – 31 to	on}	1 _
*19	1	Master pin	205 8 - 254 8	kN {21 – 26 to	n}	1

*: Dry type track link

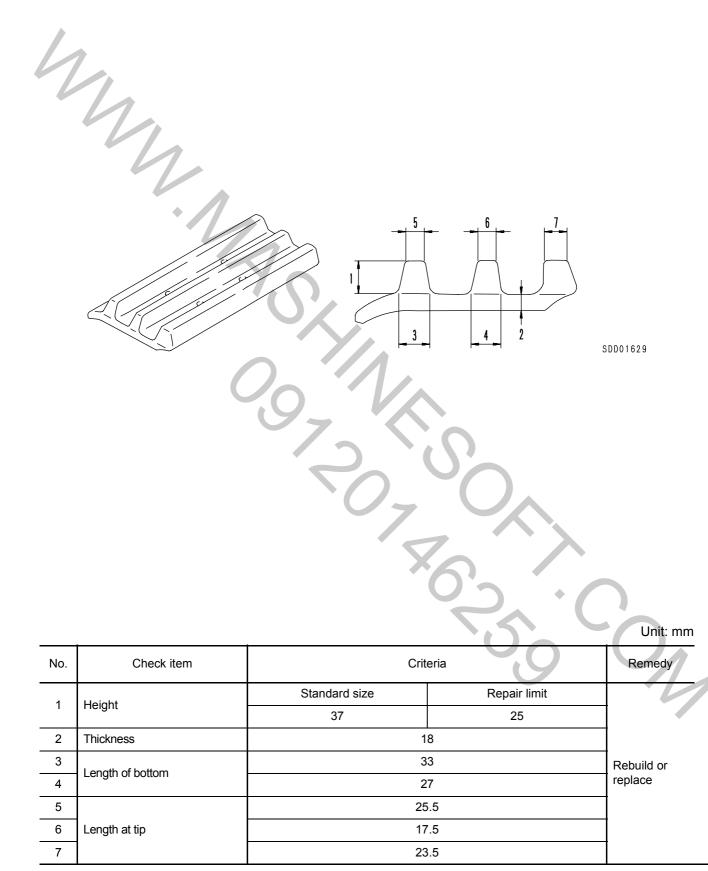
4	h	1					Unit: mm
No.	Check	item	5	Crit	eria		Remedy
20	a. Regular link b. Master link		Tightening torque (Nm {kgm}) 784.5±78.5 {80±8} Tightening torque (Nm {kgm}) Additional tig angle (to)		ar tightening	nal tightening ngle (deg.) 120±10 Lower limit torque (Nm {kgm})	Retighten
	No. of shoes (each side)		PC600-7: 49 PC600LC-7: 52			52	
21	Interference betw and link	veen bushing	Standard size	Toler Shaft +0.050 0	Hole -0.326 -0.400	Standard interference 0.326 – 0.450	
22	Interference betw pin and link	een regular	48.8	+0.180 +0.080	-0.318 -0.380	0.318 – 0.480	
23	Clearance betwe	en regular pin	Standard size	Toler Shaft	ance Hole	Standard clearance	
	and bushing		49.6	-0.62 -0.72	+0.6 0	0.72 – 1.22	Adjust or replace
		_	Standard size		ance	Standard interference	
*24	Interference between master pin and link		48.8	Shaft +0.030 0	Hole -0.318 -0.380	0.238 - 0.330	
				Tolerance		Standard	
*25	Clearance between master pin and bushing		Standard size 49.2	Shaft 0.65 0.75	Hole +0.60 0	clearance 0.65 – 1.35	-

*: Dry type track link

DOUBLE SHOE



TRIPLE GROUSER SHOE



10-28

Standard shoe

Model Item	PC600-7	PC600LC-7
Shoe width (mm) (triple shoe)	600	600
Link pitch (mm)	228.6	228.6
No. of shoes (each side)	49	52

Selection of track shoe

Select the most suitable track shoe from the following table

	PC600-7		PC600LC-7		
	Specifications	Cate- gory	Specifications	Cate- gory	
Standard	600 mm triple	Α	600 mm triple	А	
If equipped	700 mm triple	В			
If equipped	750 mm triple	В	750 mm triple	В	
If equipped	900 mm triple	В	900 mm triple	В	

Category	Use	Precautions when using	
A	Rocky ground, normal river soil	 Travel in Lo speed when traveling on rough ground with obstacles such as large boulders and fallen trees. 	
В	Normal soil, soft land	 Cannot be used on rough ground where there are large obstacles such as boulders and fallen trees. Travel in Hi speed only on flat ground; when it is impossible to avoid traveling over obstacles, lower the travel speed to approx. half of Lo speed. 	
С	Extremely soft ground (swampy ground)	 Use only for ground where "A" and "B" sink and are impossible to use. Cannot be used on rough ground where there are large obstacles such as boulders and fallen trees Travel in Hi speed only on flat ground; when it is impossible to avoid traveling over obstacles, lower the travel speed to approx. half of Lo speed. 	
D	Paved surface	The shoes are flat, so they have low gradeability	
E	Paved surface	The shoes are made of rubber, so be careful when traveling on rough ground	

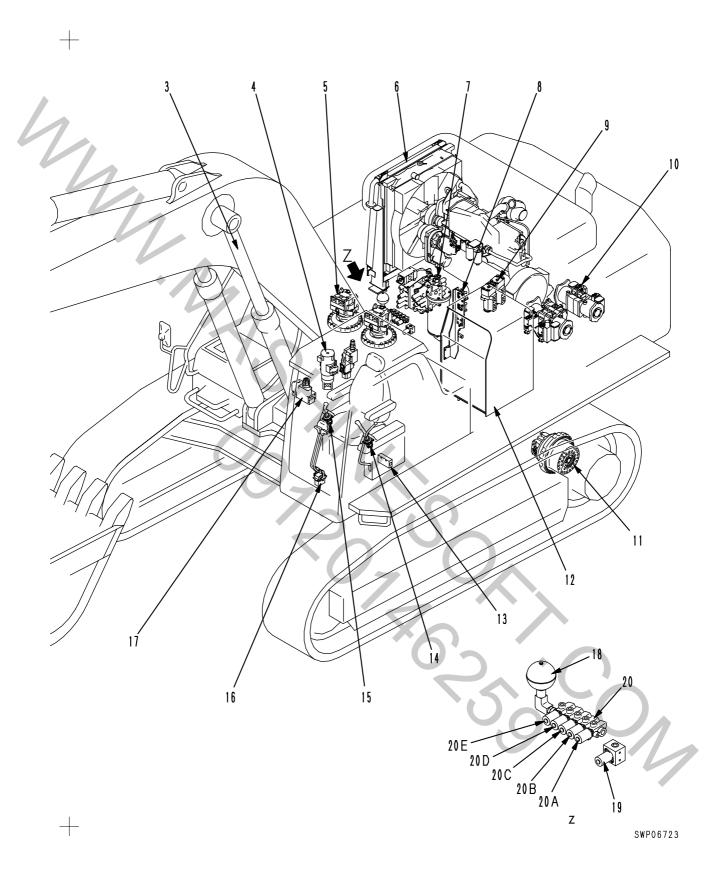
- ★ Categories "B" and "C" are wide shoes, so there are restrictions on their use. Therefore, before using, check the restrictions and consider carefully the conditions of use before recommending a suitable shoe width. If necessary, give the customer guidance in their use.
- ★ When selecting the shoe width, select the narrowest shoe possible within the range that will give no problem with flotation and ground pressure.

If a wider shoe than necessary is used, there will be a large load on the shoe, and this may lead to bending of the shoe, cracking of the links, breakage of the pins, loosening of the shoe bolts, or other problems.

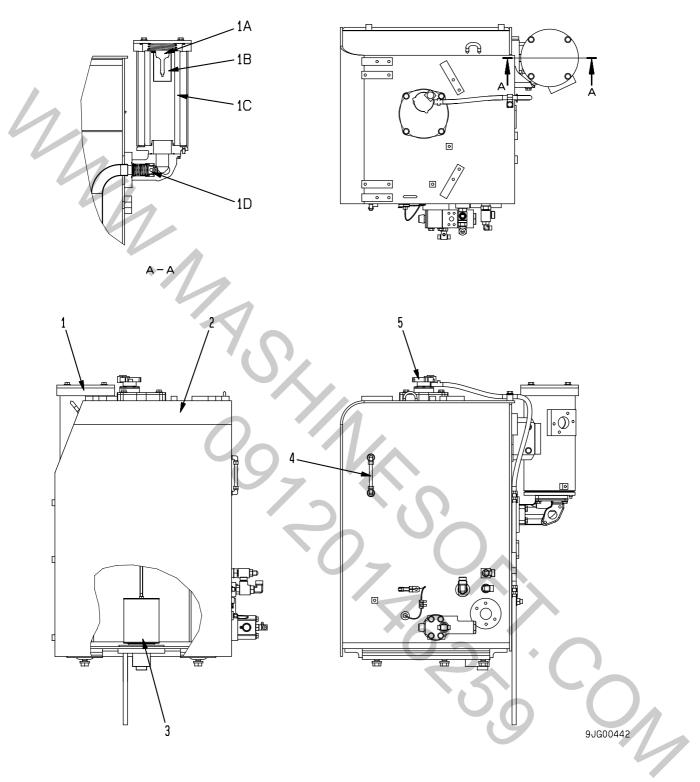
HYDRAULIC PIPING DRAWING

- 1. Bucket cylinder
- 2. Arm cylinder
- 3. Boom cylinder
- 4. Center swivel joint
- 5. Swing motor
- 6. Oil cooler
- 7. Control valve
- 8. PPC shuttle valve
- 9. Hydraulic filter
- 10. Hydraulic pump
- 11. L.H. travel motor
- 12. Hydraulic tank
- 13. PPC safety lock valve
- 14. L.H. PPC valve
- 15. R.H. PPC valve
- 16. Travel PPC valve
- 17. Boom holding valve
- 18. Accumulator
- 19. Active solenoid valve (swing)
- 20. Solenoid valve assembly
 - 20A. Swing brake solenoid valve
 - 20B. Travel speed solenoid valve
 - 20C. Pump merge/flow divider solenoid valve
 - 20D. Boom Hi 2-stage safety solenoid valve
 - 20E. Active solenoid valve (boom)

SWP06722 +



HYDRAULIC TANK, HYDRAULIC FILTER



- 1. Hydraulic filter
 - 1A. Bypass valve
 - 1B. Strainer
 - 1C. Element
 - 1D. Cooler check valve
- 2. Hydraulic tank
- 3. Suction strainer
- 4. Sight gauge
- 5. Oil filler cap

Specifications

Tank capacity: 500 *l* Amount of oil inside tank: 380 *l* (at H level)

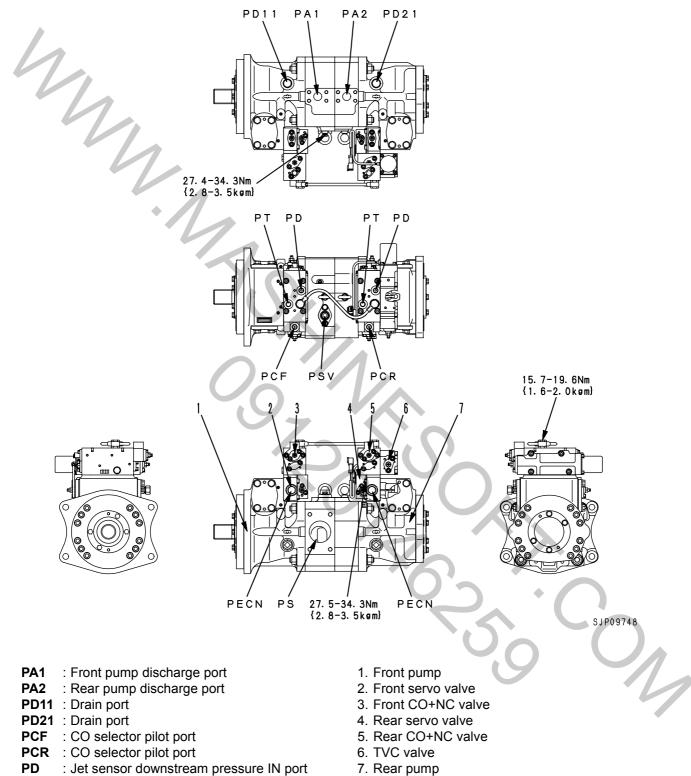
Safety valve

- Relief cracking pressure: 16.7 ± 6.9 kPa {0.17 ± 0.07 kg/cm²}
- Suction cracking pressure: 0 0.49 kPa
 - $\{0 0.005 \text{ kg/cm}^2\}$
- Bypass valve set pressure: 0.15 ± 0.03 MPa {1.5 ± 0.3 kg/cm²}

1

HYDRAULIC PUMP (PISTON PUMP)

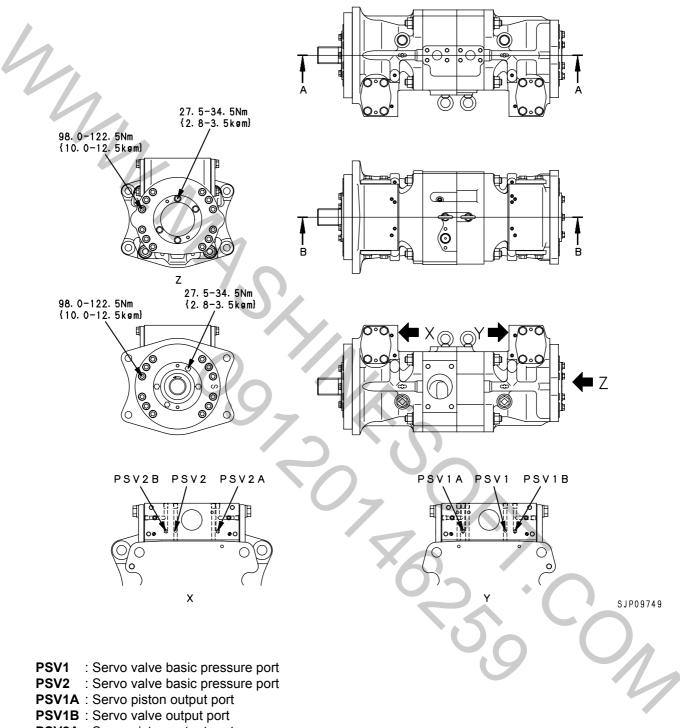
No. 1 MAIN PUMP MODEL: HPV95+95



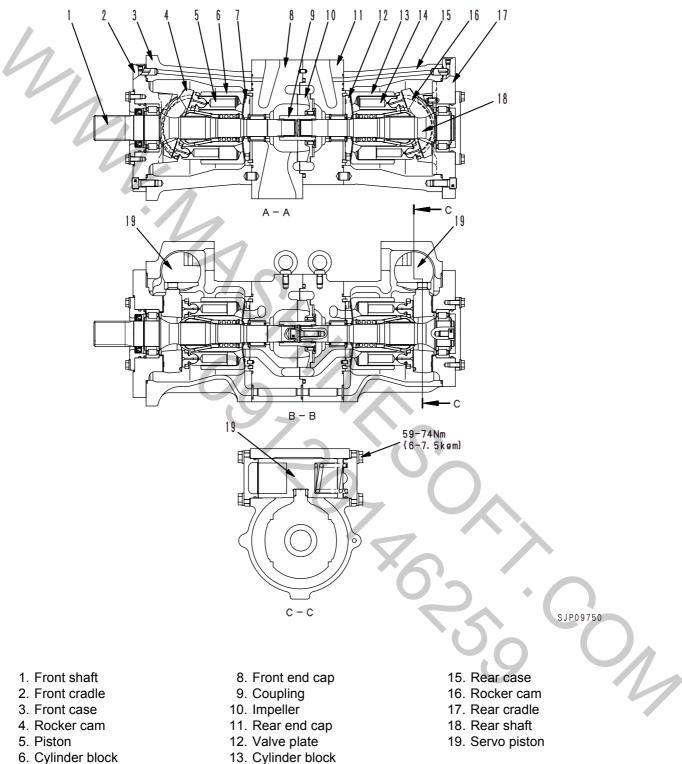
- : Pump suction port PS
- : Jet sensor upstream pressure IN port PΤ
- **PSV** : Servo basic pressure IN port
- **PECN** : CO+NC valve output pressure output port

10-34

No. 1 main pump



- **PSV2A** : Servo piston output port
- $\ensuremath{\text{PSV2B}}$: Servo valve output port

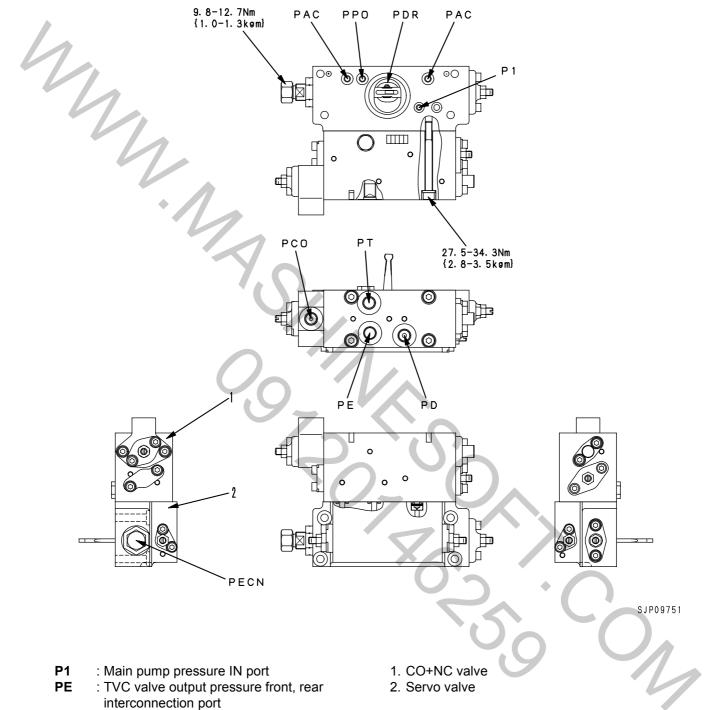


7. Valve plate

- 13. Cylinder block
- 14. Piston

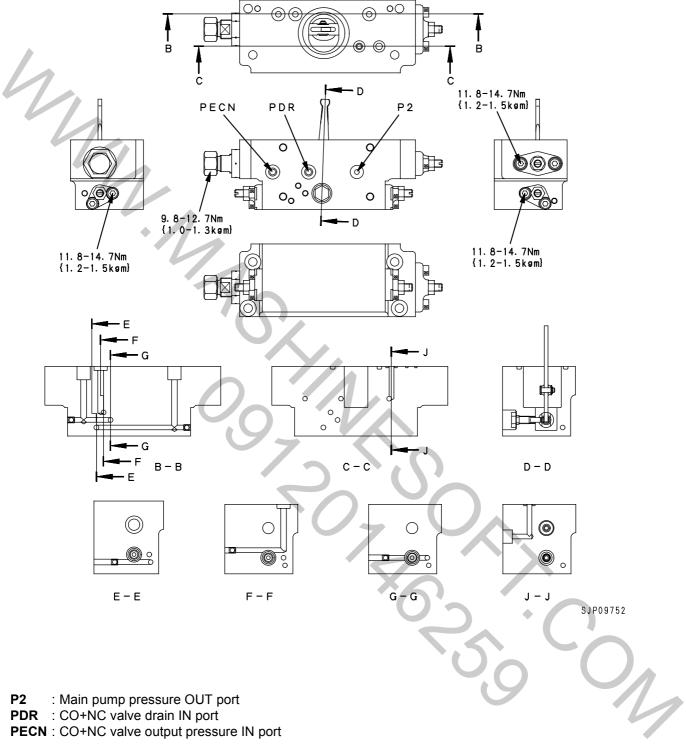
SERVO VALVE

1. Servo valve assembly (No. 1 front)



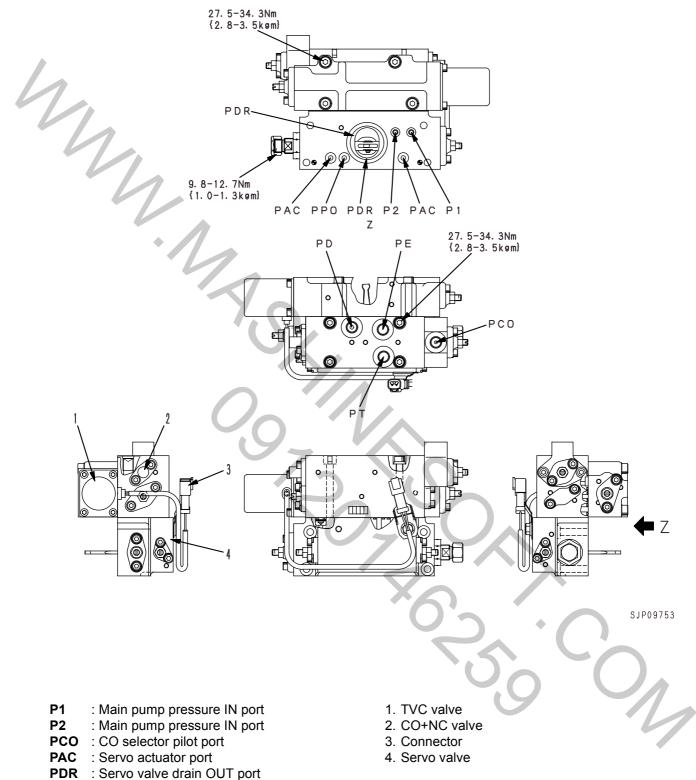
- **PCO** : CO selector pilot port
- **PD** : Jet sensor downstream pressure IN port
- **PT** : Jet sensor upstream pressure IN port
- PAC : Servo actuator port
- PDR : Servo valve drain OUT port
- **PPO** : Servo basic pressure IN port
- **PECN** : CO+NC valve output pressure output port

2. Servo valve (No. 1 front)



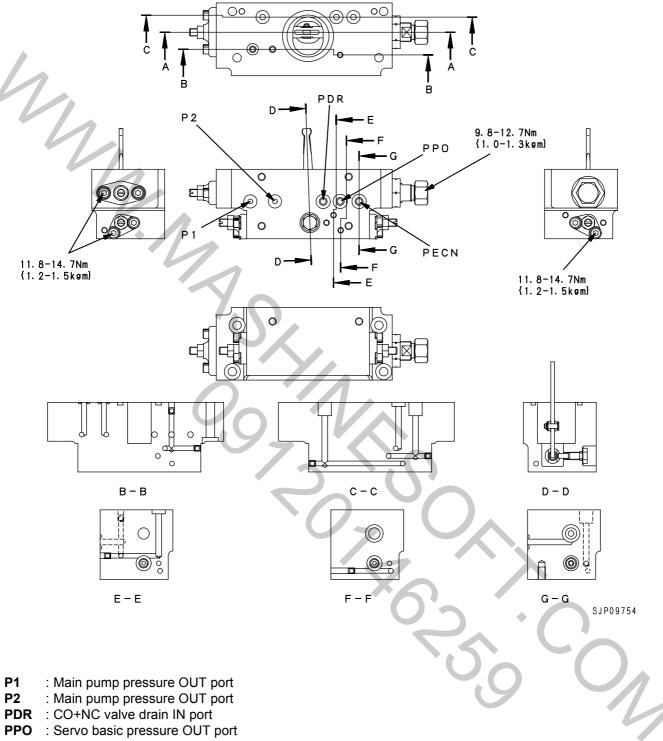
PECN : CO+NC valve output pressure IN port

3. Servo valve assembly (No. 1 rear)



- PPO : Servo basic pressure IN port
- **PD** : Jet sensor downstream pressure IN port
- **PE** : TVC valve output pressure front, rear interconnection port
- **PT** : Jet sensor upstream pressure IN port

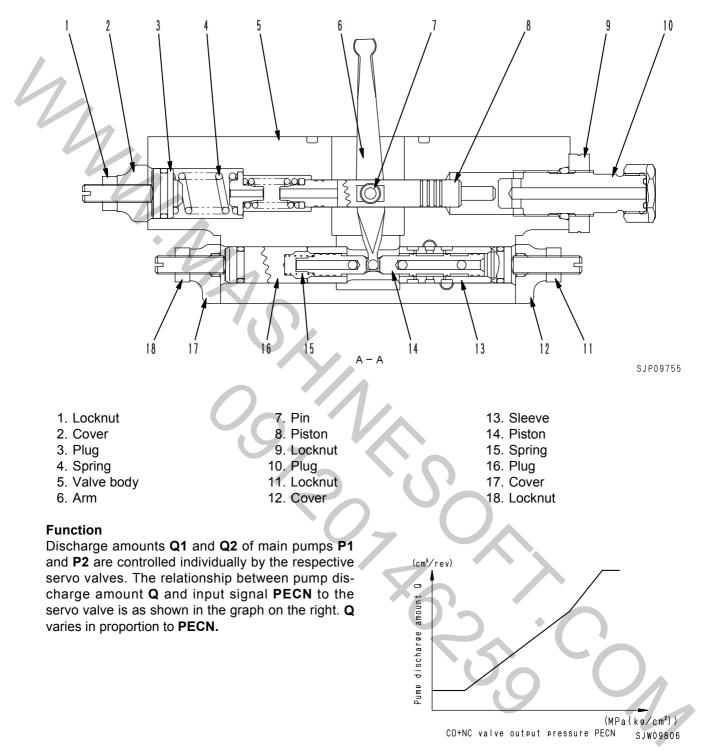
4. Servo valve (No. 1 rear)

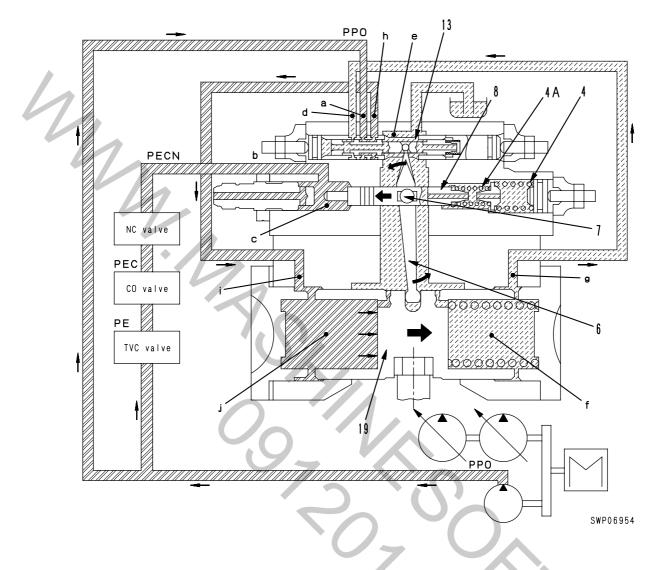


PECN : CO+NC valve output pressure IN port

Structure

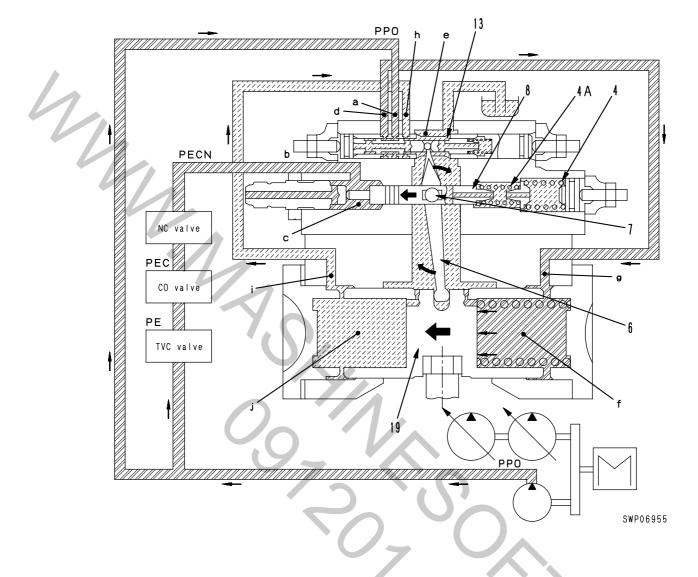
(The following illustration shows the servo valve for No. 1 rear.)





1) Operation in direction of increase of pump discharge amount (max. angle)

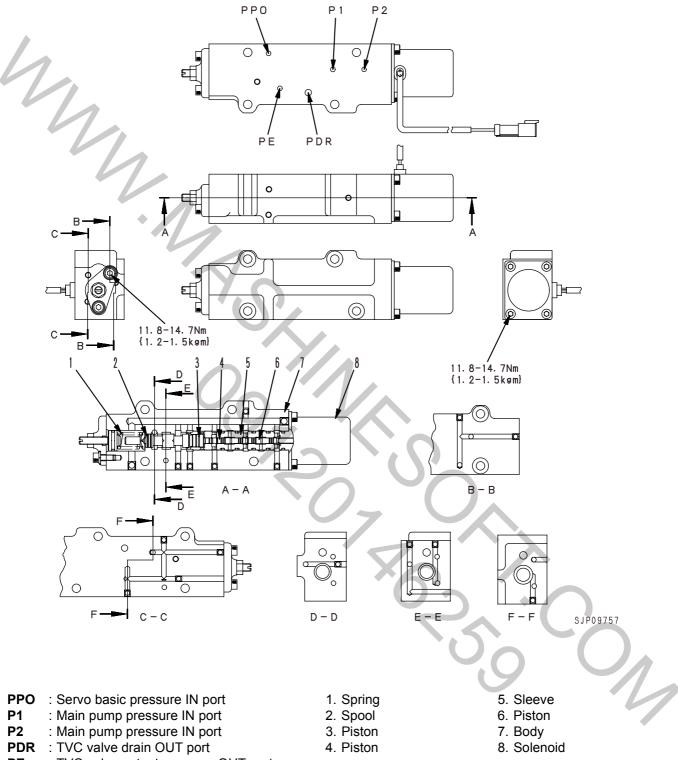
- The control pump pressure PPO is taken to port a.
- Signal pressure **PECN** from the NC valve is taken from port **b** to chamber **c**.
- When signal pressure **PECN** rises, piston (8) is pushed to the right by the pressure in chamber **c**, and stops at a point where it balances the pressure of springs (4) and (4A).
- At the same time, arm (6) uses servo piston (19) as a fulcrum and sways to the right in the same way as piston (8). This moves guide spool (13) to the right.
- When guide spool (13) moves, port a and port d are closed and port d is connected to drain chamber e. As a result, servo piston chamber f is also interconnected with drain chamber e through port g and port d.
- At the same time, port **a** is interconnected with port **h**, so the pressure oil flows through port **i** to servo piston chamber **j**, pushes servo piston (19) to the right, increases the swash plate angle in the main piston pump and increases the pump discharge amount.
- When servo piston (19) moves, arm (6) rotates counterclockwise with its center at pin (7) and moves guide spool (13) to the left. Port a, port d and port h close, so the discharge increases by an amount that matches signal pressure PECN.



2) Operation in direction of decrease of pump discharge amount (min. angle)

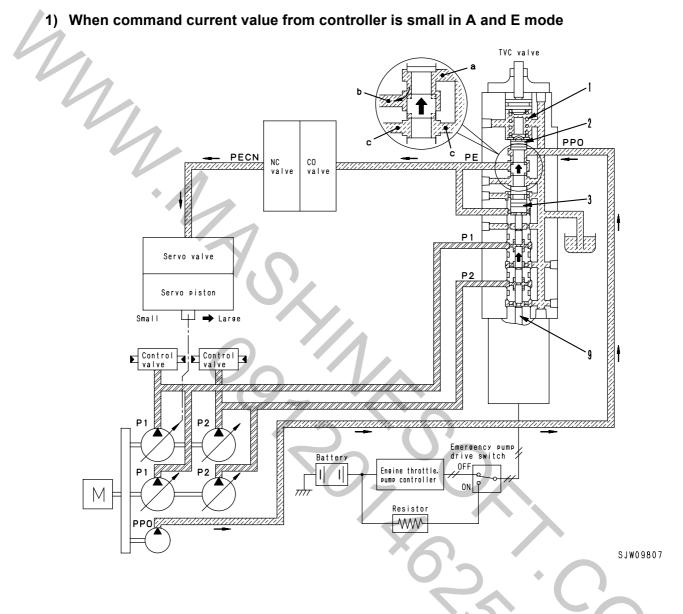
- When signal pressure PECN goes down, piston (8) moves to the left and stops at a point where the pressure in chamber c balances the pressure of springs (4) and (4A).
- At the same time, arm (6) uses servo piston (19) as a fulcrum and sways to the left in the same way as piston (8). This moves guide spool (13) to the left.
- When guide spool (13) moves, port a and port h are closed and port h is connected to drain chamber e. As a result, servo piston chamber j is also interconnected with drain chamber e through port i and port h.
- At the same time, port **a** is interconnected with port **d**, so the oil flows through port **g** to servo piston chamber **f**, pushes servo piston (19) to the left, decreases the swash plate angle in the main piston pump and decreases the pump discharge amount.
- When servo piston (19) moves, arm (6) rotates counterclockwise with its center at pin (7). Guide spool (13) is moved to the right and closes port a, port d and port h, so the discharge decreases by an amount that matches signal pressure PECN.

TVC VALVE

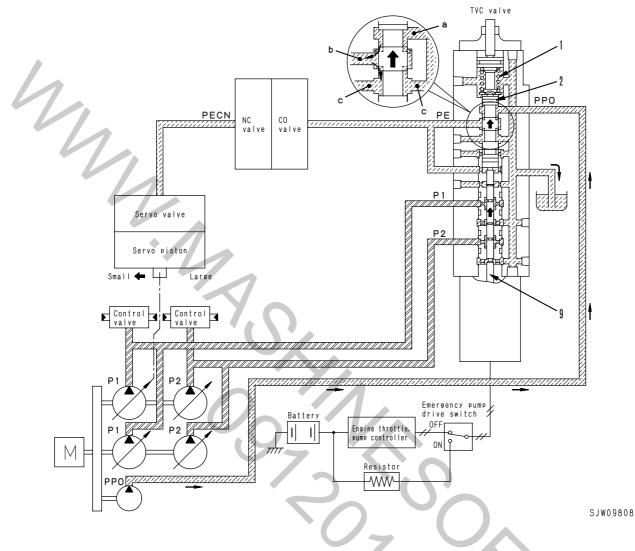


Function

- When the power mode is A-mode or E-mode, the pump discharge amount is set properly with the command current sent from the controller according to the engine speed.
- When the emergency pump drive switch is turned ON, the pump discharge amount is controlled according to the pump discharge pressure (load) by sensing the oil pressure at constant pump absorption torque.



- The command current sent from the controller actuates solenoid push pin (9) and spool (2) moves. When this happens, spool (2) stops at a point where it balances the total of the force of spring (1), the force of push pin (9), and the force of TVC output pressure PE acting on piston (3). At this time, since the command current and the force of push pin (9) are small, spool (2) is balanced on the lower side.
- As a result, ports "a" and "b" are opened almost fully and almost all the oil from the control pump is output as TVC valve output pressure PE. Then, TVC valve output pressure PE and signal pressure PECN increase, thus the pump discharge amount increases.

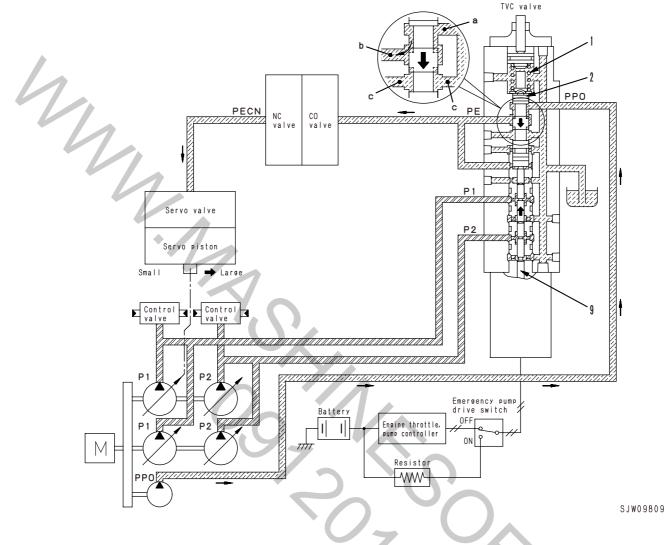


2) When command current value from controller is large in A and E mode

Operation

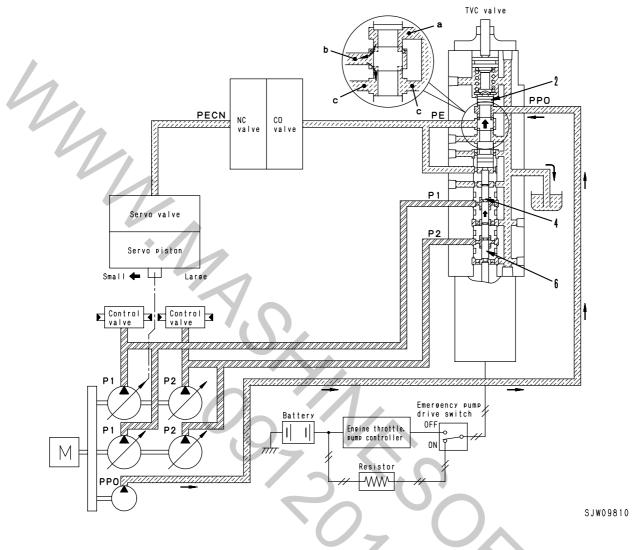
- The command current sent from the controller moves push pin (9), which moves spool (2). Spool (2) stops at a position where it is balanced with spring (1). At this time, since the command current and the force of push pin (9) are large, spool (2) is balanced on the upper side.
- As a result, the oil flow from the control pump is reduced between ports "a" and "b" and the open areas of port "b" and port "c" (drain port) increase. Then, TVC valve output pressure **PE** and signal pressure **PECN** lower, thus the pump discharge amount decreases.

'h



3) When emergency pump drive switch is turned ON and pump load is small

- If the emergency pump drive switch is turned ⁴ ON, the command current increases and the force of solenoid push pin (9) becomes larger. As a result, spring (1) is kept compressed.
- Since main pump discharge pressures **P1** and **P2** are low, spring (1) keeps pressing spool (2) down. As a result, control pump discharge pressure **PPO** becomes equal to TVC valve output pressure **PE**. At this time, TVC valve output pressure **PE** and the pump discharge amount increase.



4) When emergency pump drive switch is turned ON and pump load is large

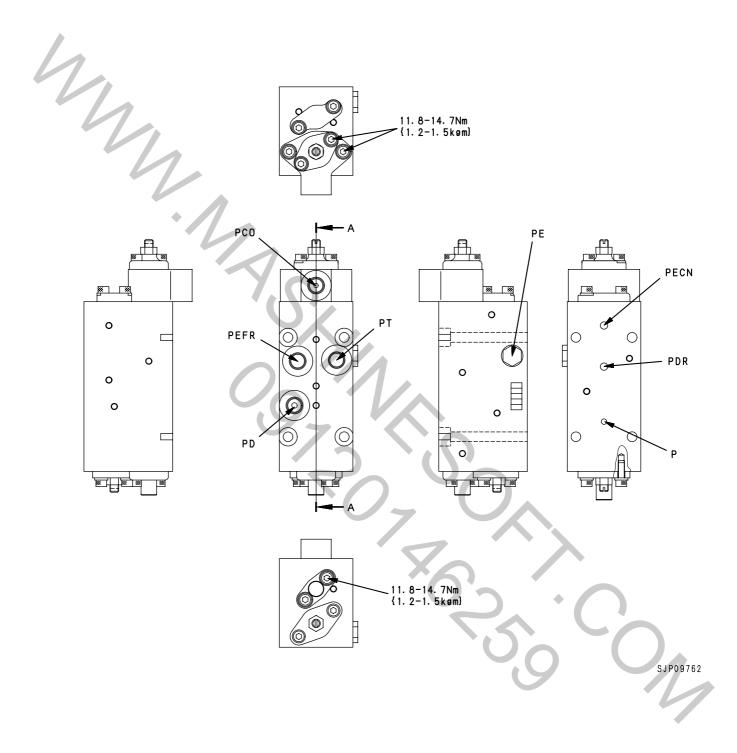
Operation

When main pump discharge pressure P1 (or P2) increases, spool (2) is moved up by piston (4) or piston (6). As a result, the flow of oil from port a to port b is throttled by the notch in the spool. At the same time, the area of the opening at port b and port c (drain port) becomes larger. In this way, TVC valve output pressure PE goes down, and the pump discharge amount decreases.

Ju -

CO+NC VALVE

1. CO+NC valve (No. 1 front)

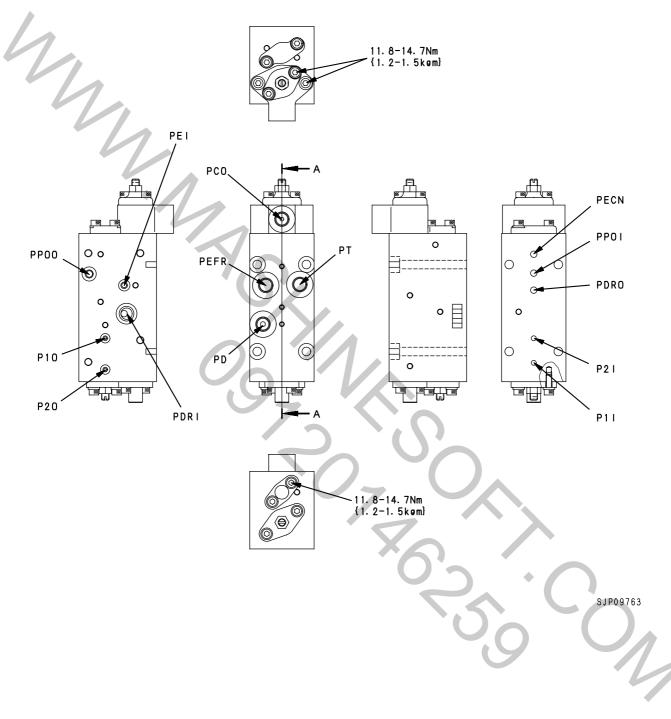


- **P** : Main pump pressure IN port
- **PEFR** : TVC valve output pressure front, rear interconnection port
- **PE** : TVC valve output pressure detection port

PCO : CO selector pilot port

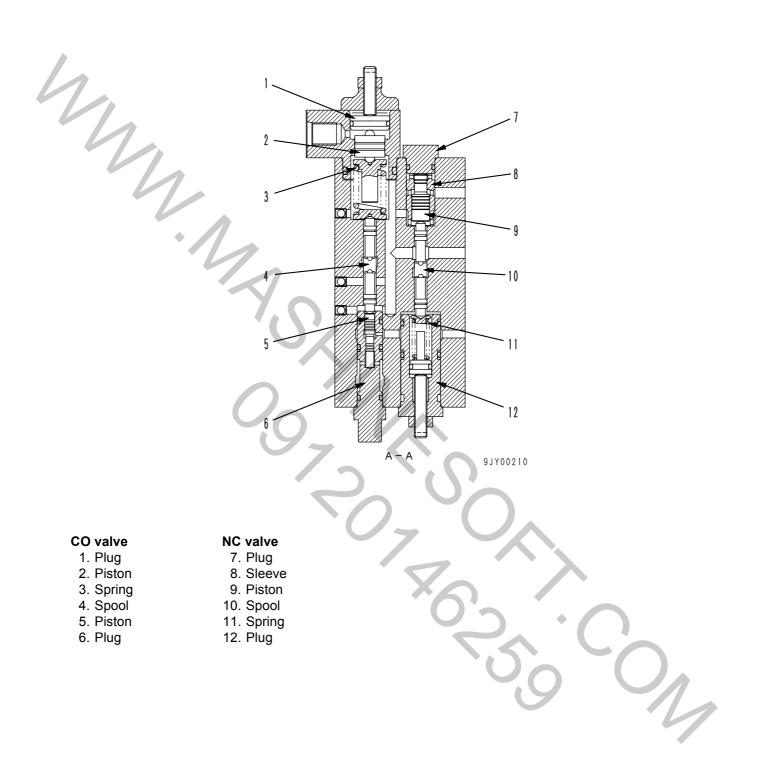
- PD : Jet sensor downstream pressure IN port
- PT : Jet sensor upstream pressure IN port
- **PDR** : CO+NC valve drain OUT port
- **PECN** : CO+NC valve output pressure OUT port

2. CO+NC valve (No. 1 rear)



- P1I : Main pump pressure IN port (front)
- P10 : Main pump pressure OUT port
- P2I : Main pump pressure IN port (rear)
- **P2O** : Main pump pressure OUT port
- **PEFR** : TVC valve output pressure front, rear interconnection port
- PEI : TVC valve output pressure IN port
- PCO : CO selector pilot port

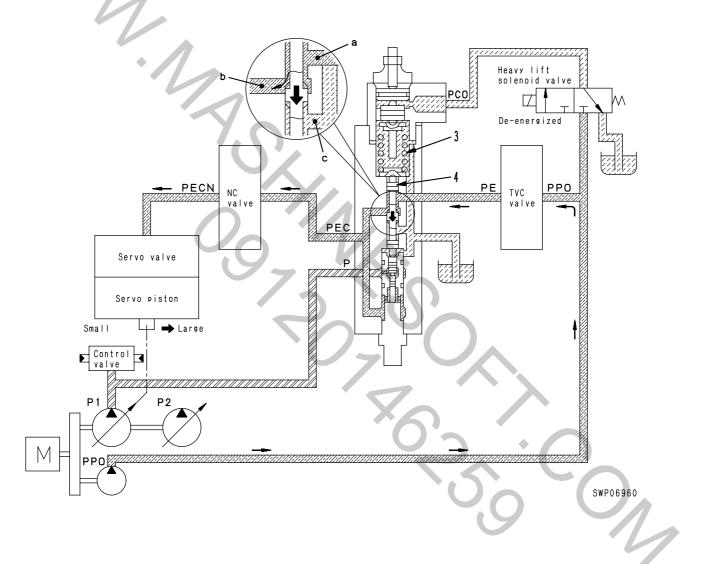
- **PD** : Jet sensor downstream pressure IN port
- **PT** : Jet sensor upstream pressure IN port
- PDRI : TVC valve drain IN port
- PDRO : CO+NC valve drain OUT port
- **PPOI** : Servo basic pressure IN port
- **PPOO** : Servo basic pressure OUT port
- $\ensuremath{\text{PECN}}$: CO+NC valve output pressure OUT port



3. CO valve

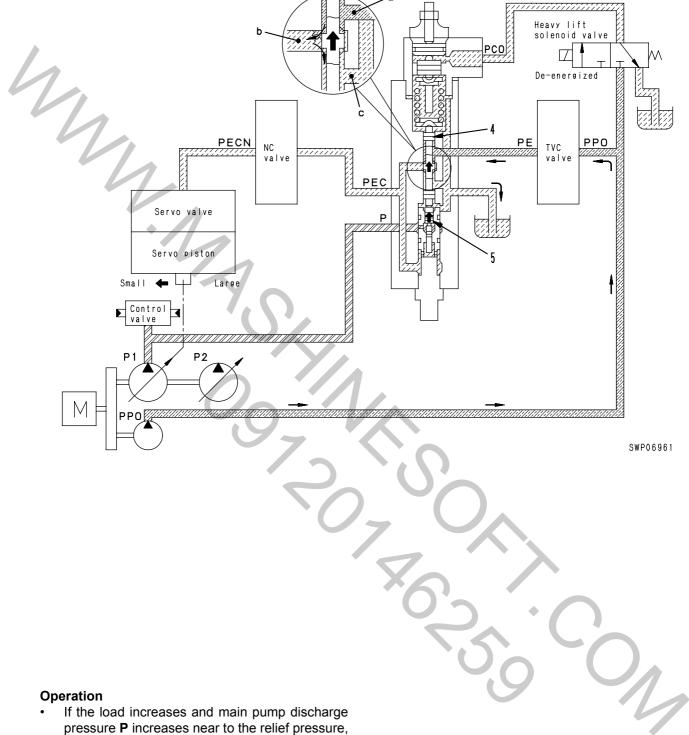
Function

- When the load becomes large during operations and the main pump discharge pressure rises to a point close to relief pressure, the cut-off function of the CO valve acts to reduce the pump discharge in order to reduce relief loss.
- At the same time, it has a cut-off cancel function actuated by the pilot pressure from the heavy-lift solenoid valve.
- The CO valve is controlled by balancing the spring with the total of main pump discharge pressure **P** and CO valve output pressure **PEC**.
- 1) When main pump discharge pressure is lower than relief pressure



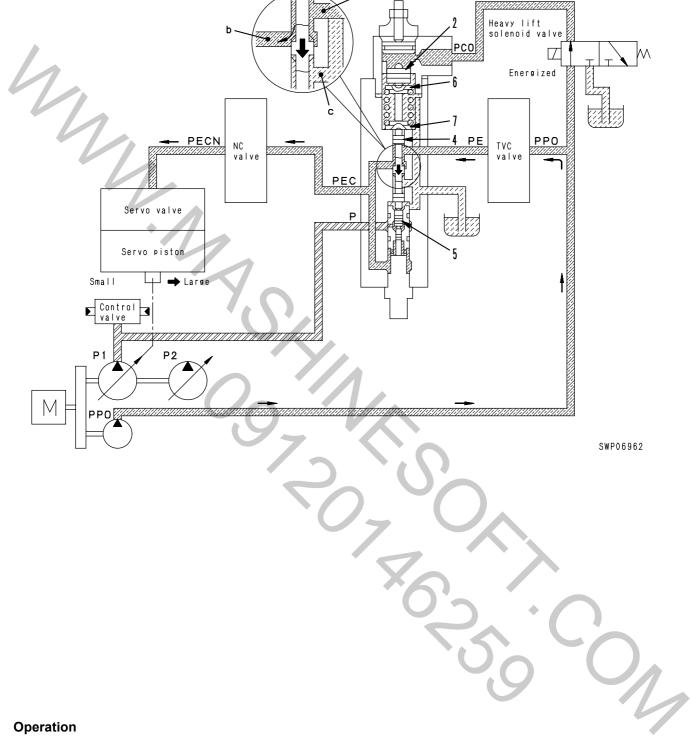
Operation

Spool (4) is pressed down by spring (3). As a result, ports "a" and "b" are opened fully, and TVC valve output pressure PE is equal to CO valve output pressure PEC. Accordingly, CO valve output pressure PEC, signal pressure PECN, and pump discharge amount become maximum.



2) When main pump discharge pressure becomes close to relief pressure

- If the load increases and main pump discharge pressure P increases near to the relief pressure, main pump discharge pressure P presses piston (5). At the same time, CO valve output pressure PEC presses piston (5) and spool (4) moves up.
- As a result, oil flow from port "a" to port "b" is reduced by the notch of the spool and the open areas of port "b" and port "c" (drain port) increase. Accordingly, CO valve output pressure PEC and signal pressure PECN lower and the pump discharge amount becomes minimum.



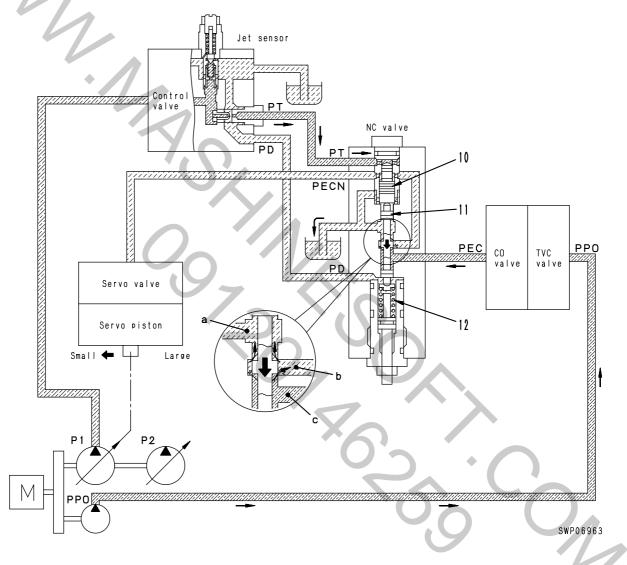
3) When cut-off function is canceled by heavy-lift solenoid valve

- If the heavy lift solenoid valve is turned ON, its pilot pressure PCO is lead in the port and piston (2) is pressed down. Accordingly, seat (6) touches seat (7) and locks spool (4).
- As a result, even if main pump discharge pres-• sure **P** increases to the relief pressure, spool (4) does not operate. Accordingly, CO valve output pressure PEC keeps maximum and the pump discharge amount does not decrease.

4. NC valve

Function

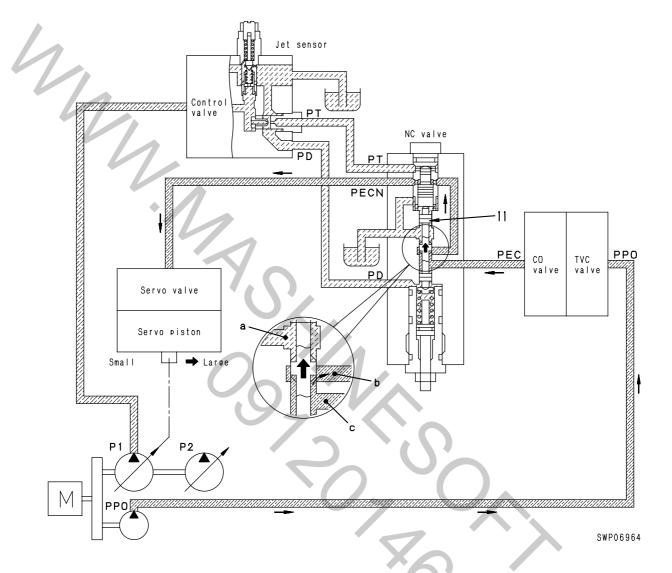
- The NC valve controls the main pump discharge amount to reduce the neutral loss and fine control loss according to the moving distance of the control valve spool.
- The main pump discharge amount is controlled by balance of the sum of jet sensor upstream pressure PT and NC valve output pressure PECN and the sum of the force of NC valve spring (12) and jet sensor downstream pressure PD.
- The jet sensor senses the flow of the oil returning through the control valve to the tank and use it as PT and PD of the NC valve.



1) When control valve is at neutral

- When the control valve is at neutral, jet sensor differential pressure (PT – PD) becomes the maximum, and the force of jet sensor output pressure PT pushing piston (10) becomes larger than the total of the force of spring (12) and the force of jet sensor output pressure PD pushing the bottom of spool (11).
- As a result, spool (11) is pushed down, so the flow from port **c** to port **b** is throttled, and the area of the opening of port **b** and port **a** (drain port) becomes larger. In this way, NC valve output pressure **PECN** becomes the minimum, and the main pump discharge amount also becomes the minimum.

2) When control lever is operated

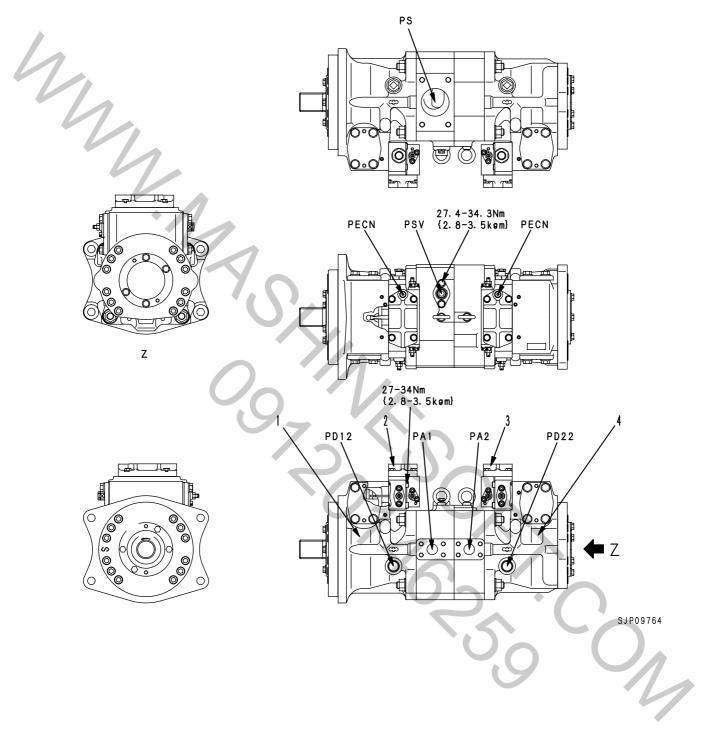


Operation

When the control lever is moved, the jet sensor differential pressure (PT – PD) goes down in accordance with the movement of the control lever. Spool (11) is pushed up, and the area of the opening of port c and port b becomes larger. In this way, NC valve output pressure PECN becomes larger and the discharge amount from the main pump increases. In other words, the pump discharge amount increases according to the amount that the control lever is operated.

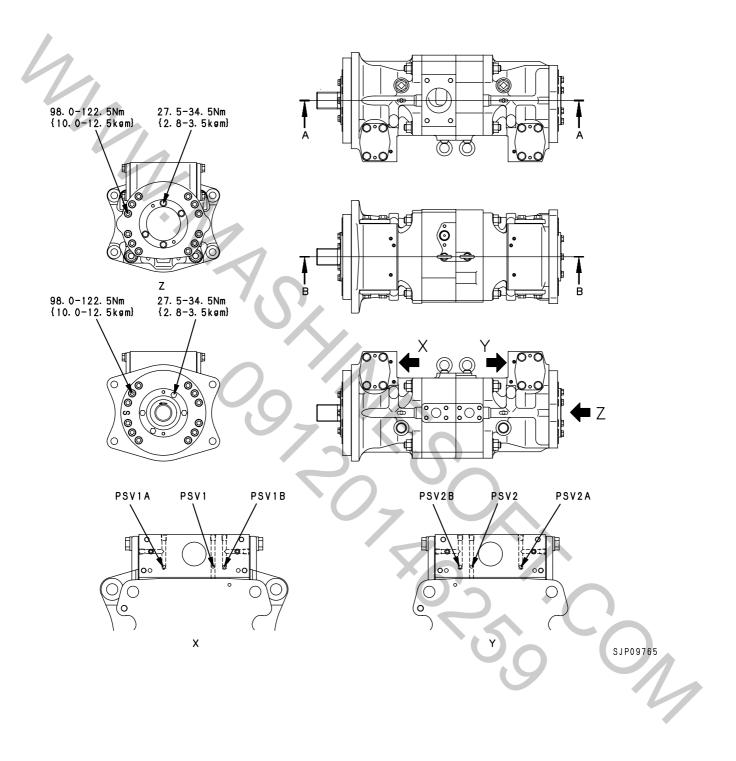
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No. 2 MAIN PUMP MODEL: HPV95+95

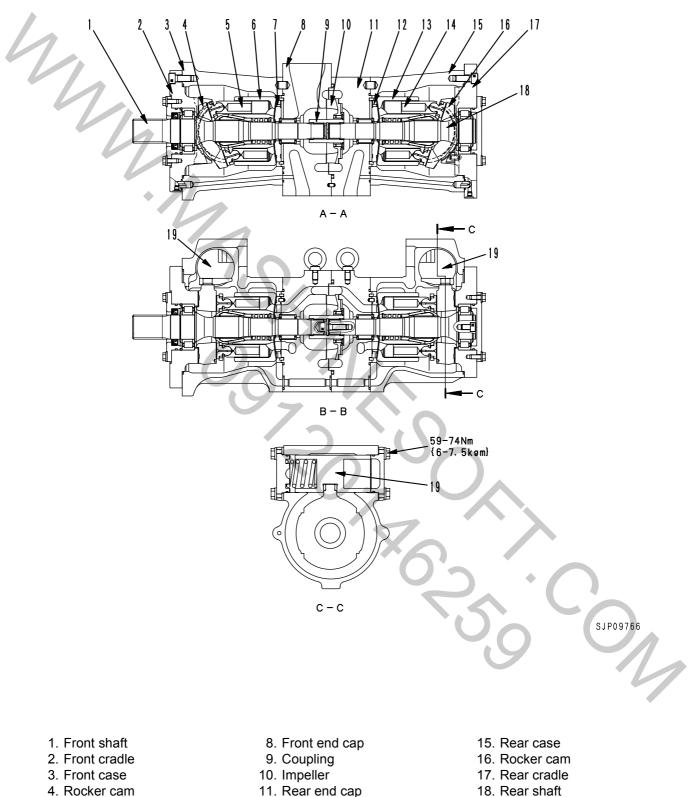


- **PA1** : Front pump discharge port
- PA2 : Rear pump discharge port
- PD12 : Drain port
- PD22 : Drain port
- **PS** : Pump suction port
- **PSV** : Servo basic pressure IN port
- **PECN** : CO+NC valve output pressure port
- 1. Front pump
- 2. Front servo valve
- 3. Rear servo valve
- 4. Rear pump

No. 2 main pump



- **PSV1** : Servo valve basic pressure port
- **PSV2** : Servo valve basic pressure port
- **PSV1A** : Servo piston output port
- **PSV1B** : Servo valve output port
- PSV2A : Servo piston output port
- **PSV2B** : Servo valve output port



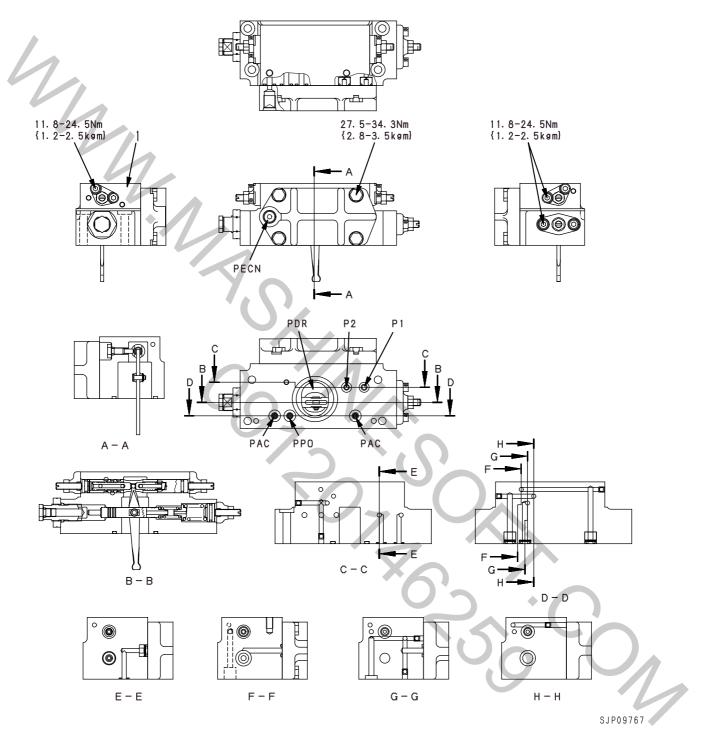
- 5. Piston
- 6. Cylinder block
- 7. Valve plate

- 12. Valve plate
- 13. Cylinder block
- 14. Piston

- 19. Servo piston

SERVO VALVE

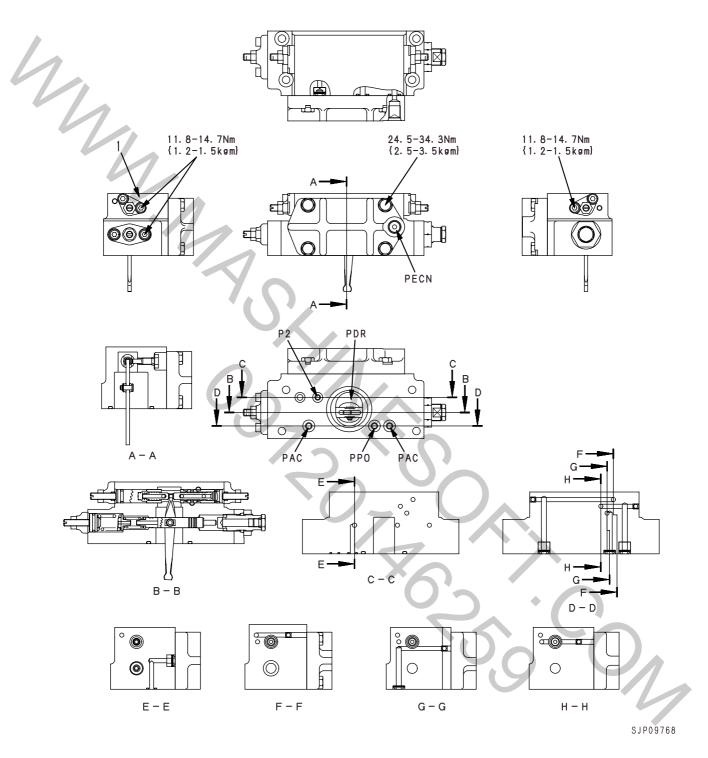
1. Servo valve (No. 2 front)



1. Servo valve

- P1 : Main pump pressure IN port
- P2 : Main pump pressure IN port
- PAC : Servo actuator port
- **PDR** : Servo valve drain OUT port
- **PPO** : Servo basic pressure IN port
- $\ensuremath{\text{PECN}}$: CO+NC valve output pressure IN port

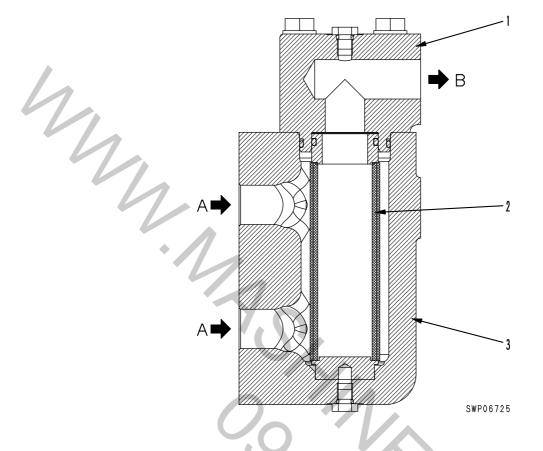
2. Servo valve (No. 2 rear)



1. Servo valve

- P2 : Main pump pressure IN port
- PAC : Servo actuator port
- PDR : Servo valve drain OUT port
- PPO : Servo basic pressure IN port
- **PECN** : CO+NC valve output pressure IN port
- PC600, 600LC-7

LINE OIL FILTER



- 1. Cover
- 2. Element
- 3. Case
- A: From main pump
- B: To control valve

Outline

There are two line oil filters installed to the discharge side of the main pump. They protect the circuit and equipment by removing all dirt and dust from the oil.

1

MMM MASHINGOTATION

CONTROL VALVE

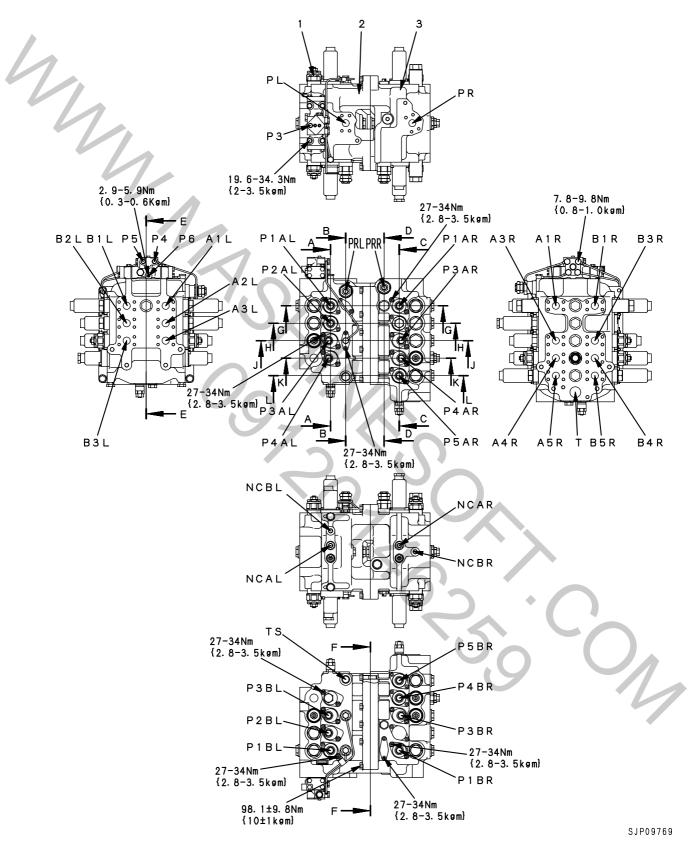
Outline

- This control valve consists of a 4-spool valve and a 5-spool valve, and a travel shuttle valve is also installed to it. Furthermore, a straight-travel valve, arm throttle valve, and swing priority valve are built in.
- The 4-spool and 5-spool valves are connected by bolts to form one unit, and internal merging of the oil flow makes it even more compact and easy to maintain.
- A1L : To L.H. travel motor PB port
- A2L : To boom cylinder bottom
- A3L : To bucket cylinder head
- A1R : To swing motor MA port
- A3R : Service
- A4R : To arm cylinder head
- A5R : To R.H. travel motor PA port
- B1L : To L.H. travel motor PA port
- B2L : To boom cylinder head
- B3L : To bucket cylinder bottom
- B1R : To swing motor MB port
- B3R : Service
- B4R : To arm cylinder bottom
- B5R : To R.H. travel motor PB port
- NCAL : To rear NC valve
- **NCBL** : To rear NC valve
- NCAR : To front NC valve
- NCBR : To front NC valve
- **P3** : From arm PPC shuttle valve
- P4 : From boom, bucket PPC shuttle valve
- **P5** : From swing PPC shuttle valve
- P6 : Work equipment oil pressure switch
- 1. Travel shuttle valve
- 2. 4-spool valve
- (straight-travel valve, arm throttle valve built in)
- 3. 5-spool valve (swing priority valve built in)

- **P1AL** : From L.H. travel PPC valve
- **P2AL** : From boom PPC valve
- **P3AL** : From bucket PPC valve
- P4AL : From arm PPC valve
 - **P1AR** : From swing PPC valve
 - P3AR : Service
 - P4AR : From arm PPC valve
- **P5AR** : From R.H. travel PPC valve
- P1BL : From L.H. travel PPC valve
- P2BL : From boom PPC valve
- P3BL : From bucket PPC valve
- **P1BR** : From swing PPC valve
- P3BR : Service
- P4BR : From arm PPC valve
- **P5BR** : From R.H. travel PPC valve
- PL : From rear main pump
- **PR** : From front main pump
- PRL : From 2-stage relief solenoid valve
- **PRR** : From 2-stage relief solenoid valve
 - : To tank
- TS : To tank

Т

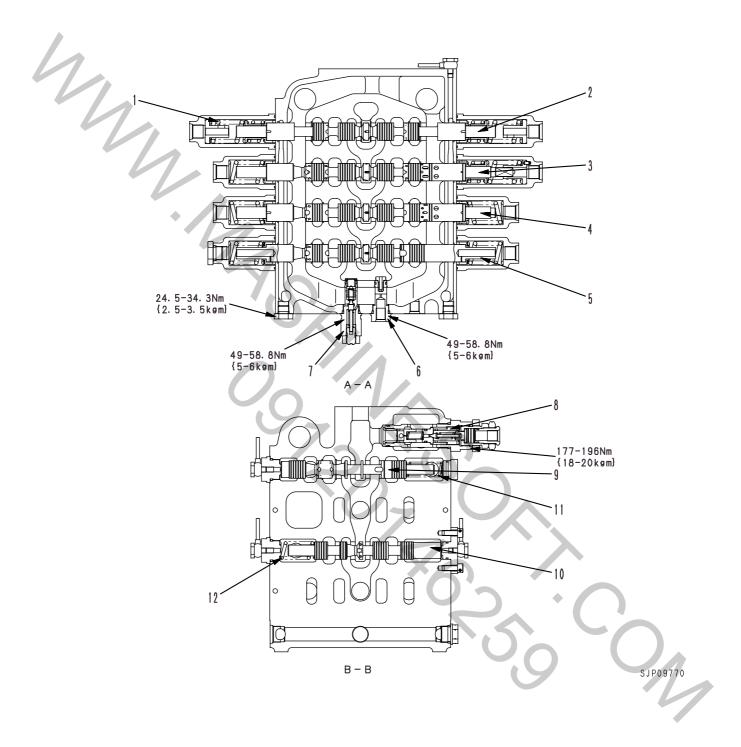
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4-spool valve + 5-spool valve (with travel shuttle valve)

Cross-sectional diagram

(1/4)



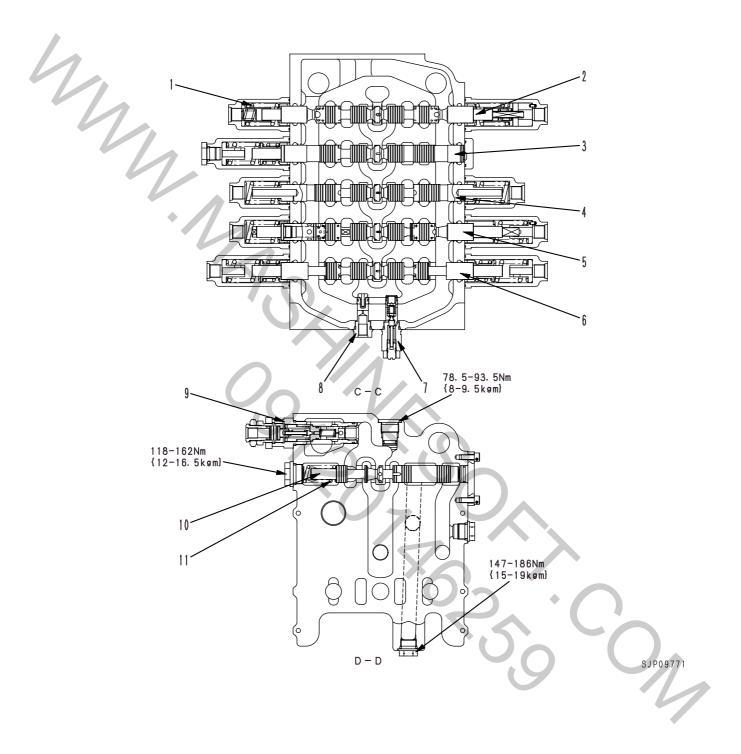
1. Spool return spring

- 2. Spool (L.H. travel)
- 3. Spool (boom Lo)
- 4. Spool (bucket Lo)
- 5. Spool (arm Hi)

- 6. Jet sensor orifice
- 7. Jet sensor relief valve
- 8. Main relief valve
- 9. Spool (straight-travel)
- 10. Spool (arm throttle)

Unit: mm Remedy No. Check item Criteria Standard size Repair limit Installed Installed Free Installed Free length Replace 11 Spool return spring x OD length load length load spring if 192 N 154 N damaged or 87.6 x 21.2 54.5 {19.6 kg} {15.7 kg} deformed 324 N 259 N 12 Spool return spring 58.1 x 26.5 52.5 {33.0 kg} {26.4 kg}

(2/4)



- 1. Spool return spring
- 2. Spool (swing)
- 3. Spool (boom Hi)
- 4. Spool (service / bucket Hi)
- 5. Spool (arm Lo)

- 6. Spool (R.H. travel)
- 7. Jet sensor relief valve
- 8. Jet sensor orifice
- 9. Main relief valve
- 10. Spool (swing priority)

hung Unit: mm No. Check item Criteria Remedy Standard size Repair limit Replace Installed Installed Installed Free length Free spring if 1 Spool return spring x OD length load length load damaged or deformed

52.5

53.8 x 26.5

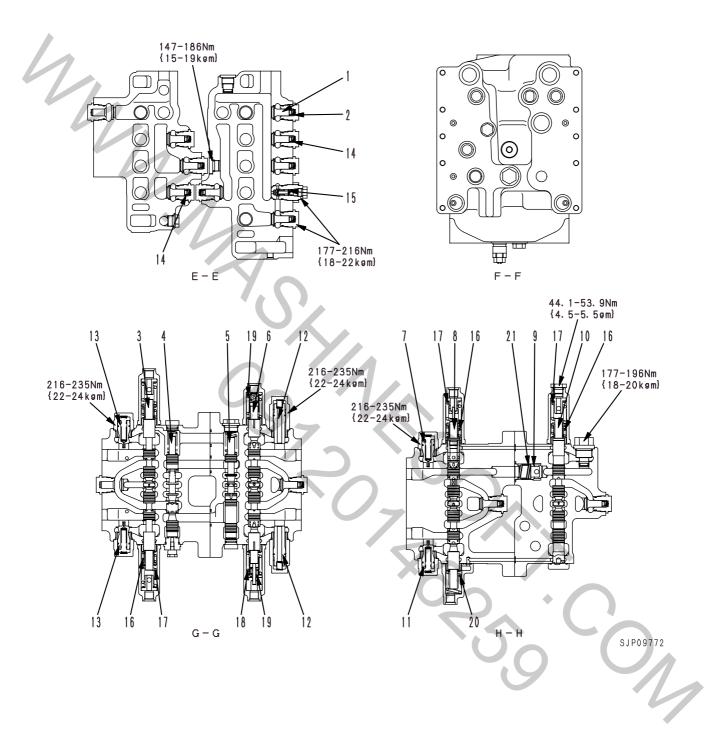
104 N

{10.6 kg}

83.4 N

{8.50 kg}

(3/4)



- 1. Check valve
- 2. Check valve spring
- 3. Spool (L.H. travel)
- 4. Spool (straight-travel)
- 5. Spool (swing priority)
- 6. Spool (swing)
- 7. Suction valve

- 8. Spool (boom Lo)
- 9. Check valve
- 10. Spool (boom Hi)
- 11. Suction valve
- 12. Suction valve
- 13. Suction valve

(5/6)

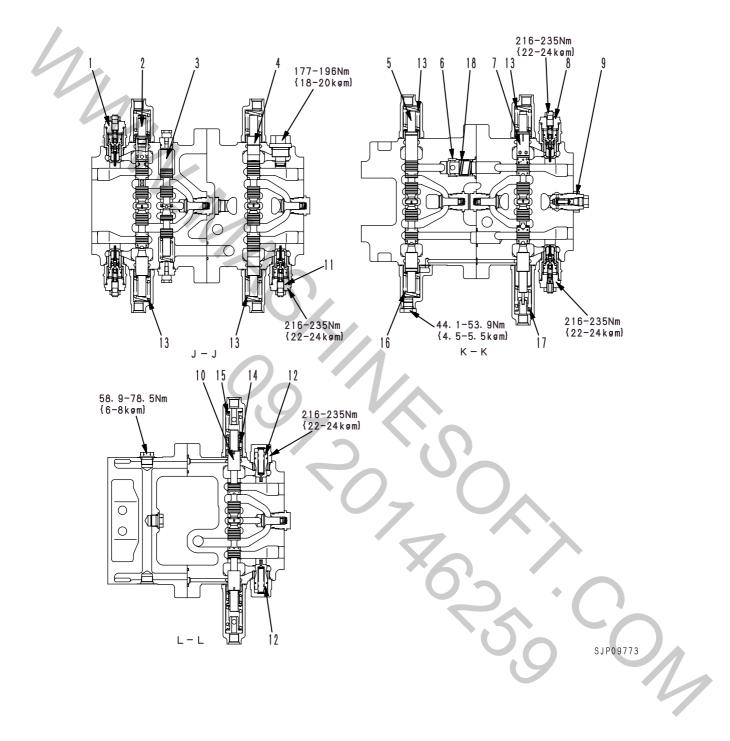
hung

Unit: mm

		· ·					
No.	Check item	Criteria					Remedy
14	Check valve spring	Standard size			Repair limit		
		Free length x OD	Installed length	Installed load	Free length	Installed load	-
		20.8 x 12.2	13.5	12.7 N {1.3 kg}	_	10.2 N {1.04 kg}	
15	Check valve spring	31.8 x 7.6	26.5	0.98 N {0.10 kg}		0.78 N {0.08 kg}	
16	Spool return spring	30.7 x 32.5	26.5	255 N {26.0 kg}	90	204 N {20.8 kg}	Replace spring if
17	Spool return spring	54.0 x 34.2	52.0	255 N {26.0 kg}		204 N {20.8 kg}	damaged or deformed
18	Spool return spring	54.8 x 34.0	53.5	125 N {12.7 kg}	_	100 N {10.2 kg}	
19	Spool return spring	21.0 x 16.9	18.2	207 N {21.1 kg}	_	_	
20	Spool return spring	54.9 x 34.0	53.5	125 N {12.7 kg}	_	100 N {10.2 kg}	
21	Check valve spring	55.9 x 30.2	29.0	7.85 N {0.80 kg}	_	6.28 N {0.64 kg}	

00-1/2

(4/4)



- 1. Suction-safety valve
- 2. Spool (bucket Lo)
- 3. Spool (arm throttle)
- 4. Spool (service / bucket Hi)
- 5. Spool (arm Hi)
- 6. Check valve

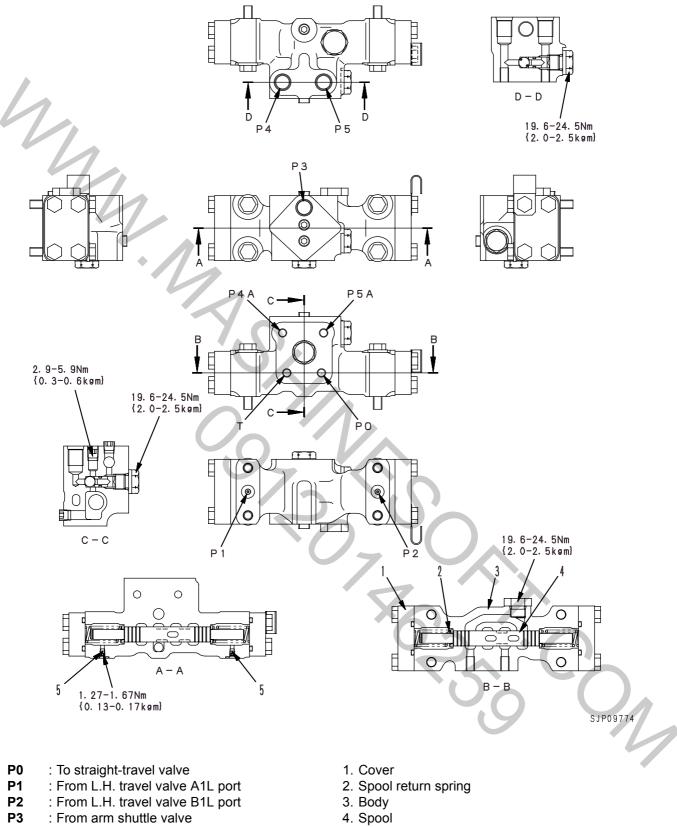
- 7. Spool (arm Lo)
- 8. Suction-safety valve
- 9. Check valve
- 10. Spool (R.H. travel)
- 11. Suction-safety valve
- 12. Suction valve

hung

Unit: mm

							Onit. min
No.	Check item			Criteria			Remedy
13	Spool return spring	Standard size			Repair limit		
		Free length x OD	Installed length	Installed load	Free length	Installed load	
		54.8 x 34.0	53.5	125 N {12.7 kg}	-9	100 N {10.2 kg}	
14	Spool return spring	30.7 x 32.5	26.5	255 N {26.0 kg}	_	204 N {20.8 kg}	Replace
15	Spool return spring	54.0 x 34.2	52.0	255 N {26.0 kg}	_	204 N {20.8 kg}	spring if damaged or deformed
16	Spool return spring	54.8 x 34.0	53.5	125 N {12.7 kg}	_	100 N {10.2 kg}	
17	Spool return spring	54.9 x 34.0	53.5	125 N {12.7 kg}	_	100 N {10.2 kg}	
18	Check valve spring	55.9 x 30.2	29.0	7.85 N {0.80 kg}	_	6.28 N {0.64 kg}	

TRAVEL SHUTTLE VALVE



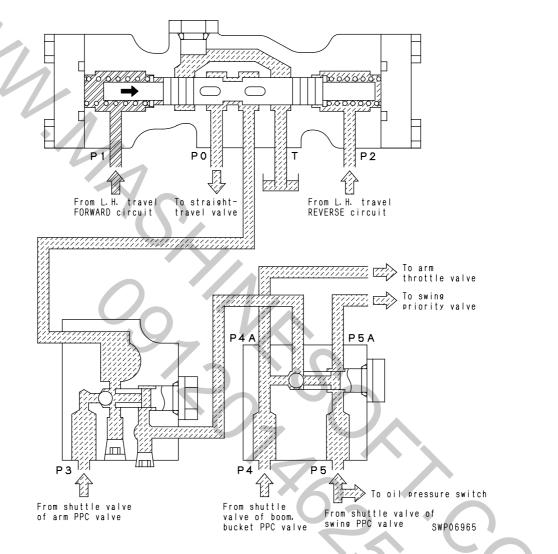
- P4 : From boom, bucket shuttle valve
- **P5** : From swing shuttle valve
- **P4A** : To arm throttle valve
- **P5A** : To swing priority valve
- T : To tank

5. Orifice

Function

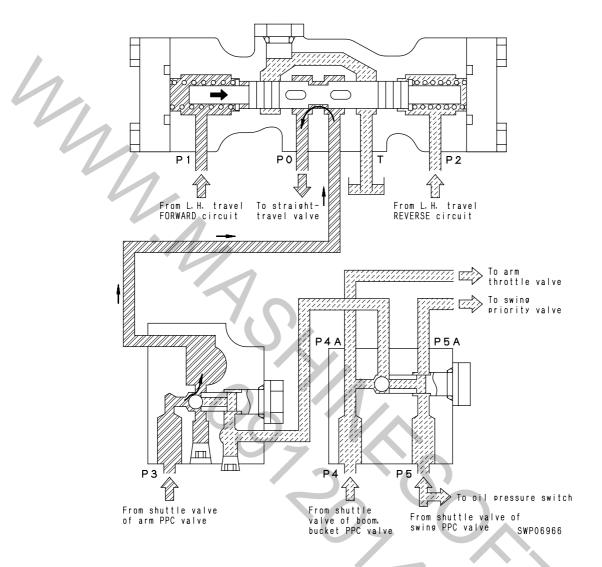
• The travel shuttle valve is installed to the top of the 4-spool valve control valve. It brings the PPC valve pressures from the L.H. travel, work equipment, and swing. It also sends pilot pressure to the straight-travel valve when the travel and work equipment or travel and swing are operated at the same time.

When control valve is at neutral



- When the travel FORWARD is operated, pilot pressure oil flows from the L.H. travel circuit to port P1 and pushes the spool to the right. Ports P3, P4, and P5 are interconnected with port P0 through the groove in the spool to the straight-travel valve.
- However, when the work equipment and swing control levers are at HOLD, the pilot pressure oil from the PPC valve does not flow, so it also does not flow to the straight-travel valve.
- When the travel reverse is operated, the pressure oil is sent to port P2 and pushes the spool to the right.

2) During simultaneous operation



Operation

- When the arm and travel FORWARD are operated at the same time, pilot pressure oil flows from the L.H. travel circuit to port **P1** and pushes the spool to the right.
- When the arm is operated, pilot pressure oil also flows to port **P3** from the arm PPC shuttle valve. This passes through the groove in the spool and port **P0**, and flows to the straight-travel valve.
- The pilot pressure oil from the swing PPC shuttle valve flows from port $P5 \rightarrow port P0 \rightarrow straight-travel valve, and the pilot pressure oil from the boom and bucket PPC shuttle valves flows from port P4 <math>\rightarrow$ port P0 \rightarrow straight-travel valve.

4

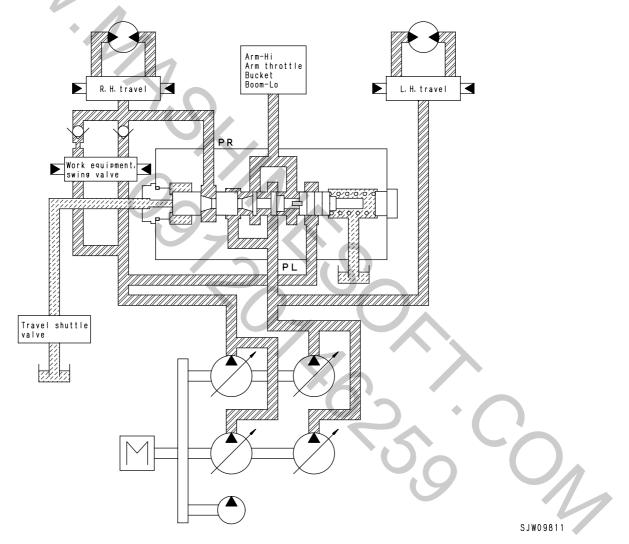
STRAIGHT-TRAVEL VALVE

Function

When the travel is operated at the same time as the boom, arm, or bucket, the pressure oil flowing to the left and right travel circuits is divided and sent to the boom, arm, or bucket circuit. If the oil in one travel circuit is divided off, the amount of oil supplied to the travel motor will be less than in the travel circuit which is not divided, so the drop in the supply of oil to the travel motor will cause the machine to deviate.

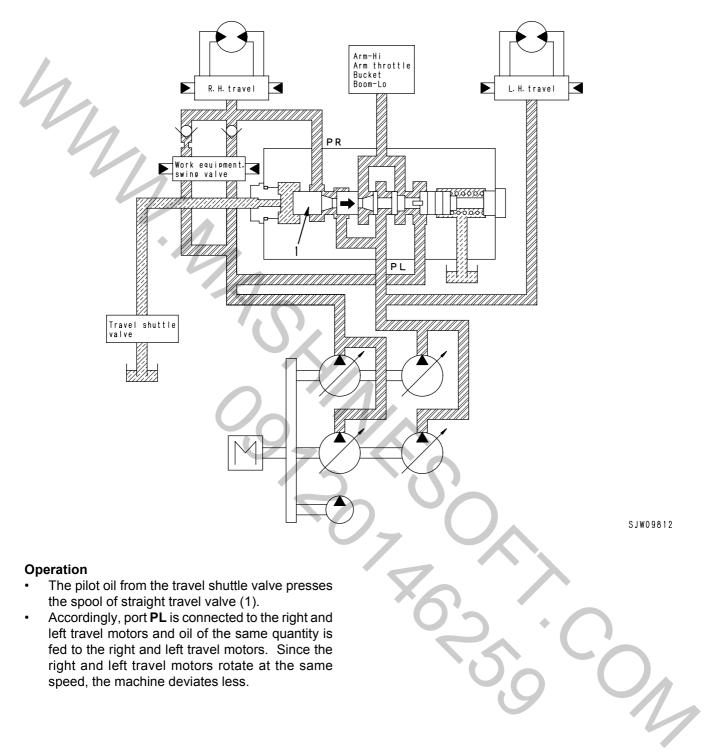
1) When travel is operated independently

- To prevent this, the straight-travel valve is switched to interconnect the left and right travel circuits. This ensures that the amount of oil supplied to the left and right travel motors is equal.
- As a result, the left and right travel motors both rotate at the same speed, and there is little travel deviation.



Operation

- No pilot pressure flows from the travel shuttle valve, so the straight-travel valve is not actuated.
- Because of this, port **PL** (L.H. travel circuit) and port **PR** (R.H. travel circuit) are not interconnected, and each circuit remains independent.

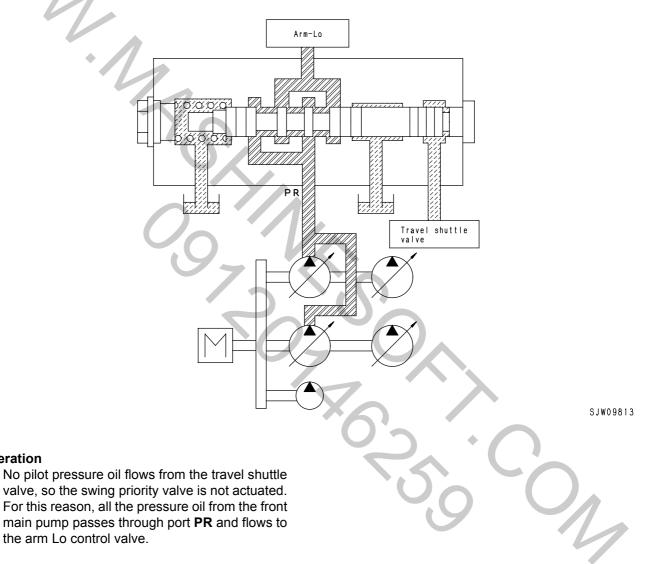


2. When travel and work equipment are operated at same time

SWING PRIORITY VALVE

Function

- When the swing and arm are operated at the same time, a large amount of the pressure oil flows to the arm circuit where the load is small, so little pressure oil flows to the swing circuit. This makes the arm speed too fast for the swing speed, and causes poor combination in simultaneous operation.
- To overcome this, the swing priority valve is ac-• tuated to throttle the pressure oil flowing to the arm Lo control valve in order to restrict the arm speed and improve the simultaneous operation performance.

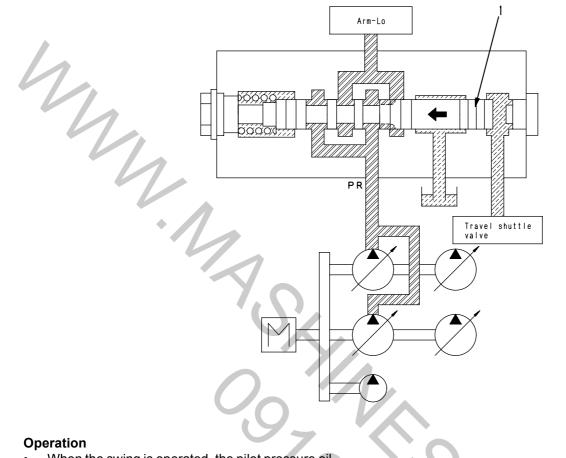


1) When swing is at HOLD

Operation

the arm Lo control valve.

2. When swing is operated



- When the swing is operated, the pilot pressure oil from the travel shuttle valve pushes spool (1) of the swing priority valve to the left.
- As a result, the pressure oil flowing from the front main pump through port **PR** to the arm Lo control valve is throttled, and the arm speed is restricted to improve the simultaneous operation performance.

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ARM THROTTLE VALVE

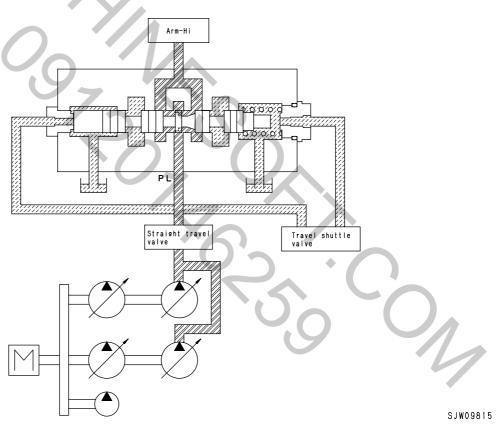
Function

When arm and boom are operated at same time

- When the arm and boom are operated at the same time, a large amount of the pressure oil flows to the arm circuit where the load is small, so little pressure oil flows to the boom circuit.
- This makes the arm speed too fast for the boom speed, and causes poor combination in simultaneous operation. This is a particular problem when the arm OUT and boom RAISE are operated at the same time.
- To overcome this, the arm throttle valve is actuated to throttle the pressure oil flowing to the arm Hi control valve in order to restrict the arm speed and improve the simultaneous operation performance.

When arm and bucket are operated at same time

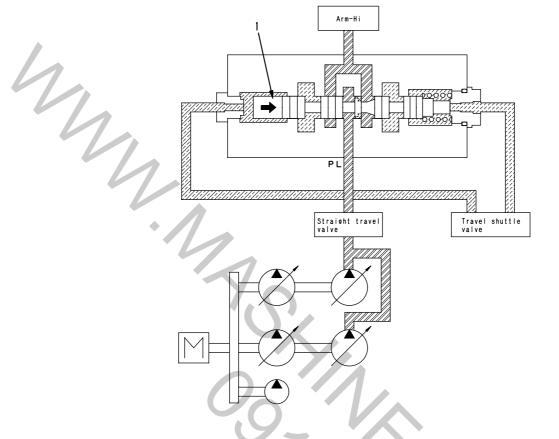
- The arm is actuated by the merged flow from two pumps and the bucket is actuated by the oil from one pump.
- In this condition, if the arm and bucket are operated at the same time, a large amount of the pressure oil flows to the arm circuit, so little pressure oil flows to the bucket circuit. This makes the arm speed too fast for the bucket speed, and causes poor combination in simultaneous operation. This is a particular problem when the arm OUT and bucket CURL are operated at the same time.
- To overcome this, the arm throttle valve is actuated to throttle the pressure oil flowing to the arm Hi control valve in order to restrict the arm speed and improve the simultaneous operation performance.



Operation

- No pilot pressure oil flows from the travel shuttle valve, so the arm throttle valve is not actuated.
- For this reason, all the pressure oil from the rear main pump passes through port **PL** and flows to the arm Hi control valve.

1) When arm is operated independently



2. When arm and boom or bucket are operated at same time

Operation

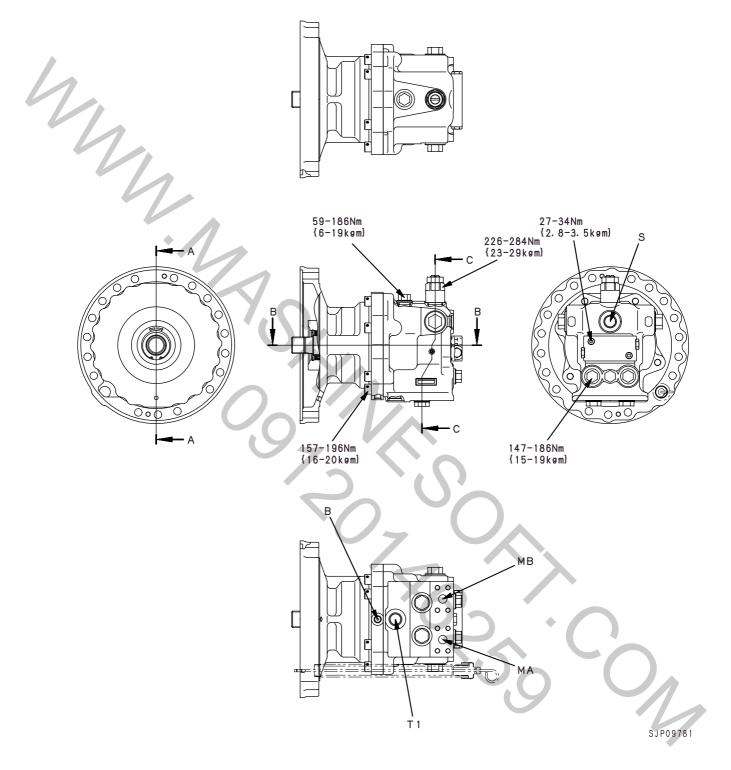
- When the arm and boom or bucket are operated at the same time, the pilot pressure oil from the travel shuttle valve pushes spool (1) of the arm throttle valve to the right.
- As a result, the pressure oil flowing from the rear main pump to the arm Hi control valve is throttled, and the arm speed is restricted to improve the simultaneous operation performance.

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SWING MOTOR

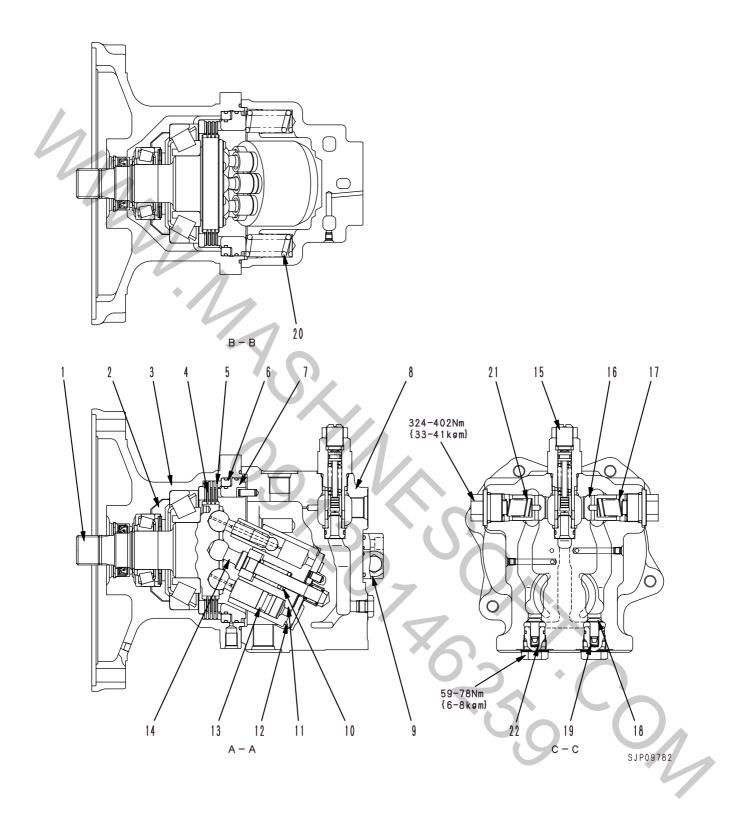
MODEL: KMF90ABE-3 (with reverse prevention valve)



- T1 : To tank
- S : From control valve
- **MA** : From control valve
- **MB** : From control valve
- **B** : From swing brake solenoid valve

Specifications

Model: KMF90ABE-3 Theoretical delivery: 87.8 cc/rev Safety valve set pressure: 25.5 MPa {260 kg/cm²} Rated speed: 2,320 rpm Brake release pressure: 2.06 MPa {21.0 kg/cm²}



- 1. Drive shaft
- 2. Spacer
- 3. Case
- 4. Disc
- 5. Plate
- 6. Brake ring
- 7. Brake piston

- 8. Housing
- 9. Reverse prevention valve
- 10. Center spring
- 11. Cylinder block
- 12. Valve plate
- 13. Piston
- 14. Center shaft

- 15. Safety valve
- 16. Check valve
- 17. Check valve spring
- 18. Shuttle valve
- 19. Shuttle valve spring
- 20. Brake spring

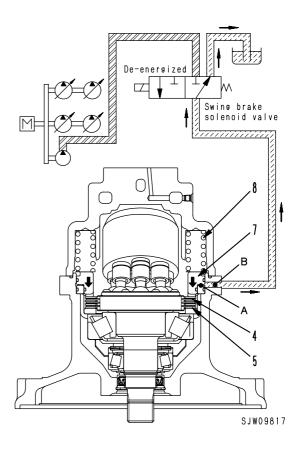
Unit: mm Remedy No. Check item Criteria Standard size Repair limit Installed Installed Free Installed Free length Replace 21 Check valve spring x OD length load length load spring if 3.04 N 2.45 N damaged or 62.5 x 20.0 39 {0.31 kg} {0.25 kg} deformed 13.7 N 11 N 22 16.4 x 8.9 Shuttle valve spring 11.5 {1.4 kg} {1.12 kg}

SWING BRAKE

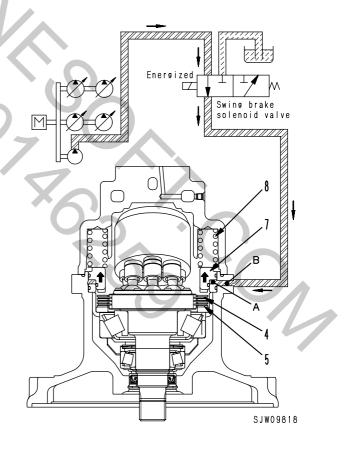
Operation

- 1. When swing brake solenoid valve is de-energized
- If the swing brake solenoid valve is de-energized, the flow of pressurized oil from the control pump is shut off, and port **B** is connected to the tank circuit.
- As a result, brake piston (7) is pushed down by brake spring (8), pushes disc (4) and plate (5) together, and the brake is applied.

·MA



- 2. When swing brake solenoid valve is energized
- When the swing brake solenoid valve is energized, the valve is switched, and pressurized oil from the control pump enters port B and flows to brake chamber A.
- The pressurized oil entering chamber A overcomes brake spring (8) and brake piston (7) moves up. As a result, disc (4) and plate (5) are separated and the brake is released.



SAFETY VALVE

Outline

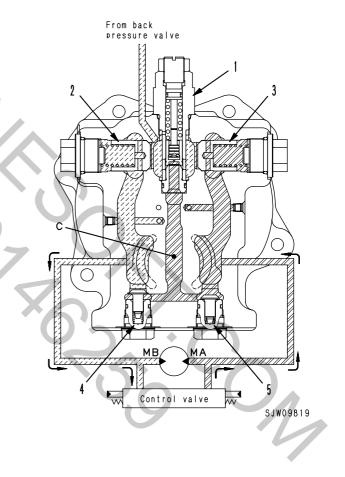
The safety valve portion consists of check valves
 (2) and (3), shuttle valves (4) and (5), and relief valve (1).

Function

- When the swing is stopped, the outlet port circuit of the motor is closed by the control valve, but the motor continues to be turned by the inertia of the swing. As a result, the pressure at the outlet port of the motor becomes abnormally high and there is danger that the motor will be damaged.
- The safety valve is installed to prevent this problem. It acts to release the abnormally high pressure oil from the outlet port (high-pressure side) of the motor and send it to the back pressure valve and prevent damage to the motor.

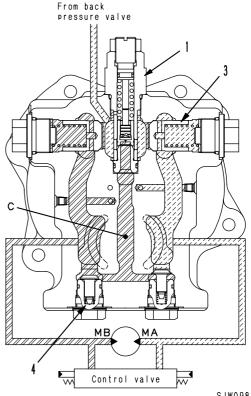
Operation

- 1. When starting swing
- If the swing control lever is operated to swing to the right, the pressurized oil from the pump passes through the control valve and is supplied to port **MA**.
- When this happens, the pressure at port **MA** rises and starting force is generated in the motor, so the motor starts to turn. The oil from the outlet port of the motor flows from port **MB** through the control valve and returns to the tank.



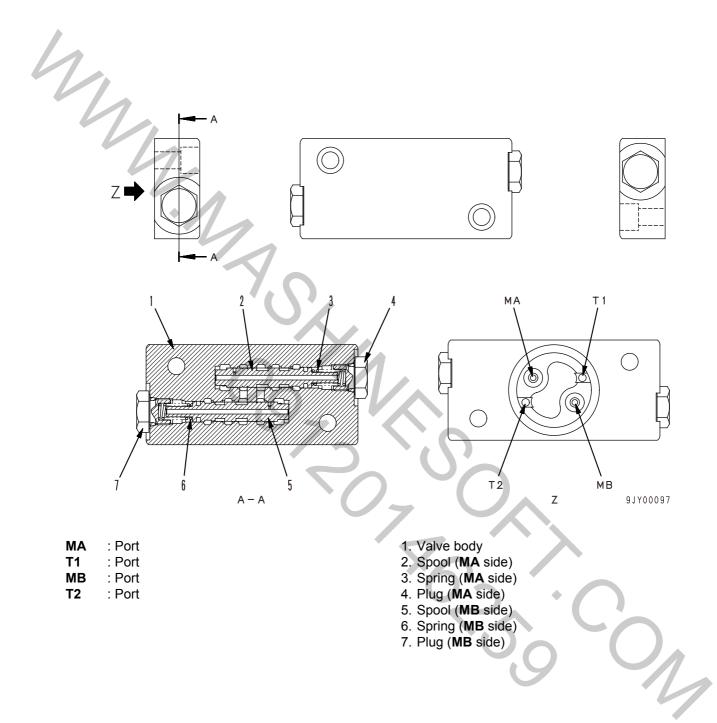
2. When stopping swing

- When the swing control lever is returned to the neutral position, no more pressurized oil is supplied from the pump to port **MA**. At the same time, the oil from the outlet port of the motor returns from the control valve to the tank, and the circuit is closed. The pressure at port **MB** rises, and rotating resistance to the motor is generated, so the brake starts to take effect.
- If the pressure at port **MB** rises higher than the pressure at port **MA**, shuttle valve (4) is pushed and chamber **C** becomes the same pressure as port **MB**. The pressure then rises to the set pressure of relief valve (1). In this way, a high brake torque is generated in the motor, and the motor stops.
- When relief valve (1) is being actuated, the relieved oil and oil from back pressure valve is supplied to port **MA** through check valve (3) to prevent cavitation at port **MA**.

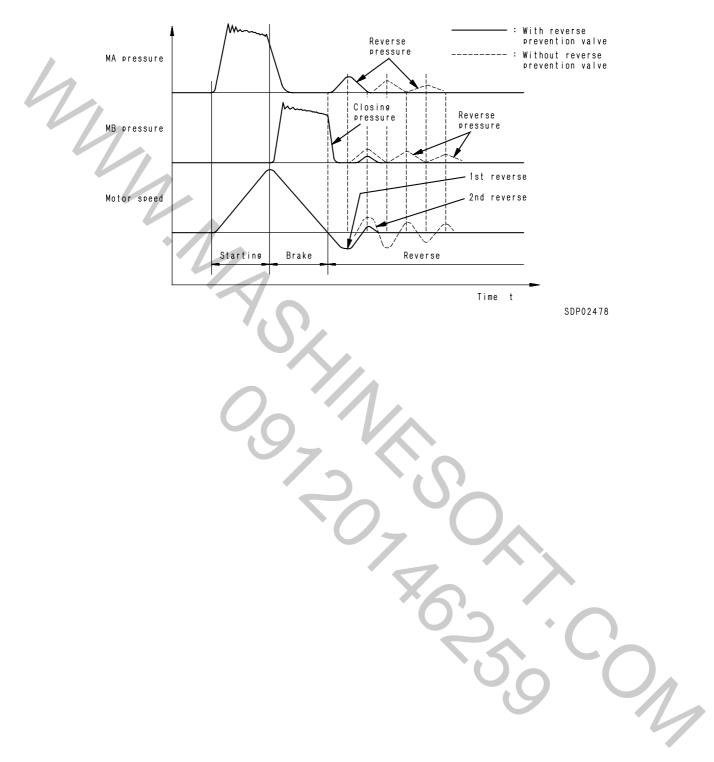


SJW09820

REVERSE PREVENTION VALVE



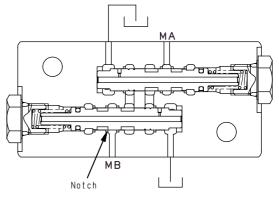
Explanation of effect



1. Function

When the swing is stopped, this valve reduces the rocking motion of the swing body due to the inertia of the swing body, backlash of the machinery system, the compressibility of the hydraulic oil, etc.

This valve is effective to prevent the cargo from being spilled when the swing is stopped as well as to shorten recycle time (excellent in the positioning accuracy and the next operation can be started quickly).



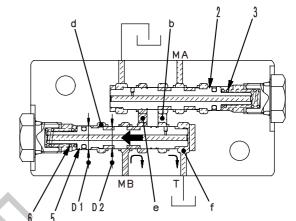
SDP02479

2. Operation

1) When the braking pressure is present at the port MB

MB pressure is introduced to chamber **d** via the notch and spool (5) makes a stroke motion to the left, pressing spring (6) due to the difference in area (**D1>D2**) and the interconnection of **MB** to **e** is established.

On this occasion, **MA** pressure is less than the set pressure of spring (3), so that spool (2) does not make a stoke motion and the pressure oil is closed by spool (2), and the braking force is secured.



SDP02036

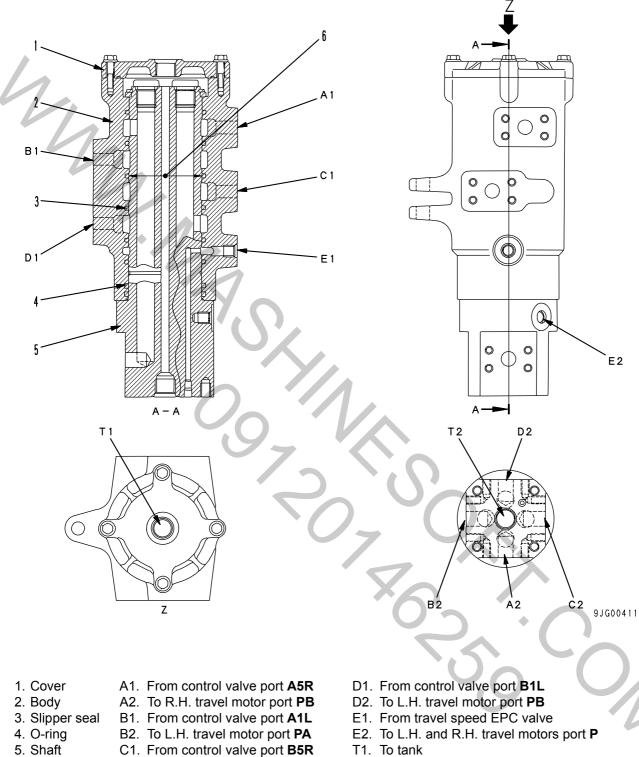
2) When the motor stopped temporarily The motor is reversed by the shutoff pressure that occurred at port MB. (First reversal)

On this occasion, the reverse pressure is generated at port **MA** side. This pressure at port **MA** is introduced to chamber **a**, and spool (2) makes a stroke motion to the right, pressing spring (3), and the interconnection of **MA** to **b** is established.

Also, the interconnection of **b** to **f** is established through the drill hole and the reverse pressure at port **MA** is bypassed to port **T**, thereby preventing the second reversal.

SDP02037

CENTER SWIVEL JOINT



T2. From L.H. and R.H. travel motors port T

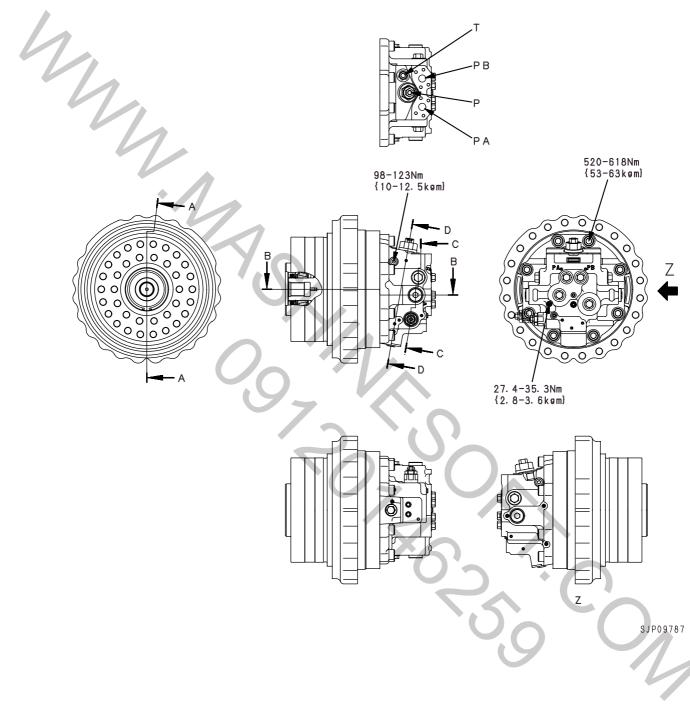
Unit: mm

No.	Check item		Remedy		
6	Clearance between rotor and shaft	Standard size	Standard clearance	Clearance limit	Replace
0		90	0.056 - 0.105	0.111	Replace

C2. To R.H. travel motor port PA

TRAVEL MOTOR

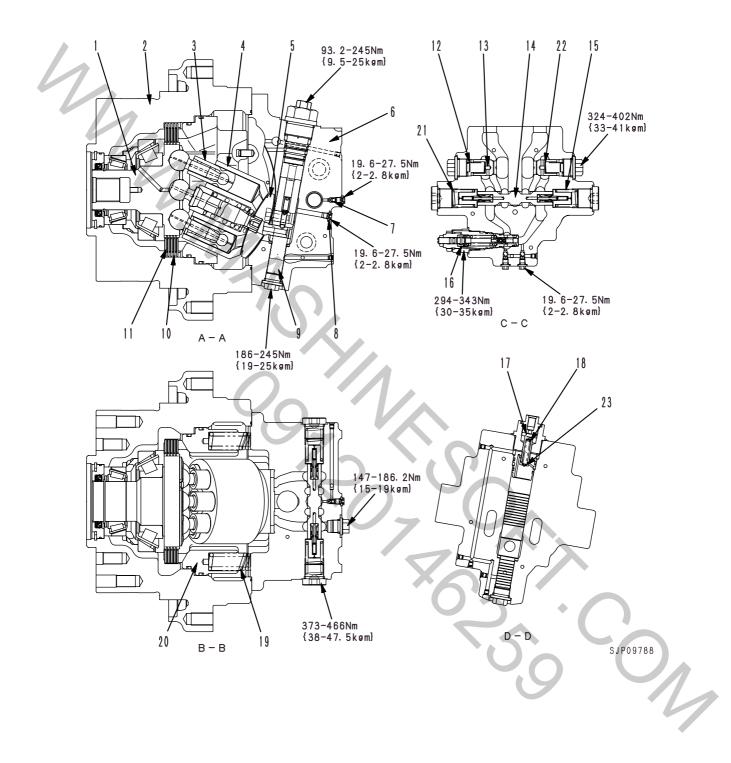
MODEL: KMV335ADT



- P :From travel speed solenoid valve
- T :To tank
- PA :From control valve
- **PB** :From control valve

Specifications

Model: KMV335ADT Theoretical delivery: Minimum 217 cc/rev Maximum 336 cc/rev Brake release pressure: 1.27 ± 0.39 MPa { 13.0 ± 4.0 kg/cm²} Travel speed selector pressure: 0.93 ± 0.25 MPa { 9.50 ± 2.50 kg/cm²}



- 1. Output shaft
- 2. Motor case
- 3. Piston
- 4. Cylinder block
- 5. Valve plate
- 6. End cover
- 7. Slow return valve

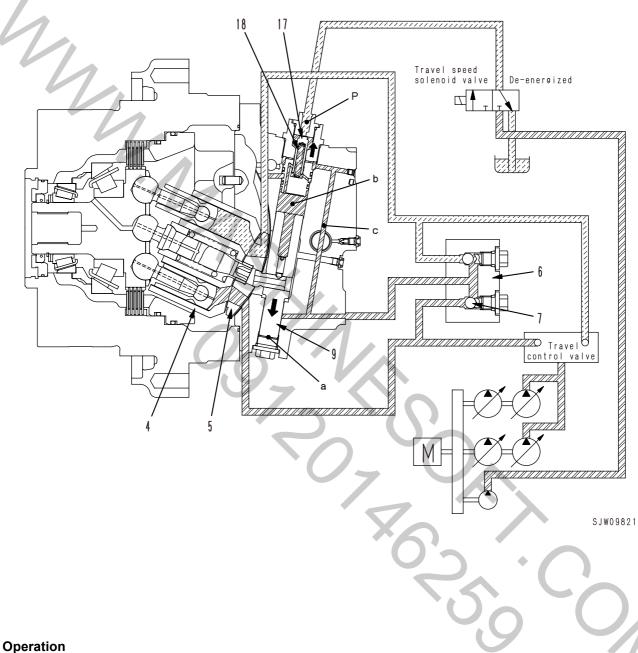
- 8. Plug
- 9. Regulator piston
- 10. Plate
- 11. Disc
- 12. Check valve spring
- 13. Check valve
- 14. Counterbalance valve
- 15. Spool return spring
- 16. Safety valve
- 17. Regulator valve
- 18. Spring
- 19. Brake spring
- 20. Brake piston

han y

Unit: mm

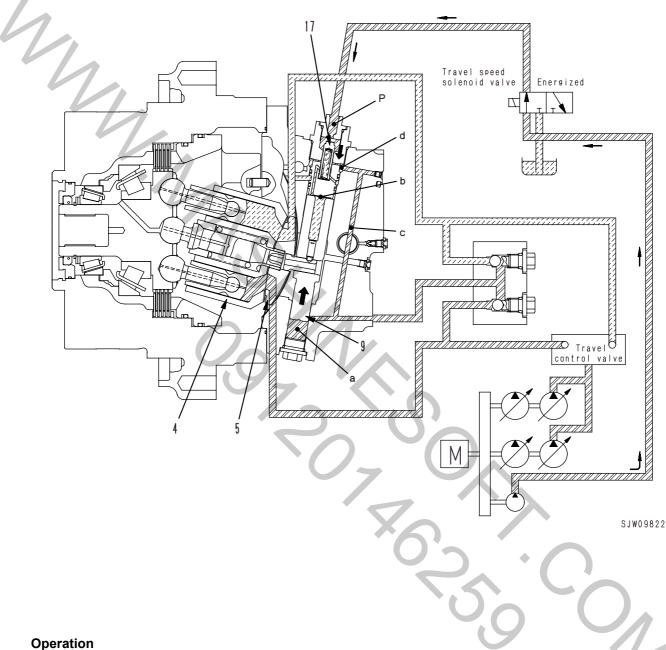
No.	Check item			Criteria	9		Remedy
	Spool return spring	Standard size			Repair limit		
21		Free length x OD	Installed length	Installed load	Free length	Installed load	~
		62.5 x 32	42.0	427 N {43.5 kg}	—	341 N {34.8 kg}	Replace spring if damaged or
22	Check valve spring	62.5 x 20.0	39.0	3.04 N {0.31 kg}	_	2.45 N {0.25 kg}	deformed
23	Regulator piston spring	55.0 x 9.0	50.0	98.1 N {10.0 kg}	_	78.5 N {8.0 kg}	

1. At low speed (motor swash plate angle at maximum)



- When the solenoid valve is de-energized, the pilot pressure oil from the control pump does not flow to port P. For this reason, regulator valve (17) is pushed upward in the direction of the arrow by spring (18).
- The main pressure oil from the control valve pushes shuttle valve (7), goes through end cover (6), and acts on chamber a of regulator piston (9). At the same time, the main pressure passes through passage c and acts on chamber b through regulator valve (17).
- Because of this, propulsion force equal to the difference in area of chambers a and b (Ab Aa) of regulator piston (9) acts in a downward direction.
- As a result, valve plate (5) and cylinder block (4) move in the maximum swash plate angle direction, the motor capacity becomes the maximum, and the system is set to low speed.

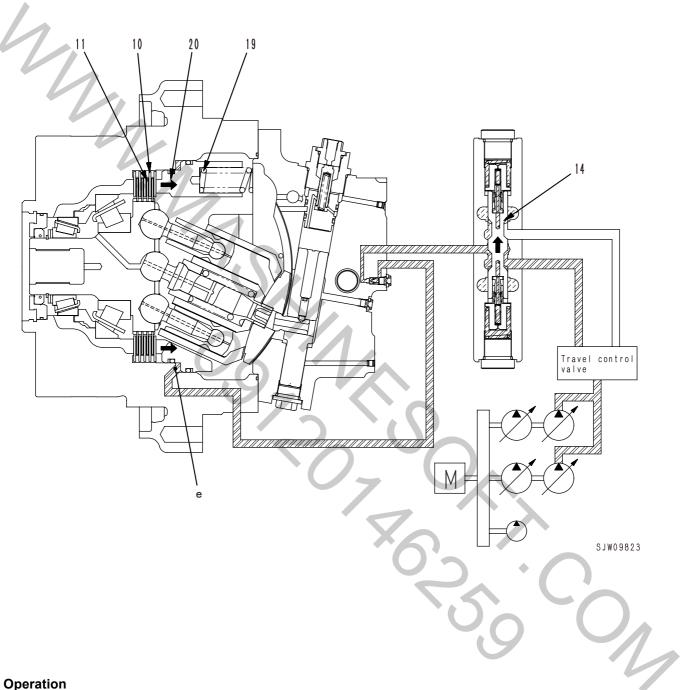
2. At high speed (motor swash plate angle at minimum)



- When the solenoid valve is energized, the pilot pressure oil from the control pump flows to port P, and pushes regulator valve (17) down.
- Because of this, the main pressure oil and the oil in chamber **d** is shut off by regulator valve (17), and the oil in chamber **b** is drained inside the case.
- A propulsion force generated by the pressure oil in chamber a of regulator piston (9) then acts upward.
- As a result, valve plate (5) and cylinder block (4) move in the minimum swash plate angle direction, the motor capacity becomes the minimum, and the system is set to high speed.

PARKING BRAKE

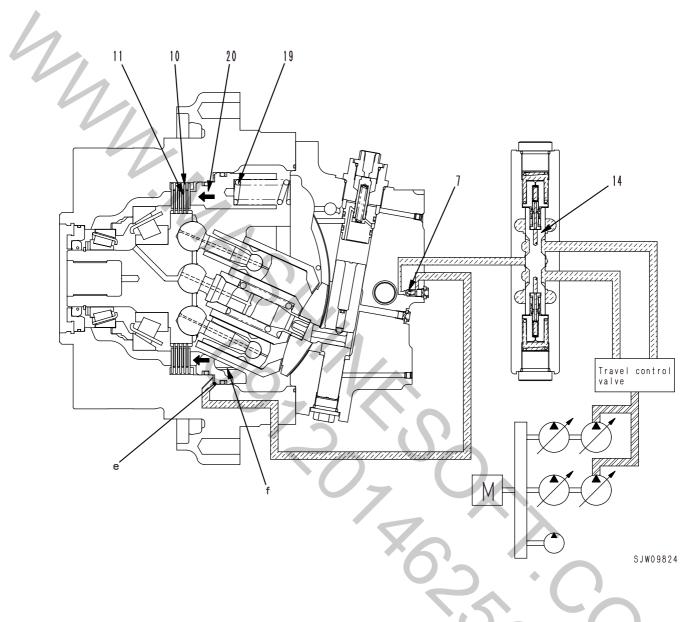
1. When starting to travel



Operation

- When the travel lever is operated, the pressurized oil from the pump actuates counterbalance valve spool (14), opens the circuit to the parking brake, and flows into chamber e of brake piston (20). It overcomes the force of spring (19), and pushes piston (20) to the right.
- When this happens, the force pushing plate (10) • and disc (11) together is lost, so plate (10) and disc (11) separate and the brake is released.

2. When stopping travel



Operation

- When the travel lever is placed in neutral, counterbalance valve spool (14) returns to the neutral position and the circuit to the parking brake is closed.
- The pressurized oil in chamber **e** of brake piston (20) passes through the throttle of slow return valve (7) until spool (14) of the counterbalance valve returns to neutral.
- When spool (14) of the counterbalance valve returns to the neutral position, the oil is drained inside the case from the throttle **f** of brake piston (20) and brake piston (20) is pushed fully to the left by spring (19).
- As a result, plate (10) and disc (11) are pushed together, and the brake is applied.
- A time delay is provided by having the pressurized oil pass through a throttle in slow return valve (7) when the brake piston returns, and this ensures that the brake is applied after the machine stops.

BRAKE VALVE

Operation of brake valve

- The brake valve consists of a check valve, counterbalance valve, and safety valve in a circuit as shown in the diagram on the right.
 - The function and operation of each component is as given below.

1. Counterbalance valve, check valve Function

When traveling downhill, the weight of the machine makes it try to travel faster than the speed of the motor.

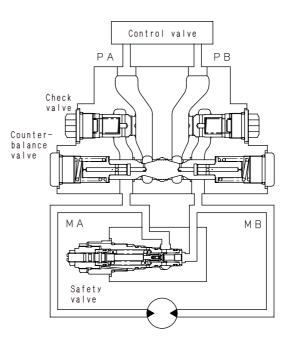
As a result, if the machine travels with the engine at low speed, the motor will rotate without load and the machine will run away, which is extremely dangerous.

To prevent this, these valves act to make the machine travel according to the engine speed (pump discharge amount).

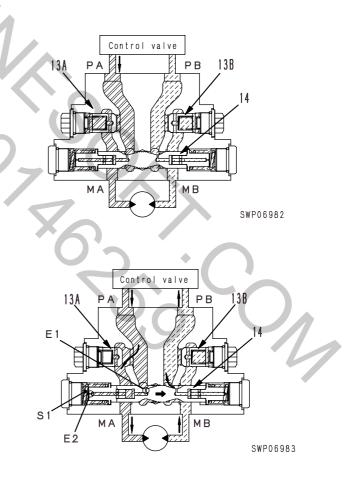
Operation when pressurized oil is supplied

- When the travel lever is operated, the pressurized oil from the control valve is supplied to port PA. It pushes open check valve (13A) and flows from motor inlet port MA to motor outlet port MB. However, the motor outlet port is closed by check valve (13B) and spool (14), so the pressure at the supply side rises.
- The pressurized oil at the supply side flows from orifice E1 in spool (14) and orifice E2 in the piston to chamber S1. When the pressure in chamber S1 goes above the spool switching pressure, spool (14) is pushed to the right.

As a result, port **MB** and port **PB** are connected, the outlet port side of the motor is opened, and the motor starts to rotate.



SWP06981



Operation of brake when traveling downhill

 If the machine tries to run away when traveling downhill, the motor will turn under no load, so the pressure at the motor inlet port will drop, and the pressure in chamber S1 through orifices E1 and E2 will also drop.

When the pressure in chamber **S1** drops below the spool switching pressure, spool (14) is returned to the left by spring (15), and outlet port **MB** is throttled.

As a result, the pressure at the outlet port side rises, resistance is generated to the rotation of the motor, and this prevents the machine from running away.

In other words, the spool moves to a position where the pressure at outlet port **MB** balances the pressure at the inlet port and the force generated by the weight of the machine. It throttles the outlet port circuit and controls the travel speed according to the amount of oil discharged from the pump.

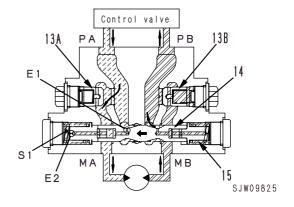
2. Safety valve (2-direction operation, 2-stage set safety valve)

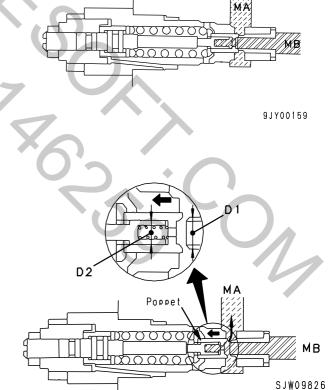
Function

 When travel is stopped (or when traveling downhill), the circuits at the inlet and outlet ports of the motor are closed by the counterbalance valve. However, the motor is rotated by inertia, so the pressure at the outlet port of the motor will become abnormally high and will damage the motor or piping. The safety valve acts to release this abnormal pressure and send it to the inlet port side of the motor to prevent damage to the equipment.

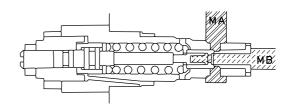
Operation in both directions

- 1) When pressure in chamber MB has become high (when rotating clockwise)
- When the travel is stopped (or when traveling downhill), chamber **MB** in the outlet port circuit is closed by the check valve of the counterbalance valve, but the pressure at the outlet port rises because of inertia.
- If the pressure goes above the set pressure, the force produced by the difference in area between D1 and D2 [π/4(D1² D2²) x pressure] overcomes the force of the spring and moves the poppet to the left, so the oil flows to chamber MA in the circuit on the opposite side.



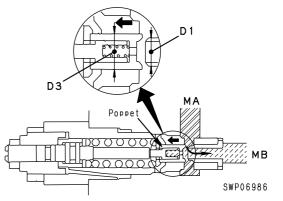


- 2) When pressure in chamber MA has become high (when rotating counterclockwise)
- When the travel is stopped (or when traveling downhill), chamber **MA** in the outlet port circuit is closed by the check valve of the counterbalance valve, but the pressure at the outlet port rises because of inertia.



9JY00161

If the pressure goes above the set pressure, the force produced by the difference in area between **D1** and **D3** $[\pi/4(D3^2 - D1^2) \times pressure]$ overcomes the force of the spring and moves the poppet to the left, so the oil flows to chamber **MB** in the circuit on the opposite side.



SET PRESSURES VARYING MECHANISM

1. When starting travel (high-pressure setting)

When the travel lever is operated, the pressurized oil from the pump actuates counterbalance valve spool (14), and opens the pilot circuit to the safety valve. The oil passes from chamber G to passage H and flows into chamber J, pushes the piston to the right, and compresses the spring to make the set load larger.

Because of this, the set pressure of the safety valve is switched to the high pressure setting, and a large drawbar pull is made available.

2. When stopping travel (low-pressure setting)

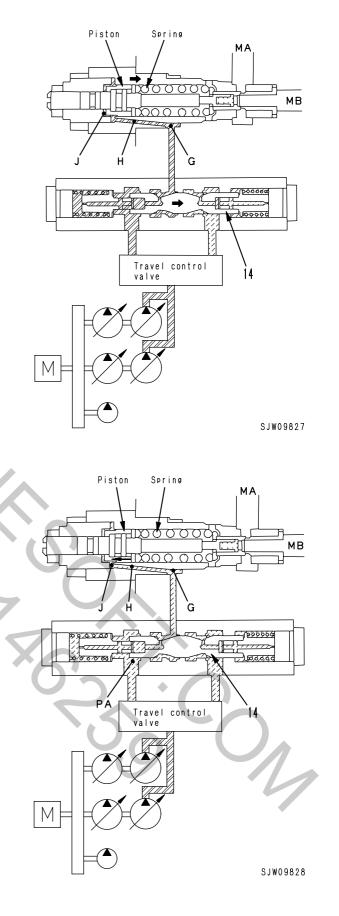
V.M.

- When the travel lever is placed at neutral, the pressure in chamber PA drops and counterbalance valve spool (14) returns to the neutral position.
- While the counterbalance valve spool is returning to the neutral position, the pressurized oil in chamber J passes through passage H, and escapes to chamber PA from chamber G. The piston moves to the left, and the set load becomes smaller.
- Because of this, the set pressure of the safety valve is switched to the low-pressure setting and relieves the shock when reducing speed.

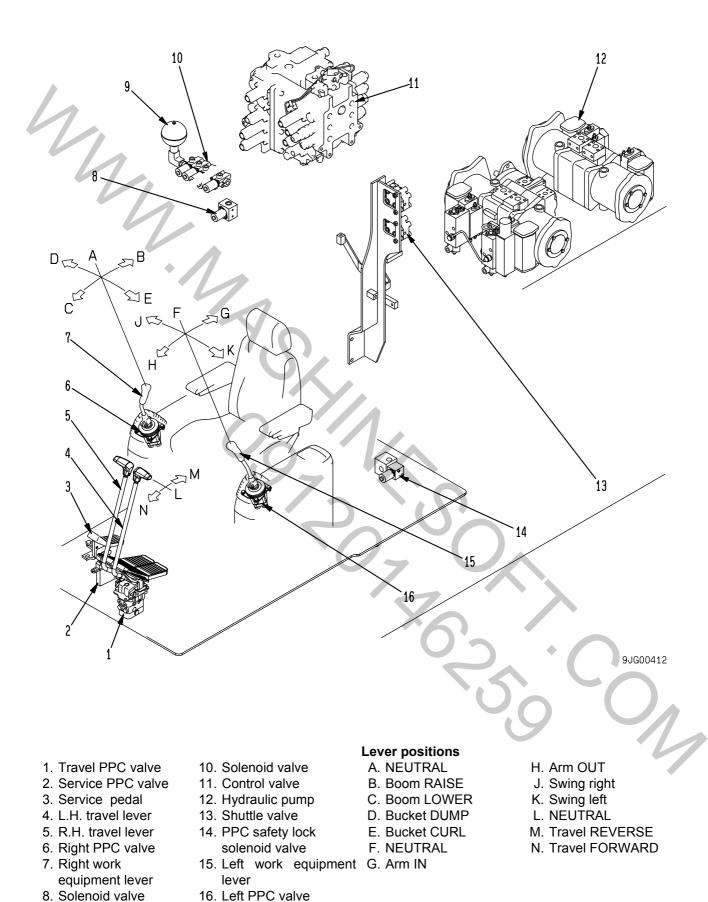
Set pressure of safety valve

High-pressure setting : 37.8 MPa{385 kg/cm²} (at starting and traveling)

Low-pressure setting : 27.5 MPa{280 kg/cm²} (at stopping)



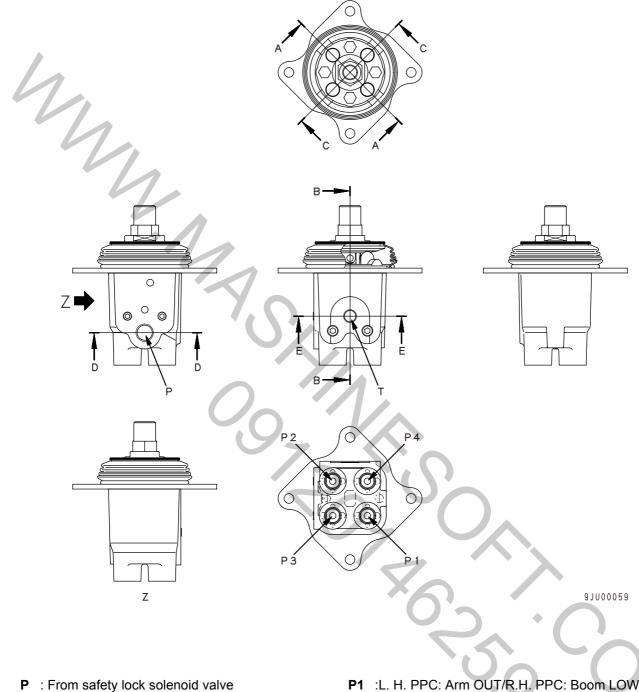
VALVE CONTROL



9. Accumulator

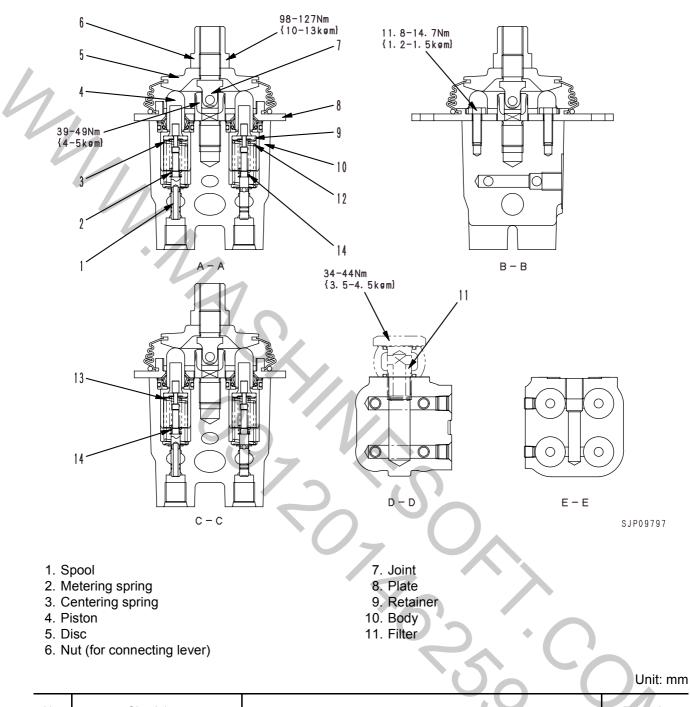
MMM MASHINGOTATION

WORK EQUIPMENT, SWING PPC VALVE



T : To tank

- P1 :L. H. PPC: Arm OUT/R.H. PPC: Boom LOWER
- P2 :L. H. PPC: Arm IN/R.H. PPC: Boom RAISE
- P3 :L. H. PPC: Right swing/R.H. PPC: Bucket CURL
- P4 :L. H. PPC: Left swing/R.H. PPC: Bucket DUMP

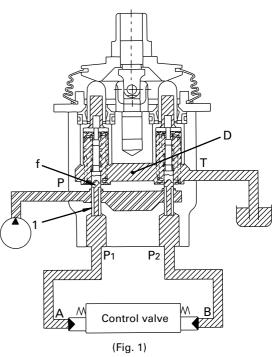


No.	Check item		Remedy				
	Centering spring (for P3, P4)	Standard size			Repair limit		
12		Free length x OD	Installed length	Installed load	Free length	Installed load	
		38.7 x 15.5	34	9.81 N {1.0 kg}	_	7.85 N {0.8 kg}	Replace spring if damaged or
13	Centering spring (for P1, P2)	42.5 x 15.5	34	17.7 N {1.8 kg}	_	14.1 N {1.44 kg}	deformed
14	Metering spring	26.5 x 8.2	24.9	16.7 N {1.7 kg}	_	13.3 N {1.36 kg}	

Operation

1. At neutral

Ports A and B of the control valve and ports P1 and P2 of the PPC valve are connected to drain chamber D through fine control hole f in spool (1). (Fig. 1)



SBP00275

2. Fine control (neutral \rightarrow fine control)

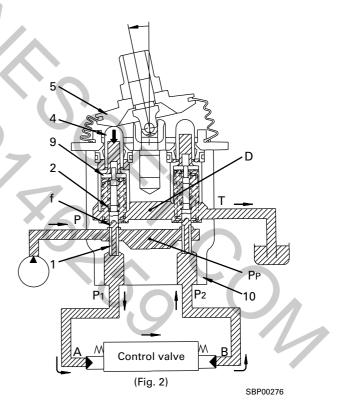
When piston (4) starts to be pushed by disc (5), retainer (9) is pushed. Spool (1) is also pushed by metering spring (2) and moves down. When this happens, fine control hole **f** is shut off from drain chamber **D**. At almost the same time, it is connected to pump pressure chamber **PP**, and the pilot pressure of the control pump is sent from port **A** through fine control hole **f** to port **P1**.

When the pressure at port **P1** rises, spool (1) is pushed back. Fine control hole **f** is shut off from pump pressure chamber **PP**. At almost the same time, it is connected to drain chamber **D**, so the pressure at port **P1** escapes. As a result, spool (1) moves up and down until the force of metering spool (2) is balanced with the pressure of port **P1**.

The relationship of the positions of spool (1) and body (10) (fine control hole **f** is in the middle between drain hole **D** and pump pressure chamber **PP**) does not change until retainer (9) contacts spool (1).

Therefore, metering spring (2) is compressed in proportion to the travel of the control lever, so the pressure at port **P1** also rises in proportion to the travel of the control lever.

In this way, the spool of the control valve moves to a position where the pressure of chamber A(same as pressure at port P1) and the force of the return spring of the control valve spool are balanced. (Fig. 2)



WORK EQUIPMENT, SWING PPC VALVE

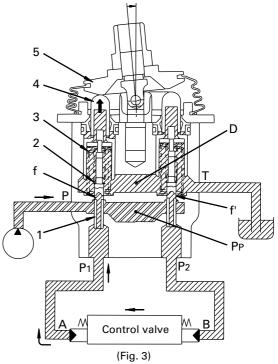
3. Fine control (control lever returned)

When disc (5) starts to be returned, spool (1) is pushed up by the force of centering spring (3) and the pressure at port P1.

Because of this, fine control hole f is connected to drain chamber D, and the pressurized oil at port P1 is released.

If the pressure at port P1 drops too much, spool (1) is pushed down by metering spring (2), so fine control hole f is shut off from drain chamber **D**. At almost the same time, it is connected to pump pressure chamber PP, so the pressure at port P1 supplies the pump pressure until the pressure recovers to a pressure equivalent to the position of the lever.

When the control valve returns, oil in drain chamber D flows in from fine control hole f' of the valve on the side that is not moving. It passes through port P2 and goes to chamber B to charge the oil. (Fig. 3)



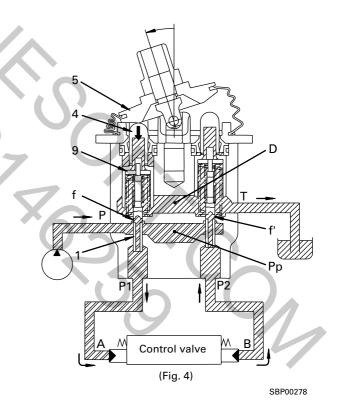
SBP00277

4. At full stroke

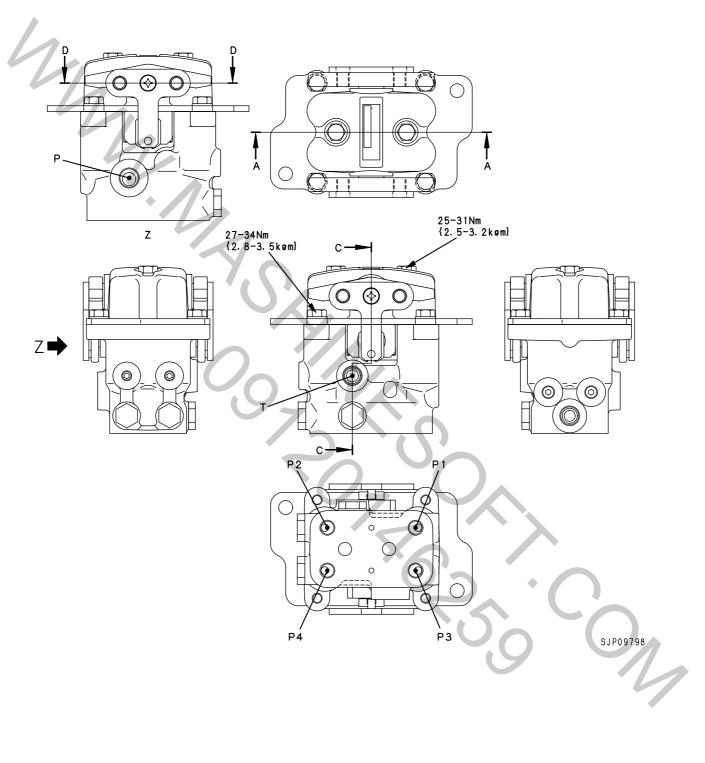
Disc (5) pushes down piston (4), and retainer (9) pushes down spool (1). Fine control hole f is shut off from drain chamber D, and is connected to pump pressure chamber PP.

Therefore, the pilot pressure oil from the control pump passes through fine control hole f and flows to chamber A from port P1 to push the control valve spool.

The return oil from chamber B passes from port P2 through fine control hole f' and flows to drain chamber D. (Fig. 4)



TRAVEL PPC VALVE

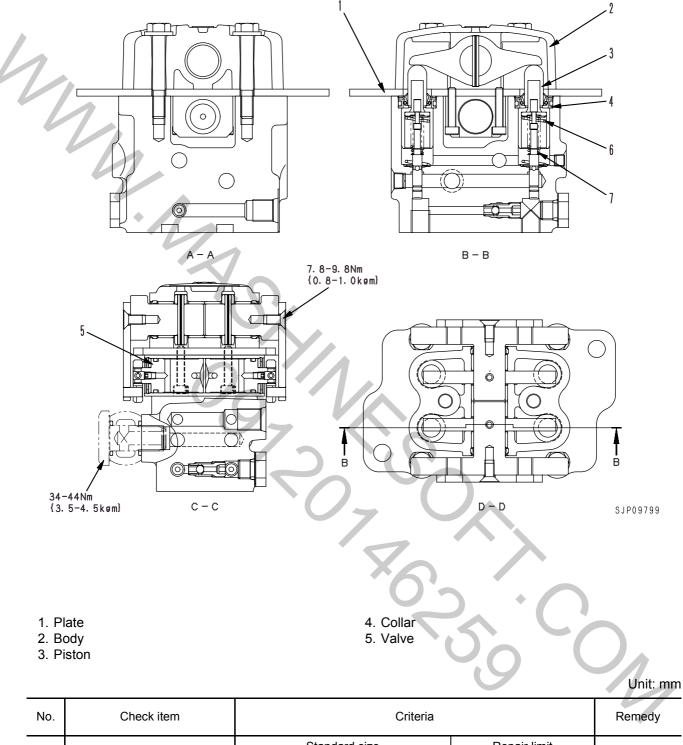


P : From main pump

T : To tank

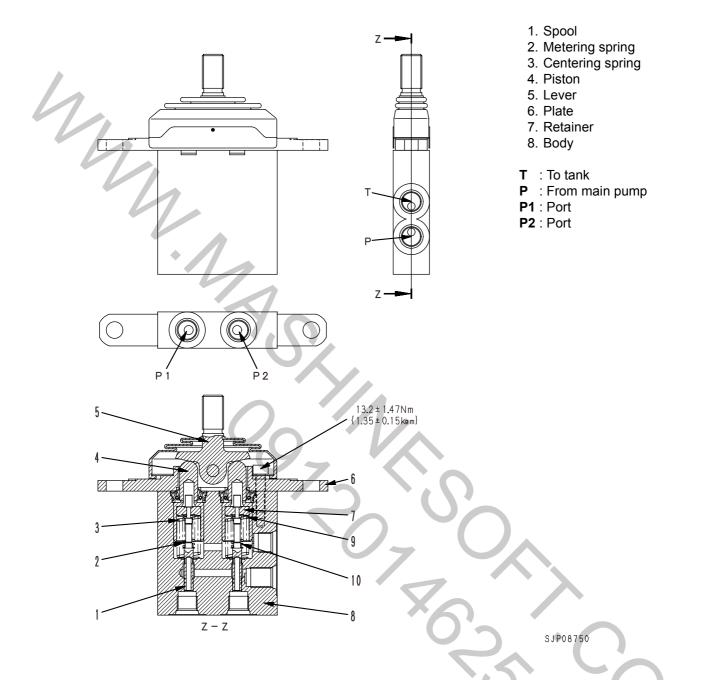
P1 : L.H. travel REVERSE
P2 : L.H. travel FORWARD
P3 : R.H. travel REVERSE
P4 : R.H. travel FORWARD

★ The travel PPC valve operates similarly to the work equipment and swing PPC valves.



6	Centering spring	Standard size			Repair limit		
		Free length x OD	Installed length	Installed load	Free length	Installed load	Replace spring if damaged or deformed
		48.6 x 15.5	32.5	108 N {11 kg}		86.3 N {8.8 kg}	
7	Metering spring	26.5 x 8.15	24.9	16.7 N {1.7 kg}	_	13.7 N {1.4 kg}	

SERVICE PPC VALVE

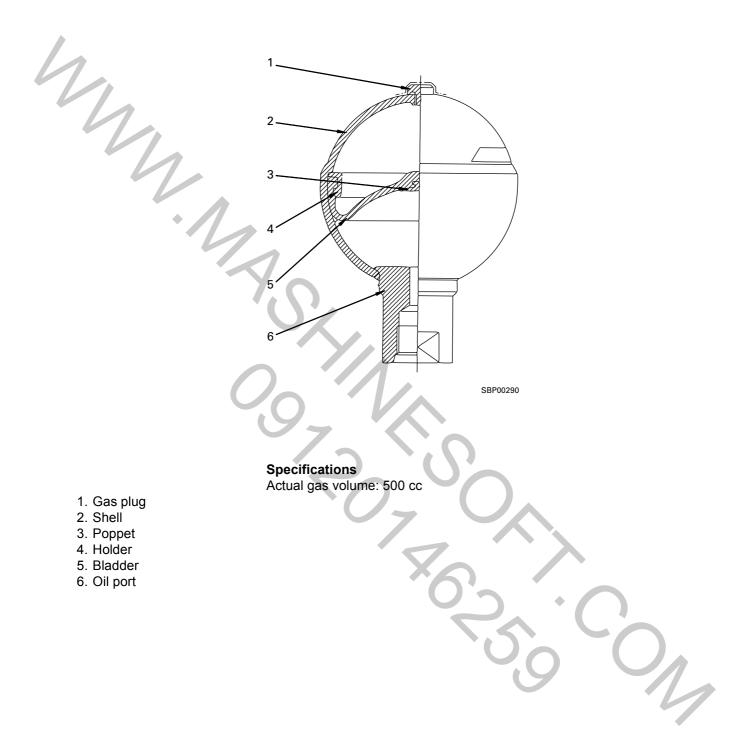


★ The service PPC valve operates similarly to the work equipment and swing PPC valves.

Unit: mm

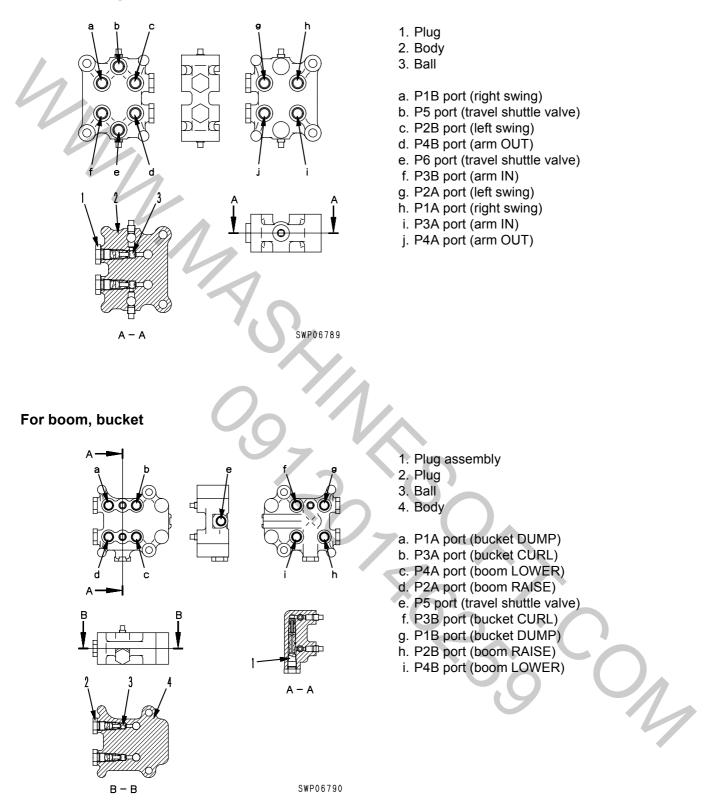
No.	Check item		Remedy				
	Centering spring	Standard size			Repair limit		
9		Free length x Outside Diameter	Installed length	Installed load	Free length	Installed load	Replace spring if
		33.9 x 15.3	28.4	124.5 N {12.7 kg}	—	100 N {10.2 kg}	damaged or deformed
10	Metering spring	22.7 x 8.1	22	16.7 N {1.7 kg}	—	13.7 N {1.4 kg}	

PPC ACCUMULATOR



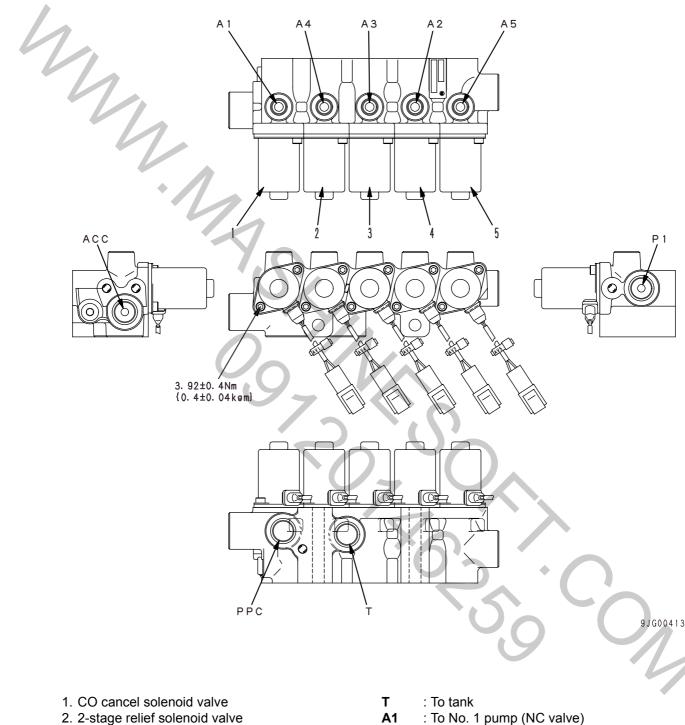
PPC SHUTTLE VALVE

For arm, swing



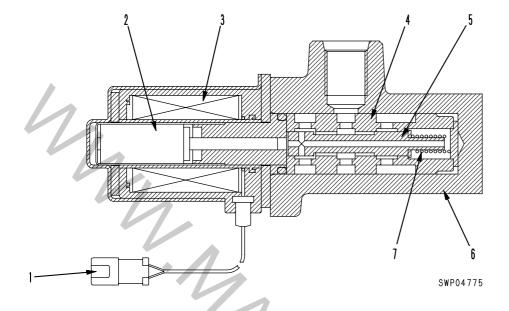
SOLENOID VALVE

FOR CO CANCEL, 2-STAGE RELIEF, BOOM HI 2-STAGE SAFETY VALVE, TRAVEL SPEED, SWING BRAKE SOLENOID VALVE



- 3. Boom Hi 2-stage safety valve solenoid valve
- 4. Travel speed solenoid valve
- 5. Swing brake solenoid valve

- : To No. 1 pump (NC valve)
- : To left and right travel motors A2
- : To boom LOWER 2-stage safety valve A3
- **A4** : To main valve (relief valve)
- A5 : To swing motor
- : From control pump P1
- ACC : To accumulator
- PPC : To PPC valve



- 1. Connector
- 2. Movable core
- 3. Coil
- 4. Cage
- 5. Spool
- 6. Block
- 7. Spring

Operation

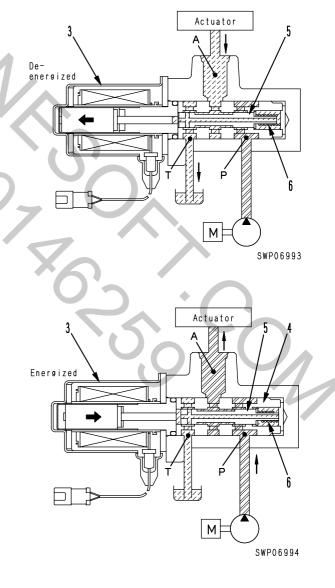
When solenoid is de-energized

 When the signal current does not flow from the PPC lock switch or swing lock switch, solenoid (3) is de-energized.

For this reason, spool (5) is pushed fully to the left by spring (6).

As a result, the circuit between ports **P** and **A** closes and the pressurized oil from the control pump does not flow to the actuator.

At the same time, the pressurized oil from the actuator flows from port \mathbf{A} to port \mathbf{T} , and is then drained to the tank.



When solenoid is energized

When the signal current flows from the PPC lock switch or swing lock switch to solenoid (3), solenoid (3) is energized.

For this reason, spool (5) is pushed to the right in the direction of the arrow.

As a result, the pressurized oil from the control pump flows from port **P** through the inside of spool (5) to port **A**, and then flows to the actuator. At the same time, port **T** is closed, and this stops the oil from flowing to the tank.

PC600, 600LC-7

Control valve

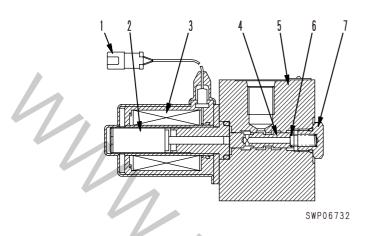
1

PPC valv

Control valve

PPC valve SJW09829

BUCKET CURL HI CANCEL

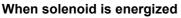


- 1. Connector
- 2. Movable iron core
- 3. Coil
- 4. Spool
- 5. Body
- 6. Spring
- 7. Plug

Operation

When solenoid is de-energized

The signal current does not flow from the controller, so coil (3) is de-energized.
 For this reason, spool (4) is returned to the neutral position by spring (6).
 As a result, the circuit between ports P and A is connected, and the pressurized oil from the PPC valve flows to the control valve.



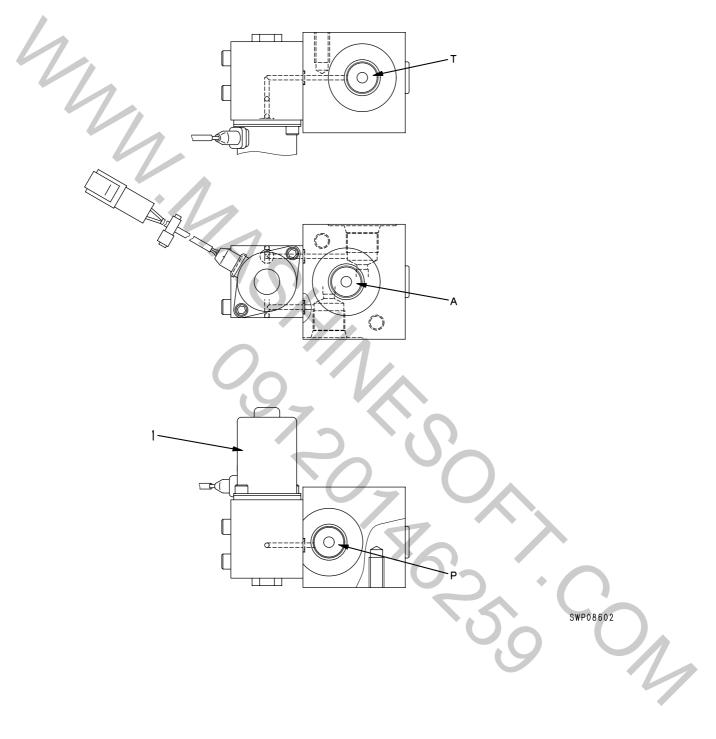
- When the signal current flows from the controller to coil (3), coil (3) is energized and movable iron core (2) is pushed to the right in the direction of the arrow.
- For this reason, spool (4) is also pushed to the right in the direction of the arrow.
 As a result, port P is closed, and the pressure oil from the control pump does not flow to the con-

trol valve. At the same time, port **A** and port **T** are intercon-

nected, and the oil from the control valve is drained to the tank.

SJW09830

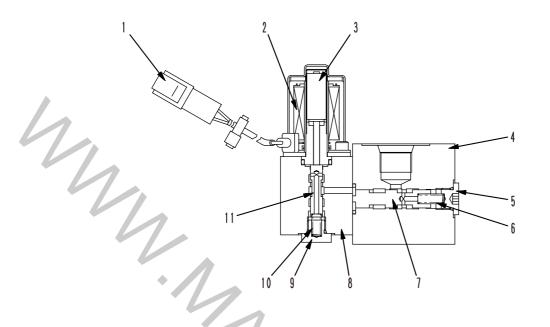
For safety lock (under cab)



1. Safety lock solenoid valve

- T: To tank
- A : To port P of work equipment PPC valve To port P of travel PPC valve
- **P** : From control pump

9JG00079



1. Connector

- 2. Solenoid
- 3. Variable iron core
- 4. Body
- 5. Plug
- 6. Spring

Operation

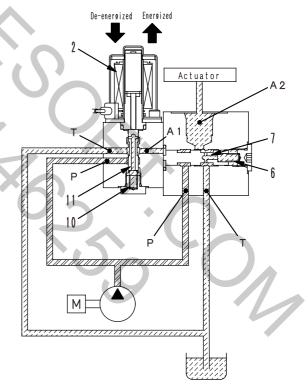
When solenoid is de-energized

- No signal current flows from the PPC hydraulic lock switch, so solenoid (2) is de-energized.
- Accordingly, spool (11) is pushed up and spool (7) is pushed to the left by spring (6).
- As a result, port P is closed, so pressure oil from the control pump does not flow to the actuator. At the same time, the oil from the actuator flows from port A2 to port T and is drained to the tank.

When solenoid is energized

- When the signal current flows from the PPC hydraulic lock switch to solenoid (2), solenoid (2) is energized.
- Accordingly, spool (11) is pushed down and the pressure oil from the control pump flows through port P to port A1 and spool (7) is pushed to the right.
- As a result, pressure oil from the control pump flows from port **P** to port **A2**, and then flows to the actuator.

At the same time, port **T** is closed, so the oil does not flow to the tank.

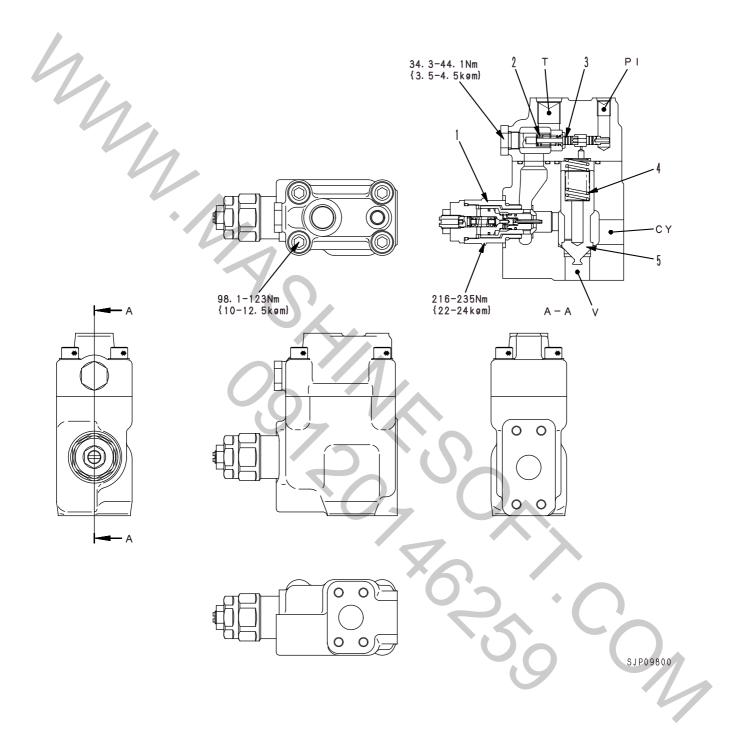


SJP09436

7. Spool

- 8. Body
- 9. Plug
- 10. Spring
- 11. Spool

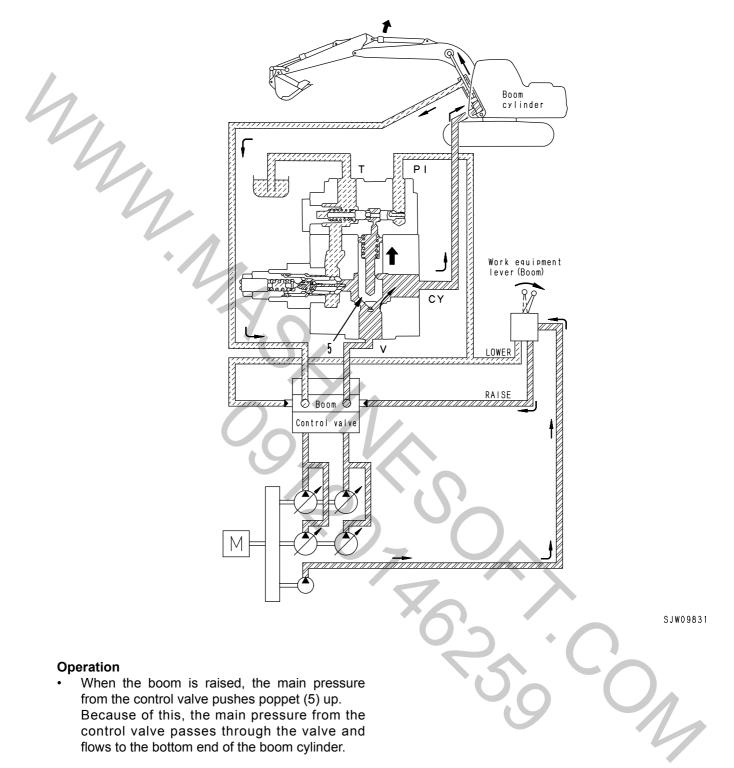
BOOM HOLDING VALVE



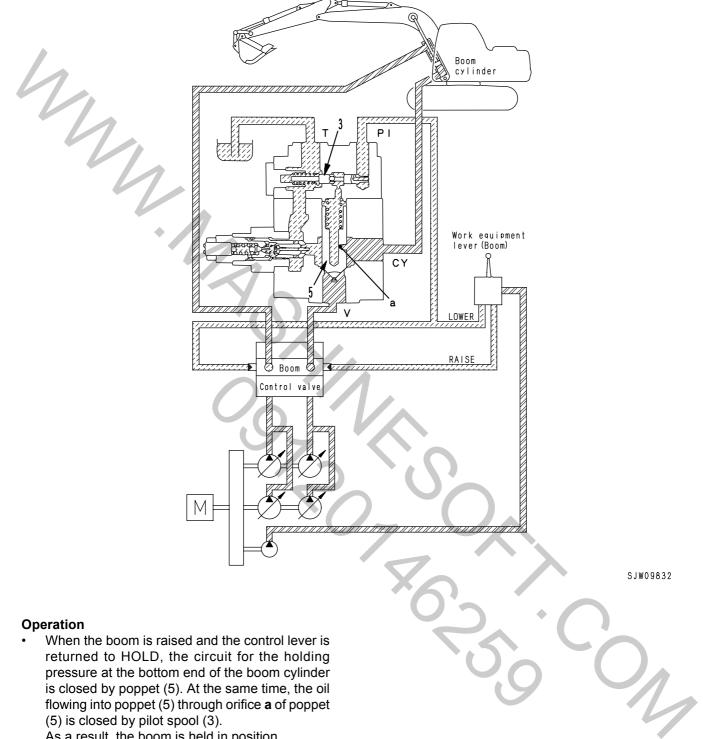
- 1. Safety-suction valve
- 2. Pilot spring
- 3. Pilot spool
- 4. Poppet spring
- 5. Poppet

- T : To tank
- V : From control valve
- **CY** : To boom cylinder bottom
- **PI** : From PPC valve (pilot pressure)

1. At boom RAISE



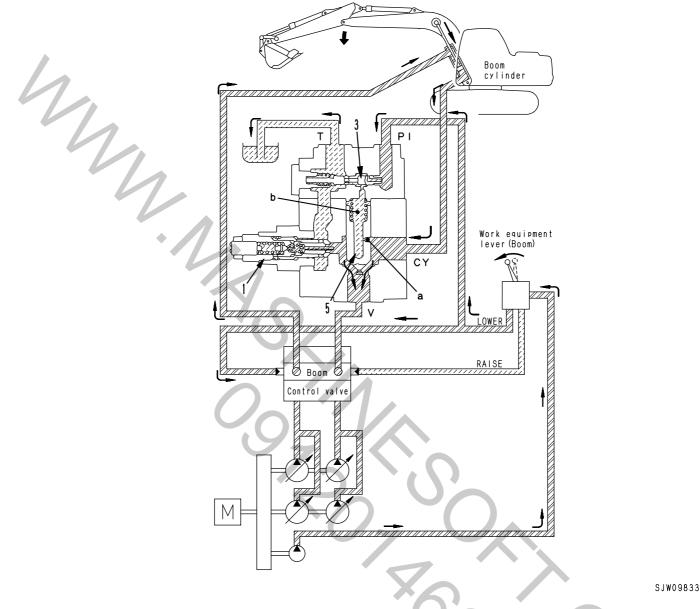
2. Boom lever at HOLD



pressure at the bottom end of the boom cylinder is closed by poppet (5). At the same time, the oil flowing into poppet (5) through orifice a of poppet (5) is closed by pilot spool (3).

As a result, the boom is held in position.

3. At boom LOWER



Operation

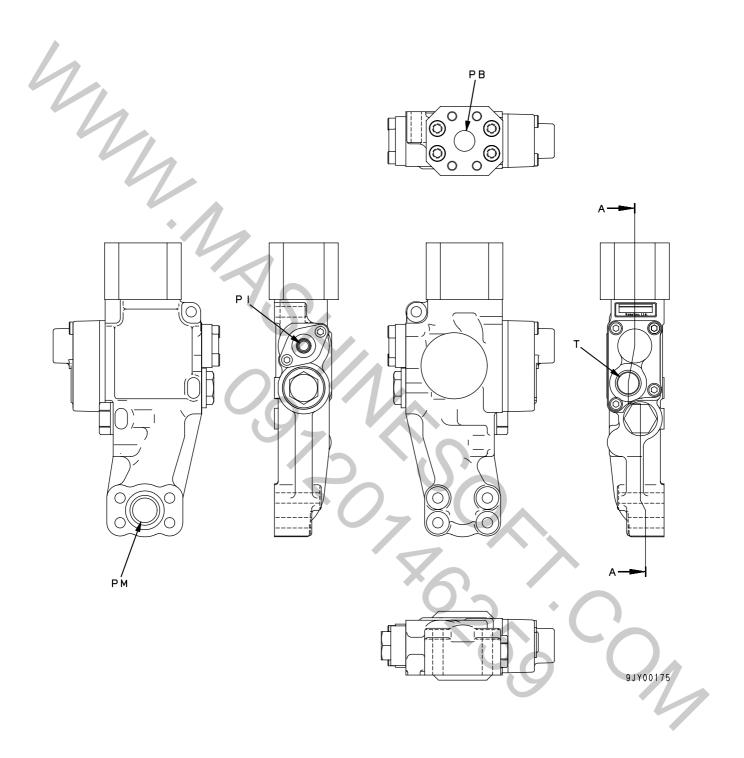
 When the boom is lowered, the pilot pressure flows to port **PI** from the PPC valve pushes pilot spool (3) and the pressurized oil in chamber **b** inside the poppet is drained.

When the pressure at port **CY** rises because of the pressurized oil from the bottom end of the boom cylinder, the pressure of the pressurized oil in chamber **b** is lowered by orifice **a**.

If the pressure in chamber **b** drops below the pressure at port **CY**, poppet (5) opens, the pressurized oil flows from port **CY** to port **V**, and then flows to the control valve.

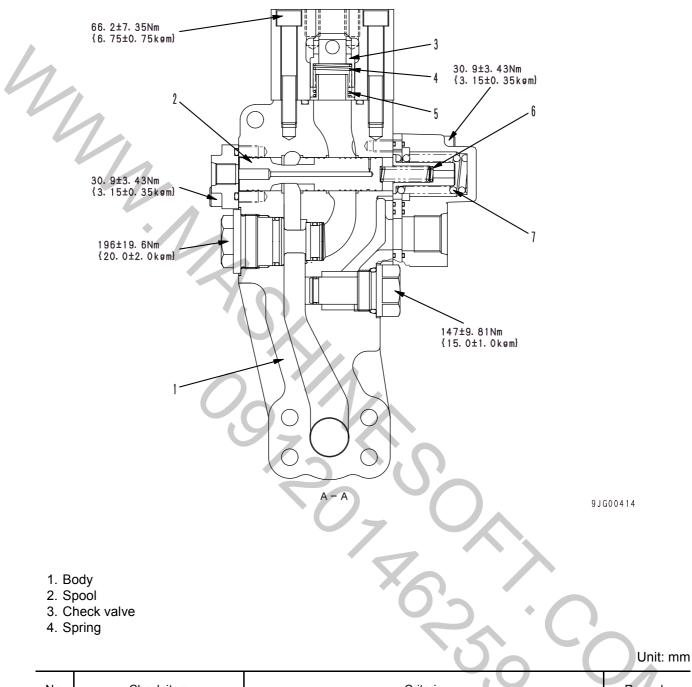
If any abnormal pressure is generated in the circuit at the bottom end of the boom cylinder, safety valve (1) is actuated and drain oil from port **CY** to port **T**. M

BOOM LOWER REGENERATION VALVE



T : To tank

- **PB** : From boom cylinder bottom
- **PM** : From boom cylinder head
- **PI** : From boom LOWER PPC valve



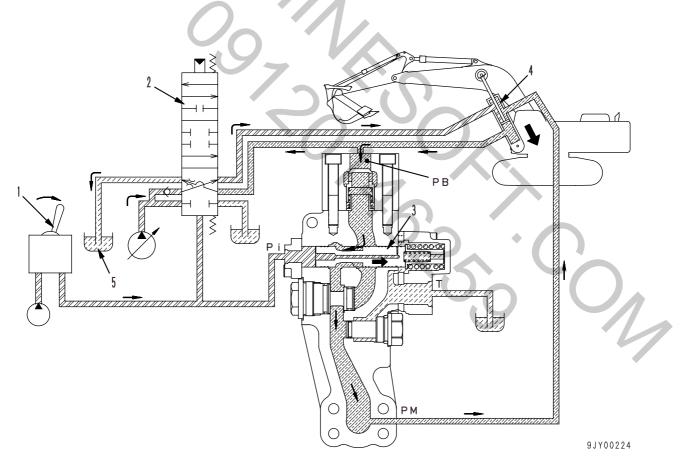
No.	Check item			Criteria	0		Remedy
			Standard size	;	Repa	ir limit	
5	Spring (check valve)	Free length x OD	Installed length	Installed load	Free length	Installed load	
		83.5 x 25.5	22	29.4 N {3.0 kg}	_	23.5 N {2.4 kg}	Replace spring if damaged or
6	Spool return spring (small)	41.1 x 9.6	35	58.8 N {6.0 kg}	_	47.1 N {4.8 kg}	deformed
7	Spool return spring (large)	49.4 x 25.7	47	207 N {21.1 kg}		166 N {16.9 kg}	

Function

 When the boom is lowered, some of the oil drained from the bottom end of the boom cylinder is circulated to the cylinder head to increase the lowering speed of the boom.

Operation

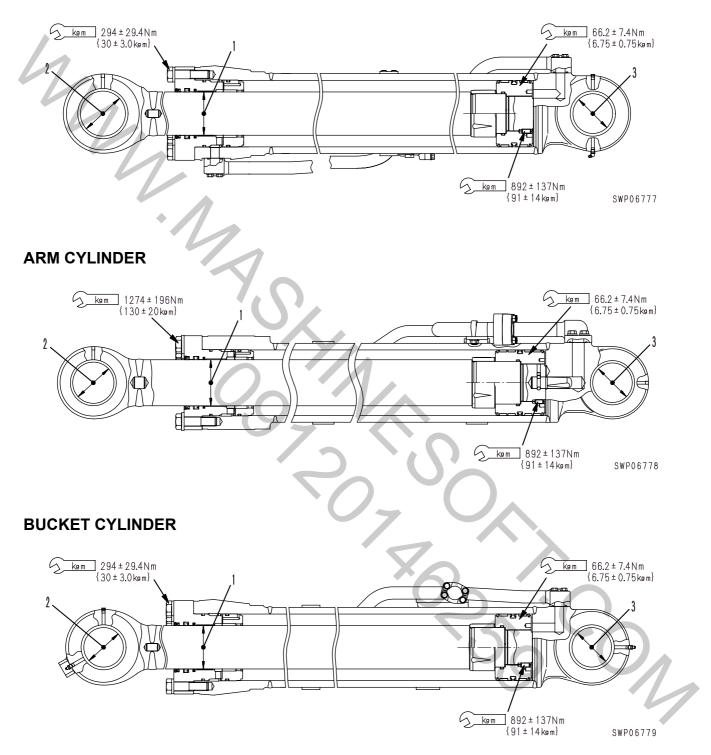
- When control lever (1) is operated to the LOWER position, PPC pressure flows and boom Lo spool (2) moves to the LOWER position. At the same time, regeneration valve spool (3) is moved by the PPC pressure from port **Pi**. As a result, the head and bottom ends of boom cylinder (4) are interconnected through ports **PB** and **PM**.
- When this happens, the oil from the cylinder bottom passes through the control valve and returns to tank (5). Some of the oil enters port **PB** of the regeneration valve and flows from port **PM** to the cylinder head to increase the lowering speed of the boom.
- The boom cylinder has a large volume, and during compound operations, the oil flow from the pump to the cylinder head is insufficient, so this action prevents any vacuum from forming inside the circuit.



MMM MASHINGOTATION

HYDRAULIC CYLINDER

BACKHOE SPECIFICATION BOOM CYLINDER



hung

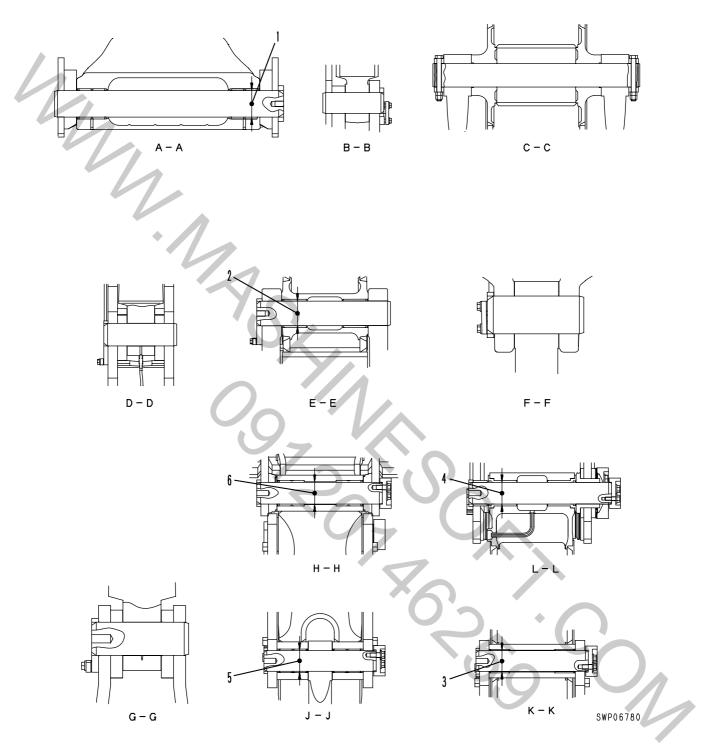
Unit: mm

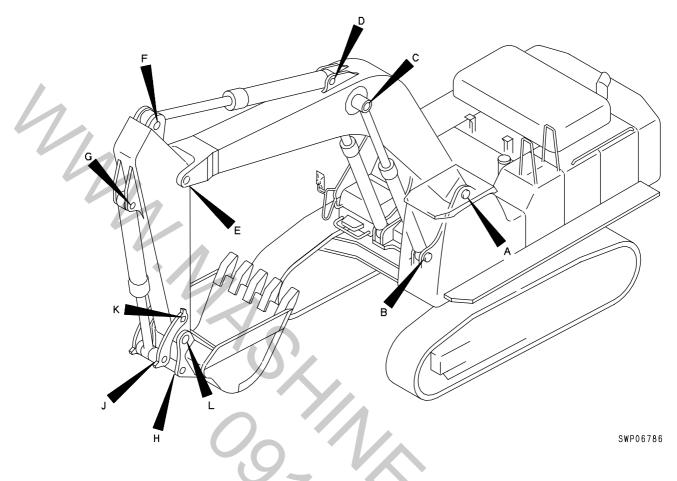
								Unit. mm
No.	Check	item		Criteria				Remedy
	Clearance between piston rod and bushing	Name of	Standard	rd Tolerance		Standard		
		cylinder	size	Shaft	Hole	clearance	limit	
1		Boom	120	-0.036 -0.090	+0.263 +0.048	0.084 – 0.353	0.453	Replace
		Arm	140	-0.043 -0.106	+0.256 +0.039	0.082 – 0.362	0.662	bushing
		Bucket	120	-0.036 -0.090	+0.263 +0.048	0.084 – 0.353	0.453	
	Clearance	Boom	125	-0.043 -0.106	+0.495 +0.395	0.438 – 0.601	1.5	
2	between piston rod support shaft	Arm	125	-0.043 -0.106	+0.495 +0.395	0.438 – 0.601	1.5	9
	and bushing	Bucket	110	-0.036 -0.090	+0.457 +0.370	0.406 – 0.547	1.5	Replace pin,
	Clearance between cylinder bottom support shaft and bushing	Boom	110	-0.036 -0.090	+0.151 +0.074	0.110 – 0.241	1.5	bushing
3		Arm	120	-0.036 -0.090	+0.457 +0.370	0.406 – 0.547	1.5	
		Bucket	110	-0.036 -0.090	+0.457 +0.370	0.406 – 0.547	1.5	

ON NA

WORK EQUIPMENT

BACKHOE SPECIFICATION



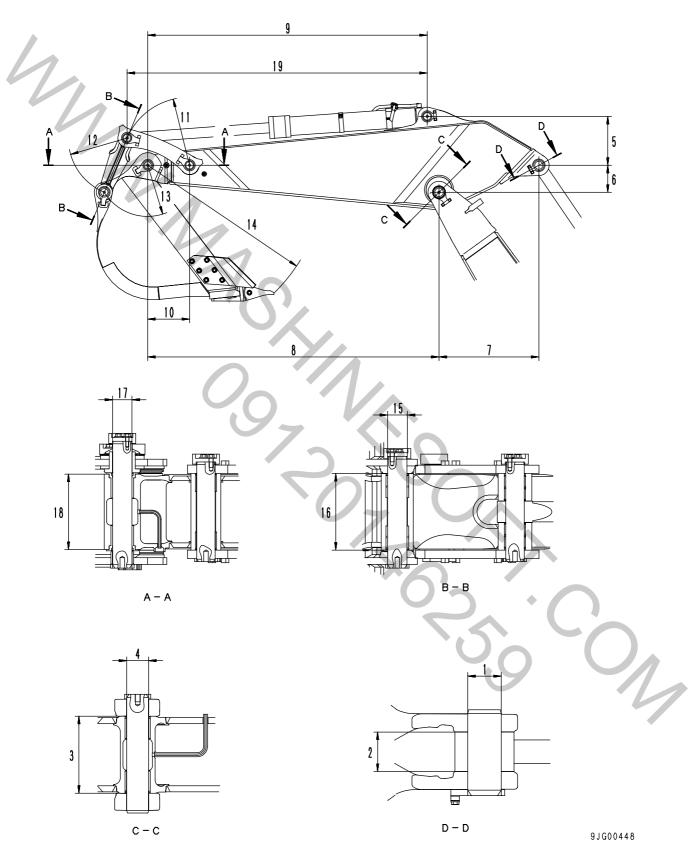


No.	Check item	~	Criteria				Remedy
1	Clearance between bushing and mounting pin of boom	Standard Tol size Shaft		ance Hole	Standard clearance	Clearance limit	
I	and revolving frame	140	-0.043 -0.106	+0.148 +0.057	0.100 – 0.254	1.5	
2	Clearance between bushing and mounting pin of boom and arm	130	-0.043 -0.106	+0.407 +0.325	0.368 – 0.513	1.5	
3	Clearance between bushing and mounting pin of arm and link	110	-0.036 -0.090	+0.360 +0.284	0.320 – 0.450	1.5	Replace
4	Clearance between bushing and mounting pin of arm and bucket	115	-0.036 -0.090	+0.326 +0.223	0.259 – 0.416	1.5	4
5	Clearance between bushing and mounting pin of link and link	110	-0.036 -0.090	+0.354 +0.275	0.311 – 0.444	1.5	
6	Clearance between bushing and mounting pin of link and bucket	115	-0.036 -0.090	+0.382 +0.279	0.315 – 0.472	1.5	
7	Bucket clearance			0.5 – 1.0			Adjust shims

DIMENSIONS OF WORK EQUPMENT

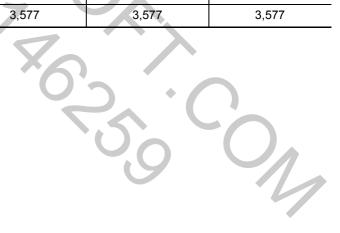
BACKHOE SPECIFICATION

1. ARM

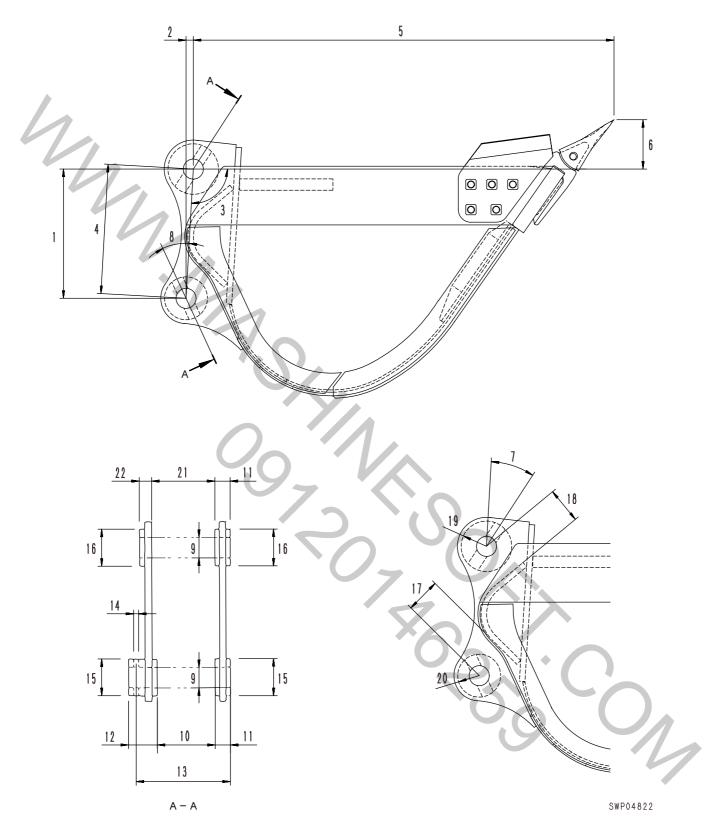


Unit: mm

	Model		PC600, PC600LC-7				
No.		2.9 m Arm	3.5 m Arm	4.3m Arm	5.2m Arm		
	1	125	125	125	125		
1	2	148	148	148	148		
	3	458	458	458	458		
	4	130	130	130	130		
V	5	499	582	627.7	666.9		
	6	460.6	321.7	338	352		
	7	1,188.9	1,187.2	1,182.7	1,178.6		
	8	2,863.2	3,465.2	4,256.6	5,188.1		
	9	3,624	3,324.2	3,315.9	3,308.2		
	10	471.3	497.6	497.6	497.6		
	11	910	810	810	810		
	12	700	700	700	700		
	13	678	608	608	608		
	14	2,169	2,138	2,138	2,138		
	15	115	115	115	115		
	16	457 ± 1	457 ± 1	457 ± 1	457 ± 1		
	17	115	115	115	115		
18	Arm as individual part	448 _{-0.5}	448 _{-0.5}	448 _{-0.5}	448 _{-0.5}		
10	When press- fitting bushing	464	464	464	464		
19	Min.	2,360	2,152	2,152	2,152		
19	Max.	3,990	3,577	3,577	3,577		



2. BUCKET



DIMENSIONS OF WORK EQUPMENT

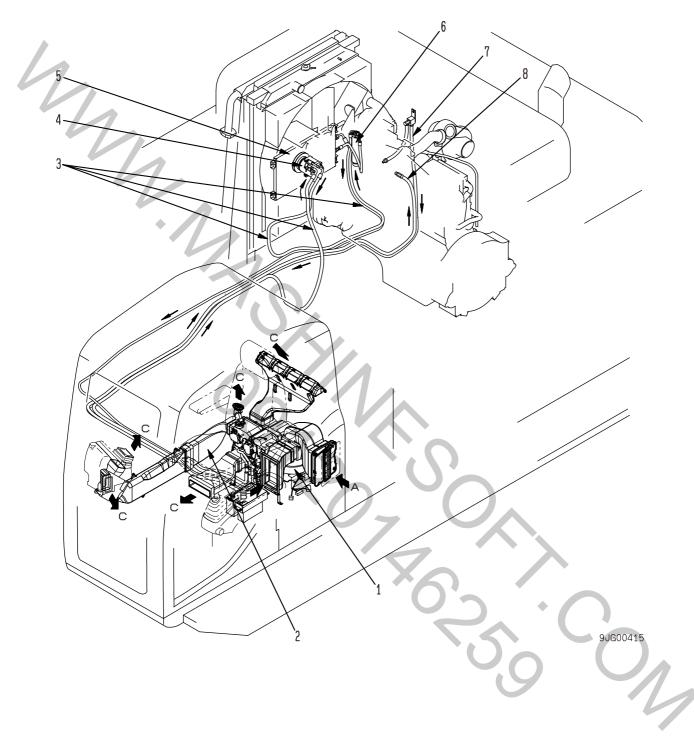
Unit: mm

	Model	PC600-7, PC600LC-7				
No.		2.0 m ³ , 2.3m ³ , 2.7m ³ Bucket	3.5 m ³ Bucket			
	1	605.2 ± 0.5	665 ± 0.5			
	2	58.1 ± 0.5	132.5 ± 0.5			
	3	95.5°	101.3°			
1	4	608	678			
	5	2,119.9	2,150.4			
	6	277.9	278.4			
	7	-	_			
	8	-	_			
	9	ø115	ø115			
	10	457 ± 1	457 ± 1			
	11	80.5	80.5			
	12	84.5	84.5			
	13	626	626			
	14		_			
	15	-	_			
	16	ø260	ø260			
	17	123.9	178.8			
	18	202.4	182.3			
	19	ø240	ø240			
	20	ø208	ø208			
	21	488.5 ± 1	488.5 ± 1			
	22	79	79			
		×6				

AIR CONDITIONER

AIR CONDITIONER PIPING

For the electric circuit diagram of the air conditioner, see Chapter 90.



- 1. Air conditioner unit
- 2. Duct
- 3. Refrigerant piping
- 4. Air conditioner compressor
- 5. Condenser
- 6. Receiver tank
- 7. Hot water return piping
- 8. Hot water pickup piping

- A : Fresh air
- B : Recirculated air
- C : Hot air/cold air

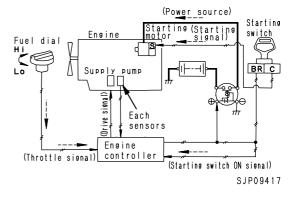
ENGINE CONTROL

1. Operation of system

Starting engine

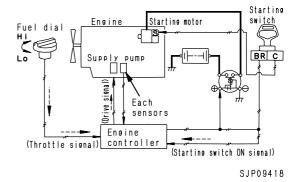
When the starting switch is turned to the START position, the starting signal flows to the starting motor, and the starting motor turns to start the engine.

When this happens, the engine controller checks the signal from the fuel control dial and sets the engine speed to the speed set by the fuel control dial.



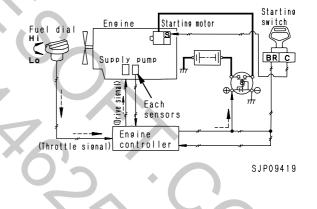
Engine speed control

 The fuel control dial sends signal voltages to the engine controller according to its angle.
 The engine controller sends drive signals to the supply pump according to the signal voltages received from the fuel control dial and controls the fuel injection pump to control the engine speed.



Stopping engine

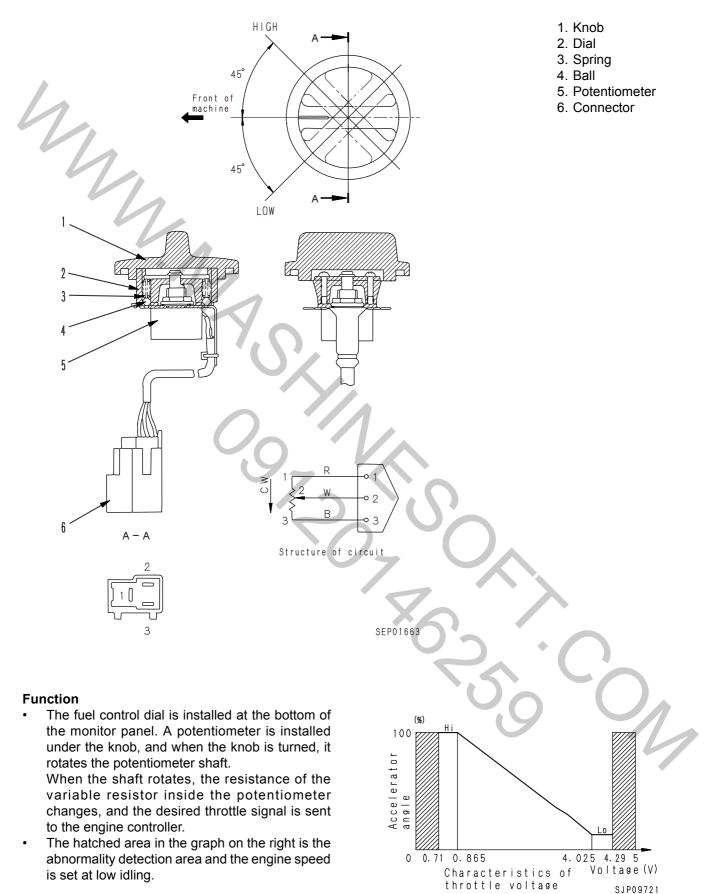
 When the engine controller detects that the starting switch is at the STOP position, it cuts the signal to the supply pump drive solenoid to stop the engine.



N

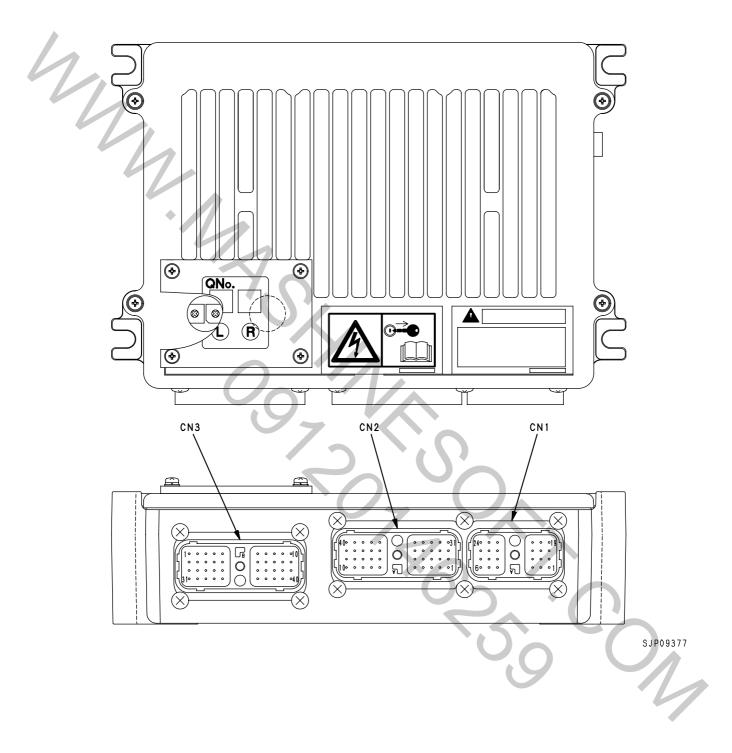
2. Components of system

Fuel control dial



MMM MASHINGOTATION

3. Engine controller



Input and output signals

CN1 [CN-E11]

	Pin No.	Signal name	Input/ Output		Pin N
	CN1-1	POWER (+24V constant)			CN2
	CN1-2	POWER (+24V constant)			CN2
	CN1-3	Model selection 1	Input		CN2
	CN1-4	GND			CN2
	CN1-5	NC	Input		CN2
/	CN1-6	NC	Output		CN2
	CN1-7	GND			CN2
	CN1-8	GND			CN2
	CN1-9	NC	Input		CN2
	CN1-10	GND			CN2-
	CN1-11	NC	Input		CN2-
	CN1-12	NC	Output		CN2-
	CN1-13	Key switch (ACC)	Input		CN2-
	CN1-14	NC	Input		CN2-
	CN1-15	Engine oil pressure switch (For high	Input		CN2-
		pressure)	mput		CN2-
	CN1-16	(Memory clear)			CN2-
	CN1-17	Model selection 3	Input		CN2-
	CN1-18	NC	Output		CN2-
	CN1-19	Key switch (ACC)	Input		CN2-
	CN1-20	Starting switch (C)	Input	1	CN2-
	CN1-21	Engine oil pressure switch (For low pressure)	Input		
	CN1-22	. ,	Input		CN2-
		Model selection 2	Input		CN2-
	CN1-24		Output		CN2-
	••••		e any at		CN2-

CN2 [CN-E12]

	N-E 12]	
Pin No.	Signal name	Input/ Output
CN2-1	GND	
CN2-2	NC	
CN2-3	NC	Input
CN2-4	RS232C_RX1	Input
CN2-5	NC	
CN2-6	NC	
CN2-7	NC	Input
CN2-8	NC	Input
CN2-9	Sensor 5V power supply 2	Output
CN2-10	Fuel control dial	Input
CN2-11	S_NET_SHIELD GND	
CN2-12	CAN_SHIELD	
CN2-13	NC	Output
CN2-14	RS232C_TX1	Output
CN2-15	G_SHIELD (GND)	
	Ne_SHIELD (GND)	
CN2-17	Fuel temperature sensor	Input
CN2-18	NC	Input
CN2-19	Sensor 5V power supply 1	Output
CN2-20	Boost pressure sensor	Input
CN2-21	S_NET (+)	Input/
	0_1121(1)	Output
CN2-22	CAN (L)	Input/ Output
CN2-23	NC	
CN2-24	(FWE_switch)	Input
CN2-25	G pulse (-)	Input
CN2-26	Ne pulse (–)	Input
CN2-27	Water temperature sensor (High)	Input
CN2-28	NC	Input
CN2-29	Analog GND	
CN2-30	NC	Input
CN2-31	S NET (+)	Input/
		Output
CN2-32	CAN (H)	Input/ Output
CN2-33	NC	
CN2-34	GND (232C_GND)	
CN2-35	G pulse (+)	Input
CN2-36	Ne pulse (+)	Input
CN2-37	Water temperature sensor (Low)	Input
CN2-38	NC	Input
CN2-39	Analog GND	
CN2-40	Common rail pressure sensor	Input
L		

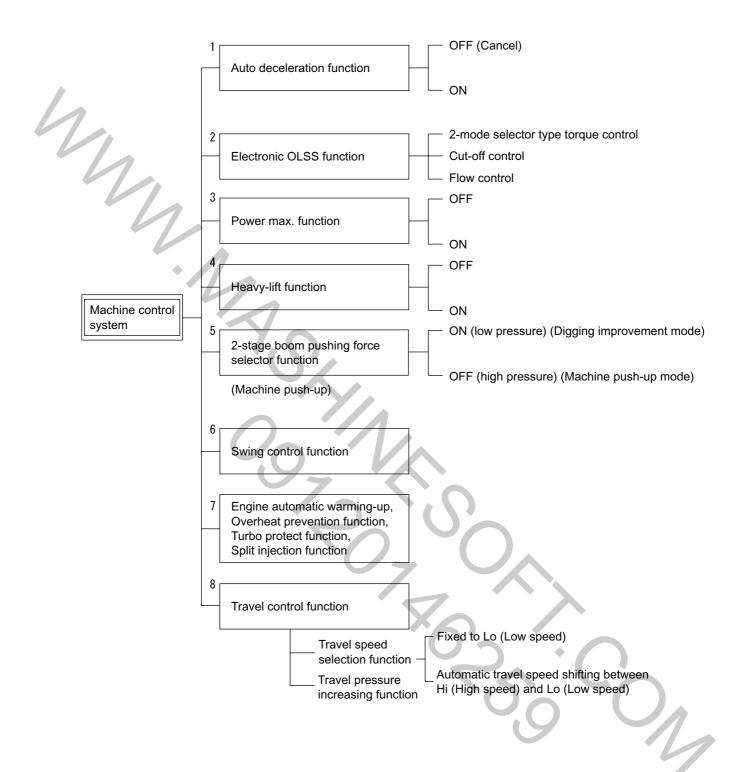
CN3 [CN-E13]

	_	
Pin No.	Signal name	Input/ Output
CN3-1	Power supply for power	Output
CN3-2	Power supply for power	
CN3-3	NC	
CN3-4	NC	
CN3-5	Injector #3 (+)	Output
CN3-6	Injector #2 (+)	Output
CN3-7	NC	Input
CN3-8	(Output mode selection 1 (Test mode))	Input
CN3-9	(Lever neutral flag (Test mode))	Input
CN3-10	(Engine rotation pulse output)	Output
CN3-11	Power GND	Input
CN3-12	Supply pump 1 (+)	Output
CN3-13	Supply pump 2 (+)	Output
CN3-14	Injector #1 (+)	Output
CN3-15	Injector #3 (–)	Output
CN3-16	Injector #2 (–)	Output
CN3-17	NC	Input
CN3-18	(Output mode selection 2 (Test mode))	Input
CN3-19	NC	Input
CN3-20	(Q command output)	Output
CN3-21	Power supply for power	
CN3-22	Supply pump 1 (–)	Output
CN3-23	Supply pump 2 (–)	Output
CN3-24	Injector #1 (–)	Output
CN3-25	Injector #6 (+)	Output
CN3-26	Injector #4 (+)	Output
CN3-27	NC	Output
CN3-28	NC	Input
CN3-29	NC	Input
CN3-30	GND	
CN3-31	Power GND	
CN3-32	Power GND	
CN3-33	Injector #5 (–)	Output
CN3-34	Injector #5 (+)	Output
CN3-35		Output
CN3-36	Injector #4 (–)	Output
CN3-37	NC	Output
CN3-38	NC	Input
CN3-39	NC	Input
CN3-40	GND	

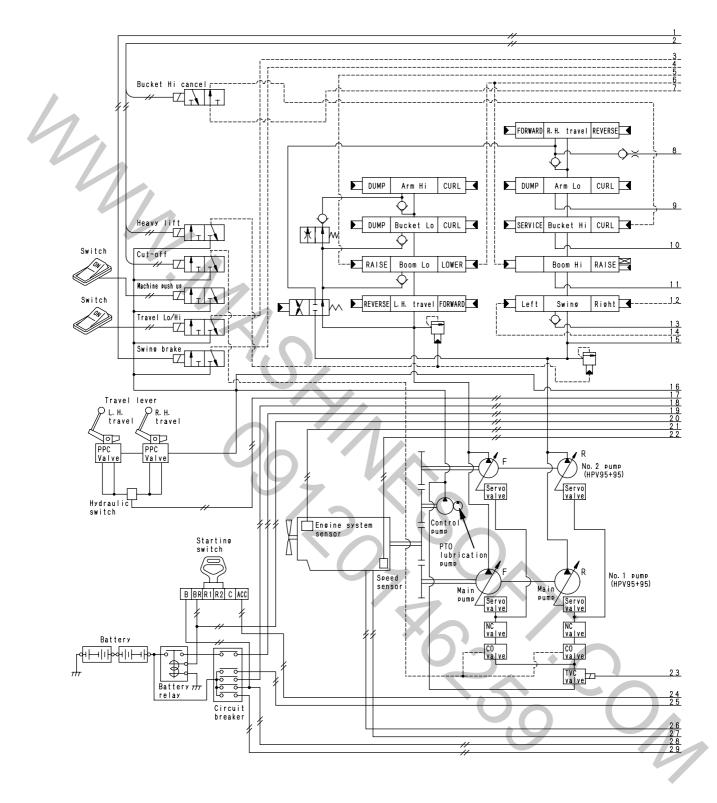
7 7

2n

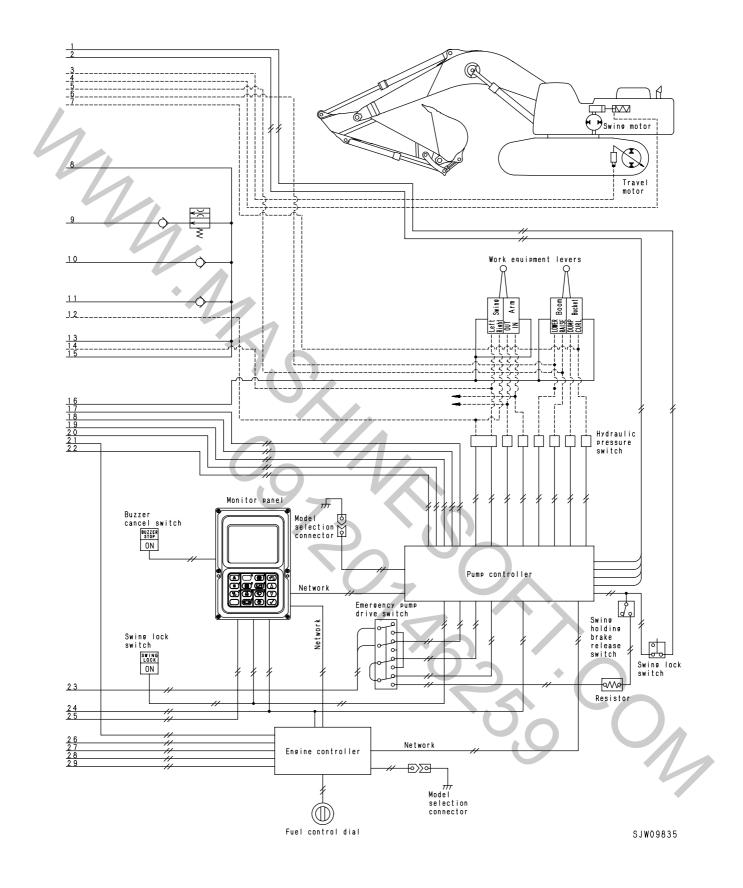
MACHINE CONTROL SYSTEM



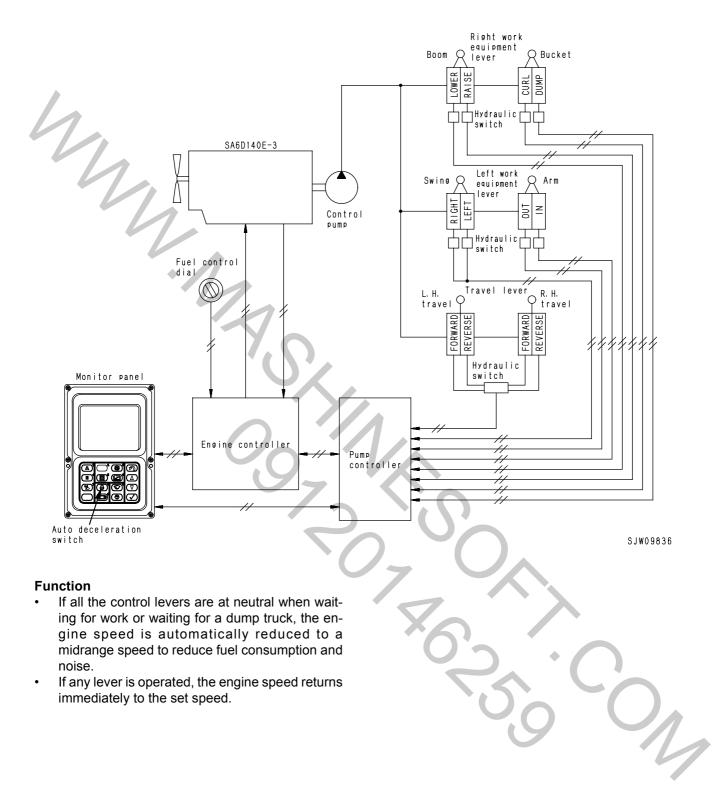
MACHINE CONTROL SYSTEM DIAGRAM



SJW09834



1. Auto deceleration function



10-146

Operation

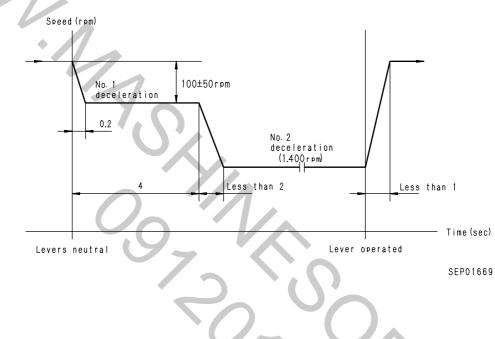
1. When auto-deceleration switch is turned ON

Control levers at neutral

- If the engine is running at above the deceleration actuation speed (approx. 1400 rpm), and all the control levers are returned to neutral, the engine speed drops immediately to approx. 100 rpm below the set speed to the No. 1 deceleration position.
- If another 4 seconds passes, the engine speed is reduced to the No. 2 deceleration position (approx. 1400 rpm), and is kept at that speed until a lever is operated.

When control lever is operated

 If any control lever is operated when the engine speed is at No. 2 deceleration, the engine speed will immediately rise to the speed set by the fuel control dial.



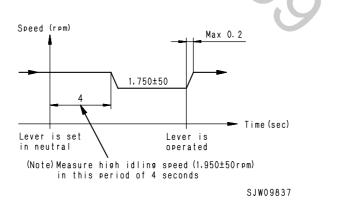
2. When auto-deceleration switch is turned OFF

Control lever at neutral

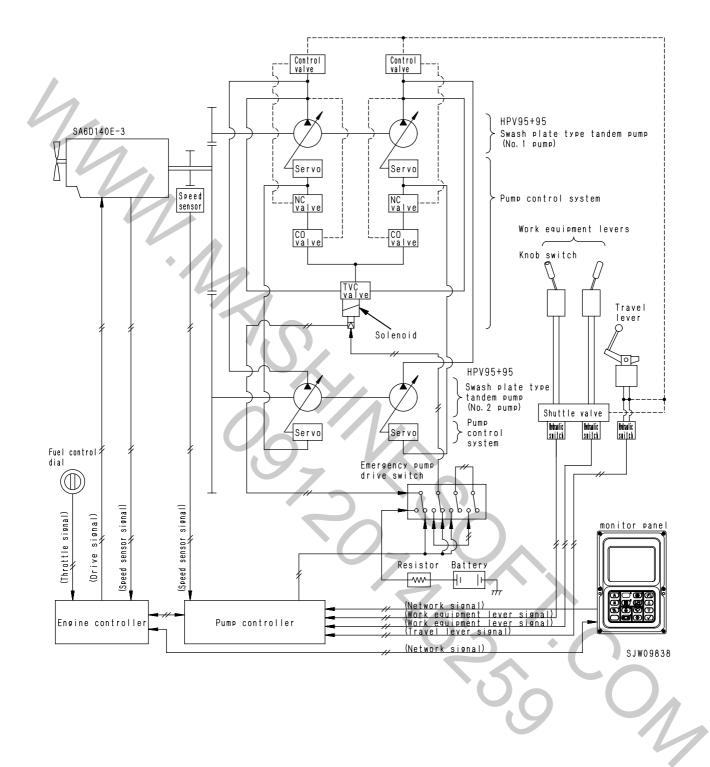
• If the engine is running at a speed above 1,750 rpm and all the control levers are returned to neutral, the engine speed drops to approx. 1,750 rpm after 4 seconds and is kept at that speed until a lever is operated.

When control lever is operated

If any control lever is operated under the condition shown at left (after the engine speed drops to approx. 1,750 rpm), the engine speed will immediately rise to the speed set by the fuel control dial.



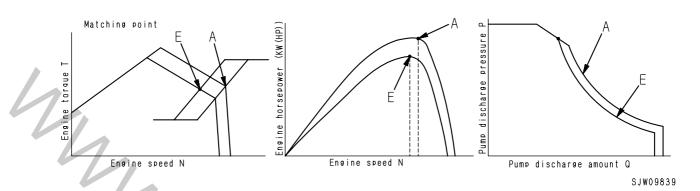
2. Electronic OLSS function Pump control system



- Interconnected control of all pumps is carried out by one TVC valve.
- A mode: Total horsepower control by engine speed sensing
 - E mode: Total horsepower control by engine speed sensing
- Emergency pump drive circuit:
 - Constant torque control

1) Control method in each mode

A, E mode



• Matching point in A, E mode: Rated output point

Model	PC600, PC600LC-7				
A	287 kW/1,800 rpm {385 HP/1,800 rpm}				
E	247 kW/1,720 rpm {331 HP/1,720 rpm}				

 When the load on the pump rises and the pressure rises, the engine speed goes down. At this time, the pump discharge is reduced and the engine speed is set about the rated output point. If the pressure lowers, the pump discharge is increased until the engine speed is set about the rated output point. By repeating this control, the engine can always

By repeating this control, the engine can always be used at near the rated output point.

 Compared with the A mode, which provides the maximum output, the E mode lowers the engine output to provide matching at a point which gives better fuel consumption efficiency than the A mode.

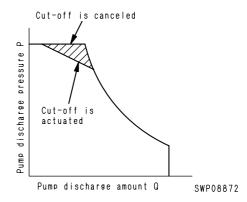
Jn,

2) Cut-off function

 If the load during operation increases and the pump discharge pressure rises to near the relief pressure, the main pump cut-off valve is actuated to reduce the relief loss.

3) Cut-off cancel function

- The cut-off cancel function acts to stop the operation of the cut-off function in order to ensure the pump flow when close to the relief pressure, thereby preventing any drop in speed.
- The actuation and cancellation of the cut-off function is set automatically by operating the power max. switch, travel lever, and heavy lift switch.



Cut-off function and actuation of each switch

Switch		g mode itch	Trave	l lever	Heav	ry lift	Power swi		Swing loo	ck switch
Function	А	Е	ON	OFF	ON	OFF	ON	OFF	ON	OFF
Cut-off function	Actu- ated	Actu- ated	Cancel	Actu- ated	Cancel	Actu- ated	Cancel	Actu- ated	Cancel	Actu- ated

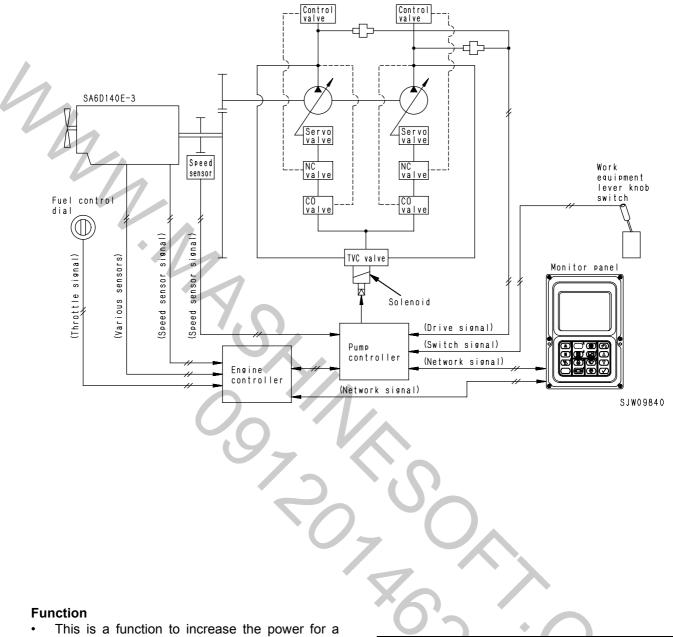
4) 2-stage relief function

 When the power max. switch is ON, if the travel lever is operated and the heavy lift switch is ON, the pilot pressure of the 2-stage relief valve raises the set pressure of the main relief valve from 31.9 MPa {325 kg/cm²} to 34.3 MPa {350 kg/cm²} to increase the digging and travel power.

	Power max. switch		Trave	lever	Heavy lift switch (Note 1)		
	ON	OFF	Operated	Neutral	ON	OFF	
Main relief valve set pressure MPa {kg/cm²}	34.3 {350}	31.9 {325}	34.3 {350}	31.9 {325}	34.3 {350}	31.9 {325}	

Note 1: Actuated when the heavy lift switch is ON and the boom RAISE is operated independently

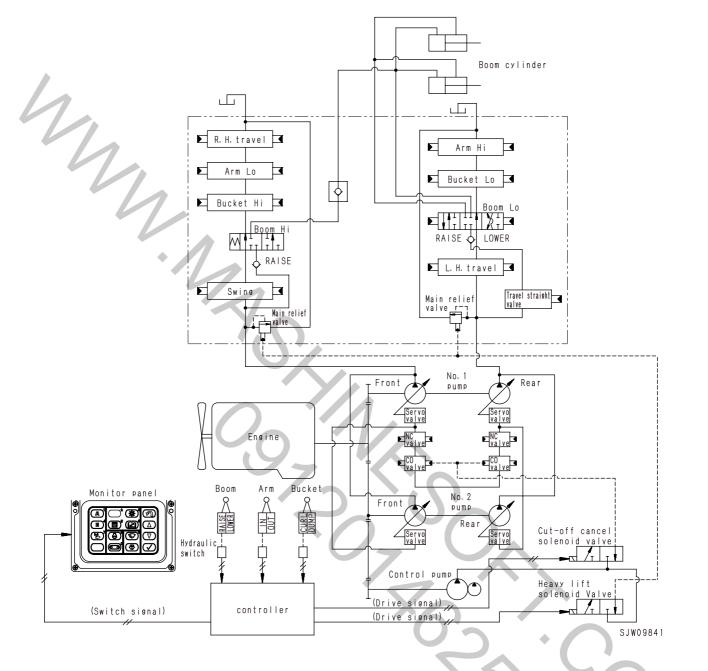
3. Power max. function



- This is a function to increase the power for a fixed period when the L.H. knob switch is oprerated. It makes it possible to obtain a sudden burst of power to match the working conditions.
- If knob switch on the work equipment control lever is turned ON, the following functions are actuated.

Power max. switch Mode, function	OFF	ON
CO function	Actuated	Canceled
Main relief valve Pressure	31.9 MPa {325 kg/cm²}	34.3 MPa {350 kg/cm²}
Operating time	_	Canceled after 8.5 sec even when kept pressed

4. Heavy-lift function



Outline

- This function increases the boom lifting power by approx. 8%.
- It can be actuated only when the boom RAISE is being actuated independently. If the arm IN and bucket DUMP are operated at the same time, the heavy-lift function is automatically canceled.

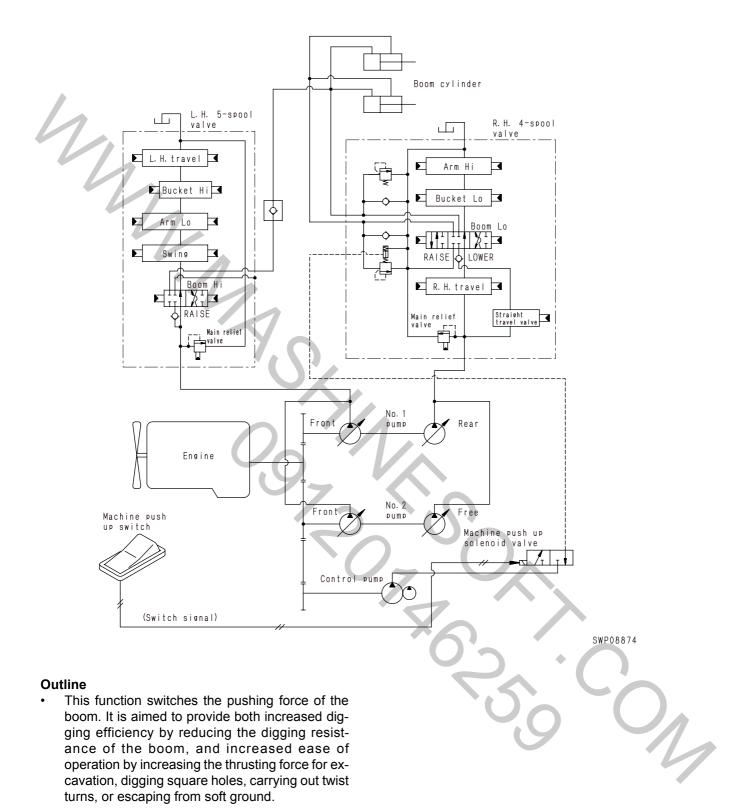
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Operation

	Heavy-lift	Lever of	peration	Heavy-lift	Main relief		Boom lifting
	switch	Boom RAISE	Operate arm or bucket	solenoid valve	valve set pressure	CO valve	force
	OFF	Operated	_	De-energized	31.9 MPa {325 kg/cm²}	Actuated	Normal
L	1		Neutral	Energized	34.3 MPa {350 kg/cm²}	Canceled	8% up
	ON	Operated	Operated	If the arm IN or b boom RAISE op cally canceled, a same as when th	Normal		

*S*₁

5. 2-stage boom pushing force selector function



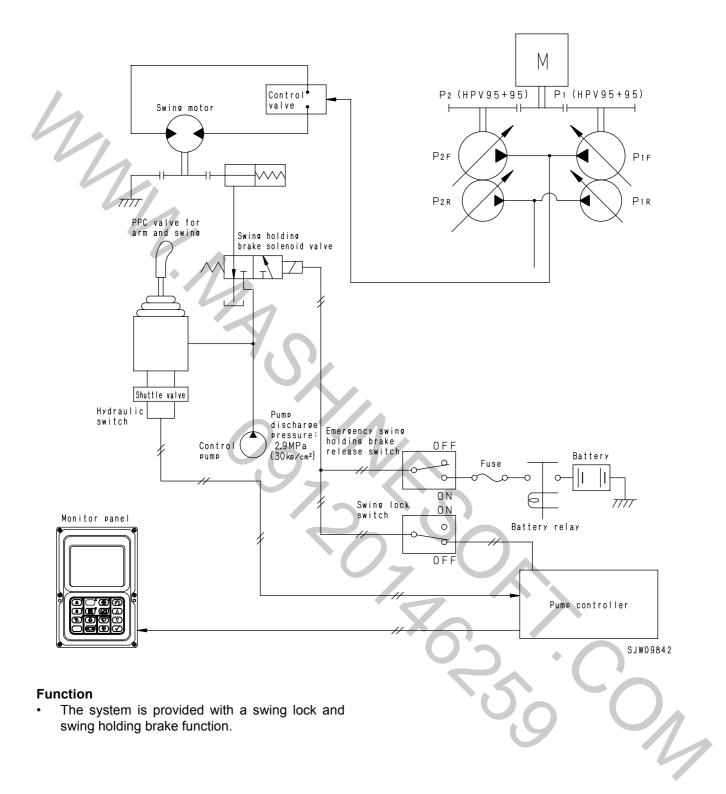
Operation

This function acts to change the set pressure of the safety valve at the boom cylinder end of the R.H. 4-spool control valve boom Lo in 2 ways: to low pressure (14.7 MPa {150 kg/cm²}) and high pressure (33.3 MPa {340 kg/cm²}).

	Mode	Machine push-up switch	Machine push-up solenoid valve	Safety valve set pressure	Effect
L	Boom pushing force (low mode)	NDP00178	Energized	14.7 MPa {150 kg/cm²}	By reducing the boom pushing force, it is made easier for the boom to escape auto- matically in the RAISE direction and to reduce the number of times that the boom is operated. At the same time it also makes the digging operation smoother.
	Boom pushing force (high mode)	NDP00179	De-energized	33.3 MPa {340 kg/cm²}	By increasing the thrust force for boom LOWER, the ease of operation is improved for excavation, digging square holes, car- rying out twist turns, or escaping from soft ground.

Jn,

6. Swing control function



Swing lock, swing holding brake function

Actuation

 The swing lock (manual) can be locked at any desired position, and the swing lock and swing holding brake (automatic) are interconnected with the swing, so they prevent any hydraulic drift after the swing is stopped.

★ Swing brake solenoid valve For details of the structure and function, see SOLENOID VALVE.

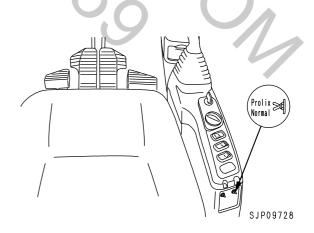
★ Swing motor For details of the structure and function, see SWING MOTOR.

Mode	Swing lock switch	Swing lock monitor	Swing brake solenoid valve	Actuation
Swing holding brake	OFF	OFF	See diagram on right	When swing and work equipment levers are placed at neutral, swing brake is applied after approx. 7 sec; when any swing or work equipment lever is operated, brake is canceled and swing can be operated freely. • Time chart Operated Control Neutral 24V Solenoid OV Canceled Brake Actuated SJW09843
Swing brake	ON	ON	De-energized	Swing lock is actuated and swing is held in position. Even when swing lever is operated, swing lock is not canceled and swing does not move.

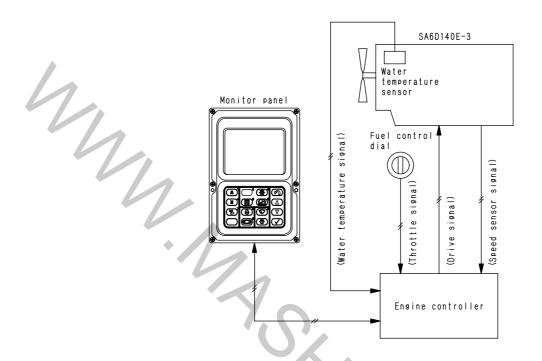
Operation of swing lock prolix switch

- If any abnormality should occur in the controller, and the swing holding brake is not actuated normally and the swing cannot be operated, the swing lock prolix switch can be operated to cancel the swing lock and allow the swing to be operated.
- ★ Even when the swing lock prolix switch is turned ON, the swing lock switch stays ON and the swing brake is not canceled.
- ★ When the swing brake is canceled, the swing has only a hydraulic brake operated by the safety valve, so if the swing is stopped on a slope, there may be hydraulic drift.

Swing lock prolix switch	(when co	N ntroller is rmal)	Of (when co norr	ntroller is
Swing lock switch	ON	OFF	ON	OFF
Swing brake	Swing lock applied	Swing lock canceled	Swing lock applied	Swing holding brake applied



7. Engine automatic warming-up, overheat prevention function, turbo protect function, split injection function



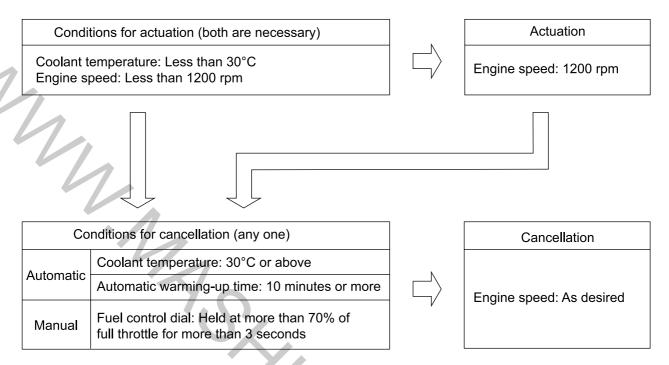
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Function

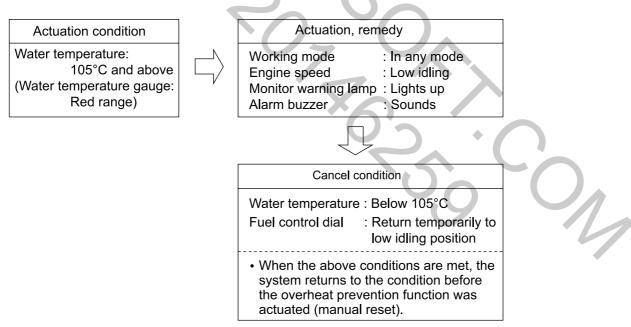
- If the water temperature is low, this automatically raises the engine speed to warm up the engine after it is started. In addition, if the water temperature rises too high during operations, it reduces the load of the pump to prevent overheating.
- To protect the turbocharger bearing during cold weather, the engine speed is kept below the fixed speed when the engine is started. In addition, to improve the starting ability, a small amount of fuel is injected two or more times before the main injection.

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- 1) Engine automatic warming-up function
- After the engine is started, if the engine coolant temperature is low, the engine speed is automatically raised to warm up the engine.



- 2) Engine overheat prevention function
- This function protects the engine by lowering the pump load and engine speed to prevent overheating when the engine coolant temperature has risen too high.
- This system is actuated at 105°C and above.



3) Turbo protection function

Function to protect turbocharger bearing during cold weather by keeping engine speed below fixed speed when engine is started.

Actuation condition

Engine water temperature	Turbo protect time (sec)
More than +10°C	0
+10°C to -10°C	Gradually changes between 0 and 5
Less than –10°C	5

Engine speed: 1000 rpm

Even if the fuel control dial is operated during the above time, the engine speed will not change. After the set time passes, the operation moves to the automatic warming up function in Step 1).

4) Split injection function

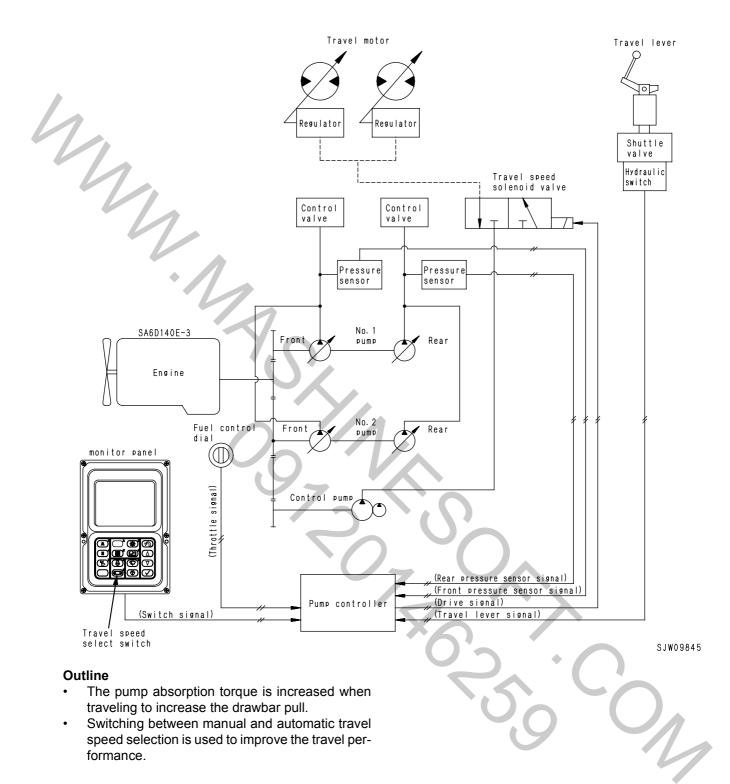
To improve the ease of starting in cold weather, a small amount of fuel is injected two or more times within the set time after calculating in the table below before starting the main injection. As a result, the lower idling speed during this time becomes slightly higher.

Actuation condition

Water temperature	Split injection time (sec)
More than 20°C	0
20°C to -30°C	0 – 15
Less than –30°C	15

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8. Travel control function



Travel speed selection function

- 1) Manual selection using travel speed switch
- If the travel speed switch is set to Lo, Hi, the pump controller controls the pump flow and motor volume at each speed range as shown on the right to switch the travel speed.
- 2) Automatic selection according to engine speed If the engine speed is reduced to below 1,400 rpm by the fuel control dial:
 - If the machine is traveling in Lo, it will not shift even if Hi is selected.
 - If the machine is traveling in Hi, it will automatically shift to Lo.
- 3) Automatic selection according to pump discharge pressure

If the machine is traveling with the travel speed switch at Hi, and the load increases, such as when traveling up a steep hill, if the travel pressure continues at 31.9 MPa (325 kg/cm²) for more than 1.0 sec, the pump volume is automatically switched and the travel speed changes to Lo.

(The travel speed switch stays at Hi.)

The machine continues to travel in Lo, and when the load is reduced, such as when the machine travels again on flat ground or goes downhill, and the travel pressure stays at 22.6 MPa {230 kg/cm²} or less for more than 1.0 sec, the pump volume is automatically switched and the travel speed returns to Hi.

Travel pressure increasing function

Outline

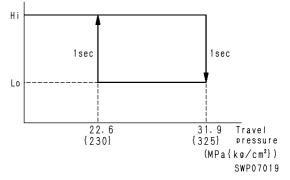
To maintain the drawbar pull when traveling, the cut-off is canceled and the main relief pressure is raised from 31.9 MPa{325 kg/cm²} to 34.3 MPa {350 kg/cm²}.

Operation

	Pressure increase solenoid valve	Main relief valve set pressure	Cut-off cancel solenoid valve	CO valve
When traveling	Energized	34.3 MPa {350 kg/cm²}	Energized	Canceled
When not traveling	De-energized	31.9 MPa {325 kg/cm²}	De-energized	Actuated

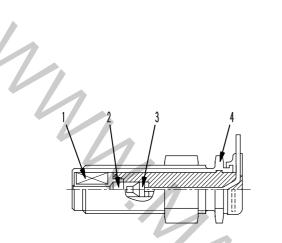
Travel speed switch	Lo (Low speed)	Hi (High speed)
Motor volume	Max.	Min
Travel speed (km/h)	3.0	4.9

Travel speed

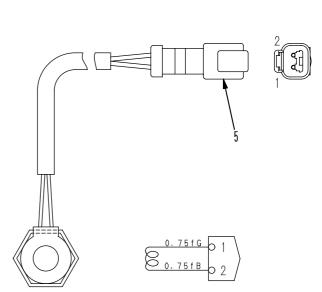


Components of system

1) Engine speed sensor



- 1. Wire
- 2. Magnet
- 3. Terminal
- 4. Housing
- 5. Connector

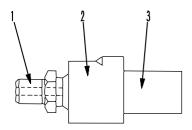


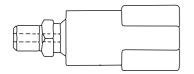
SJP08345

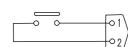
Function

- The engine speed sensor is installed to the ring gear portion of the engine flywheel. It counts electrically the number of gear teeth that pass in front of the sensor, and sends the results to the engine controller and pump controller.
- This detection is carried out by a magnet, and an electric current is generated every time the gear tooth passes in front of the magnet.

2) PPC hydraulic switch







Structure of circuit SEP01692

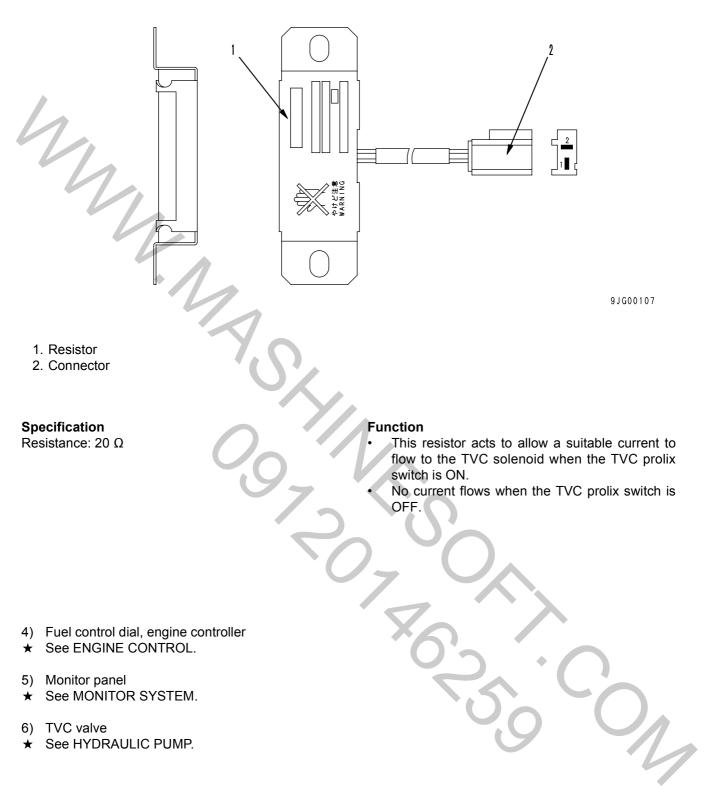
Specifications

Plug
 Switch
 Connector

Composition of points: N.O. points Actuation (ON) pressure: 0.5 ± 0.1 MPa { 5.0 ± 1.0 kg/cm²} Reset (OFF) pressure: 0.3 ± 0.05 MPa { 3.0 ± 0.5 kg/cm²}

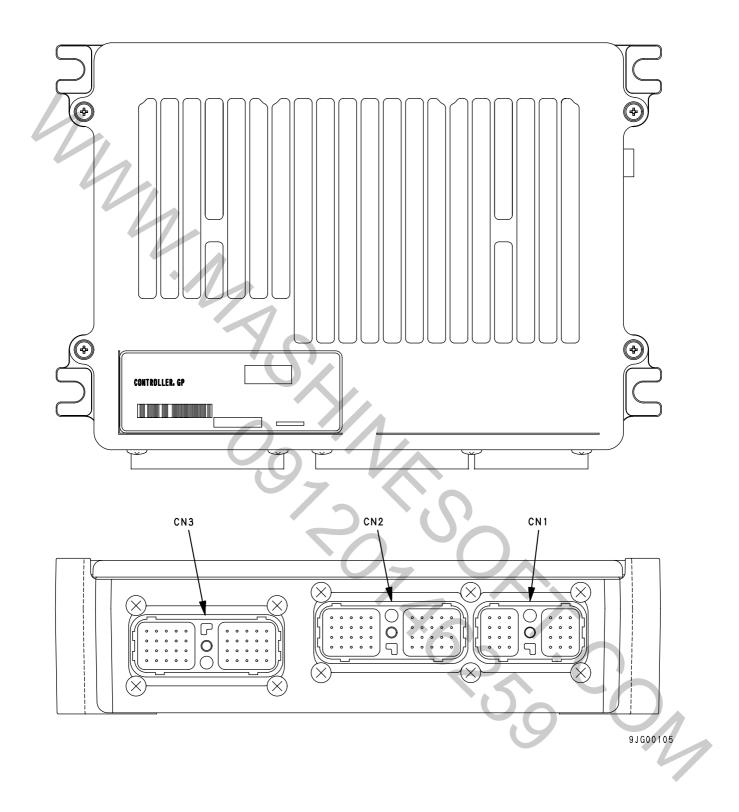
 Function
 There are 12 switches installed to the PPC block. The operating condition of each actuator is detected from the PPC pressure, and this is sent to the engine controller and pump controller.

3) TVC prolix resistor



MMM MASHINGOTATION

7) Pump controller



Input and output signals

CN1 [CN-C01]

Pin No.	Signal name	Input/ Output		Pin No
CN1-1	NC	Input		CN2-1
CN1-2	R pump pressure sensor	Input		CN2-2
CN1-3	NC	Input		CN2-3
CN1-4	NC			CN2-4
CN1-5	(Auto grease controller trouble)	Input		CN2-5
CN1-6	NC	Input		CN2-6
CN1-7	NC	Input		CN2-7
CN1-8	F pump pressure sensor	Input		CN2-8
CN1-9	NC	Input		CN2-9
CN1-10	GND (SIG)			CN2-10
CN1-11	Knob switch	Input		CN2-1
CN1-12	NC	Input		CN2-12
CN1-13	NC	Input		CN2-1
CN1-14	NC	Input		CN2-14
CN1-15	NC	Input		CN2-1
CN1-16	NC	Output		CN2-16
CN1-17	Key switch (Terminal C)	Input		CN2-1
CN1-18	NC	Input		CN2-18
CN1-19	NC	Input		CN2-19
CN1-20	NC	Input		CN2-20
CN1-21	NC		1.	CN2-2
CN1-22	Sensor power supply (+5V)	Output		GNZ-Z
CN1-23	Key switch (Terminal Acc)	Input		CN2-22
CN1-24	Stop light switch	Input		GNZ-Z
)		CN2-2:
				CN2-24
				CN2-2
			7	CN2-20
				CN2-2
				CN2-28
				CN2-29

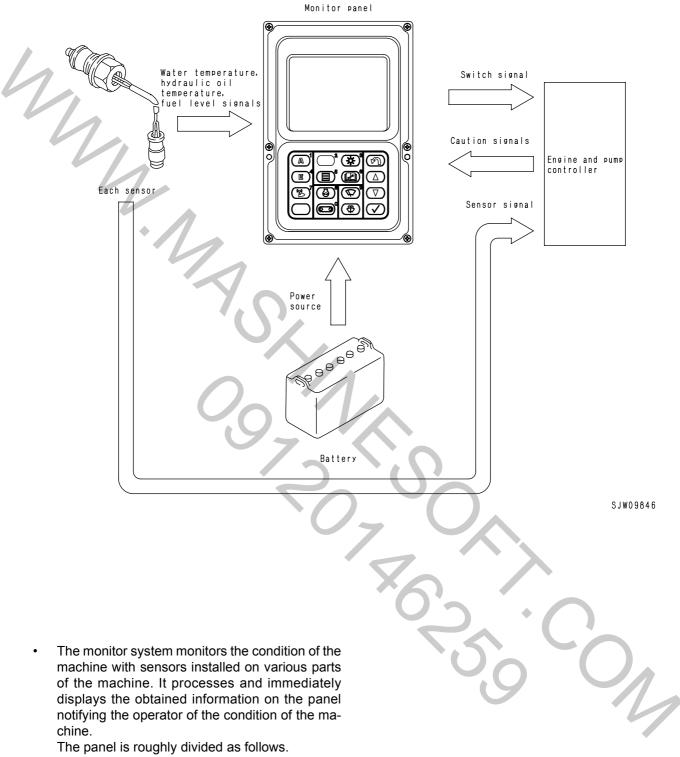
CN2 [CN-C02]

1	•		
	Pin No.	Signal name	Input/ Output
	CN2-1	NC	Output
	CN2-2	Swing prolix switch	Input
	CN2-3	NC	Input
	CN2-4	RS232C-R × D	Input
	CN2-5	(Overload sensor (ON/OFF))	Input
	CN2-6	NC	Input
	CN2-7	Model selection 4	Input
	CN2-8	NC	Output
	CN2-9	NC	Output
	CN2-10	NC	Input
	CN2-11	NC	Output
	CN2-12	CAN_SH	
	CN2-13	NC	Input
	CN2-14	RS232C-T × D	Output
	CN2-15	NC	Input
	CN2-16	NC	Input
	CN2-17	Model selection 3	Input
	CN2-18	NC	Output
	CN2-19	NC	Output
	CN2-20	NC	Input
	CN2-21	S_NET	Input/
		<u> </u>	Output
	CN2-22	CAN0_L	Input/
		_	Output
	CN2-23	NC	Input/
	CNI2 24	FWE switch	Output
		Horn switch	Input
	CN2-25 CN2-26		Input Input
		Model selection 2	Input
		NC	Input
	CN2-29		mput
~		NC	Input
	CN2-31	GND (S NET GND)	mpat
			Input/
	CN2-32	CAN0_H	Output
			Input/
	CN2-33	NC	Output
	CN2-34	GND (RS232C)	
	CN2-35	Service valve pressure switch	Input
	CN2-36	NC	Input
	CN2-37	Model selection 1	Input
	CN2-38	Swing lock switch	Input
	CN2-39	Engine speed sensor (GND)	
	CN2-40	Engine speed sensor	Input

CN3 [CN-C03]

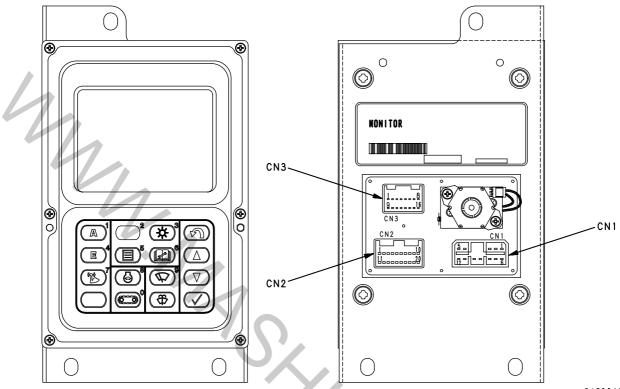
Pin No.	Signal name	Input/ Output
CN3-1	VB (Controller PWR)	Input
	VIS (Solenoid PWR)	Input
A	TVC solenoid (–)	Input
	Battery relay drive	Output
	5 5	Output
CN3-6		Output
	Bucket Hi cancel solenoid	Output
		Output
	Bucket CURL pressure switch	Input
	Boom RAISE pressure switch	Input
	VB (Controller PWR)	Input
	VIS (Solenoid PWR)	Input
CN3-13		Input
	VB (Controller PWR)	Input
	Step light drive relay	Output
	TVC solenoid (+)	Output
	CO cancel solenoid	Output
CN3-18		Output
	Bucket DUMP pressure switch	Input
	Boom LOWER pressure switch	Input
	GND (Controller GND)	Input
CN3-22		
CN3-23		Input
	VB (Controller PWR)	Input
	Flash light drive relay	Output
CN3-26	C F	Output
	Travel Hi/Lo selector solenoid	Output
	2-stage relief solenoid	Input Input Output Output Output Output Input Input Input
	Swing pressure switch	Input
	Arm IN pressure switch	Input
	GND (Controller GND)	Input
	GND (Controller GND)	Input
	GND (Controller GND)	Input
CN3-34		Input
CN3-34		Output
CN3-35 CN3-36		Output
	Swing holding brake solenoid	Output Output
		Output
CN3-38		
	Travel pressure switch	Input
CN3-40	Arm OUT pressure switch	Input

MONITOR SYSTEM



- 1. Monitor section to output alarms when the machine has troubles
- 2. Gauge section to display the condition constantly (Coolant temperature, hydraulic oil temperature, fuel level, etc.)
- The monitor panel also has various mode selector switches and functions to operate the machine control system.

MONITOR PANEL



9JG00427

Outline

• The monitor panel has the functions to display various items and the functions to select modes and electric parts.

The monitor panel has a CPU (Central Processing Unit) in it to process, display, and output the information.

The monitor display unit consists of LCD (Liquid Crystal Display). The switches are flat sheet switches.

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Input and output signals

	CN1		
	Pin	Signal name	Input/
	No.	Signai name	output
	1	Key switch (Battery)	Input
	2	Key switch (Battery)	Input
	3	Washer motor output	Output
	4	Key switch (Terminal C)	Input
	5	Wiper contact W (Lower wiper contact P)	Input
ļ	6	GND	
	7	GND	
	8	VB + (24 V)	Input
	9	Wiper motor (+) <upper (+)="" motor="" wiper=""></upper>	Output
	10	Wiper motor (–) <lower (–)="" motor="" wiper=""></lower>	Output
	11	NC	Input
	12	Wiper contact P (Upper wiper contact P)	Input

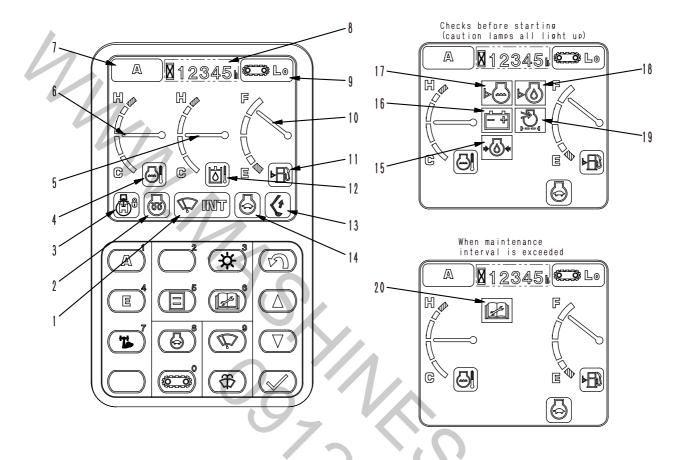
CN2		
Pin No.	Signal name	Input/ output
1	NC	Input
2	Fuel	Input
3	Radiator water level	Input
4	NC	Input
5	Air cleaner clogging sensor	Input
6	NC	Input
7	NC	Input
8	Engine oil level sensor	Input
9	Network (S-NET signal)	Input/ output
10	Network (S-NET signal)	Input/ output
11	Charge level	Input
12	Hydraulic oil temperature (Analog)	Input
13	GND (For analog signal)	
14	Personal code relay (Lo)	Input
15	Window limit switch <lower switch="" wiper=""></lower>	Input
16	Buzzer cancel	Input
17	Swing lock	Input
18	Preheating	Input
19	Light switch	Input
20	Network (S-NET GND)	

CN3		
Pin	Signal name	Input/
No.	olgharhame	output
1	NC	Input
2	NC	Input
3	NC	Input
4	NC	Input
5	NC	Input
6	NC	Input
7	NC	Input
8	NC	Input
9	NC	Input/
9		output
10	NC	Input/
10		output
11	NC	Input
12	NC	Input
13	GND	
14	GND (Shield)	Input
15	CAN (+)	Input
16	CAN (–)	Input



MONITOR CONTROL, DISPLAY PORTION

MONITOR PORTION



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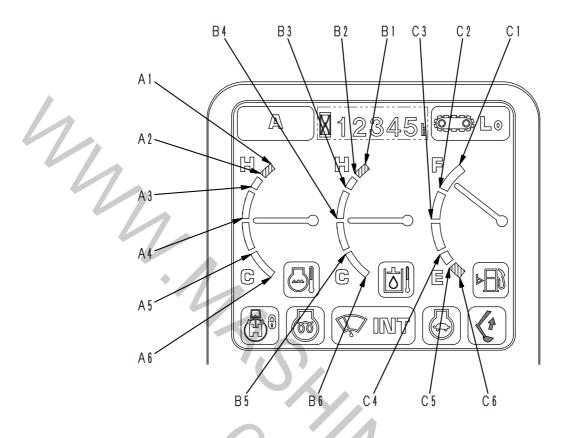
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- 1. Wiper motor
- 2. Preheating monitor
- 3. Swing lock monitor
- 4. Engine water temperature monitor
- 5. Hydraulic oil temperature gauge
- 6. Engine water temperature gauge
- 7. Working mode monitor
- 8. Service meter
- 9. Travel speed monitor
- 10. Fuel gauge

- 11. Fuel level monitor
- 12. Hydraulic oil temperature monitor
- 13. Power Max. monitor
- 14. Auto-deceleration monitor
- 15. Radiator water level caution
- 16. Battery charge caution
- 17. Engine oil pressure caution
- 18. Engine oil level caution
- 19. Air cleaner clogging
- 20. Maintenance time warning caution

MONITOR ITEMS AND DISPLAY

Symbol	Symbol Display item Display m					
		Swing lock switch	Swing hold release		Swing lock monitor	
		OFF	OF	F	OFF	
A 0	Swing lock	ON	OF	F	ON	
SAT00098		OFF	0	N	Flashes	
1		ON	0	N	ON	
		Continuous set	time	Prehea	ating monitor status	
	Drohesting	Up to 30 sec			ON	
	Preheating	From 30 sec. to 4	0 sec.		Flashes	
SAP00526	1	More than 40 s	ec.		OFF	
ATTIP	ľ Oľ	Power Max. switch status		Power Max. monitor status		
Winnin Th	Power Max.	Being pressed		Lights u approx. 9 s	up but goes out after sec. when kept pressed	
ALLER		Not being pressed			Flashes	
SJP08778						
	Engine water temperature	7				
	Hydraulic oil temperature	See gauge display on the	e next page			
	Fuel level	0-	\bigcirc	\wedge		
		R	325	6		



SJP08779

Gauge	Range	Temperature, volume	Indicator	Buzzer sound
	A1	105	Red	0
	A2	102	Red	
Engine water	A3	100	Green	
temperature (°C)	A4	80	Green	
	A5	60	Green	
	A6	30	White	
	B1	105	Red	0
	B2	102	Red	
Hydraulic oil tempera-	В3	100	Green	
ture (°C)	B4	80	Green	
	B5	40	Green	
	B6	20	White	
	C1	524	Green	
	C2	382	Green	
	C3	249	Green	
Fuel level (ℓ)	C4	138	Green	
	C5	101	Green	
	C6	84	Red	

Checks before starting (caution lamps all light up), when maintenance interval is exceeded.

If the checks before starting or maintenance interval is exceeded items light up, the display of the hydraulic oil temperature gauge and the hydraulic oil temperature monitor are stopped, and the following cautions are displayed.

Symbol	Display item	Check before starting item	When engine is stopped	When engine is running
SAP00519	Engine oil pressure	•	_	When abnormal, lights up and buzzer sounds
SAP00522	Battery charge	•	_	Lights up when abnormal
SAP00520	Radiator water level	•	Lights up when abnormal	When abnormal, lights up and buzzer sounds
SAP00523	Engine oil level	•	Lights up when abnormal	-
SAP00521	Air cleaner clogging		-	Lights up when abnormal
SJP08780	Maintenance	O ₇	Lights up when there is only 30 sec. after key is out.	

The problems that have occurred are displayed in order from the left.

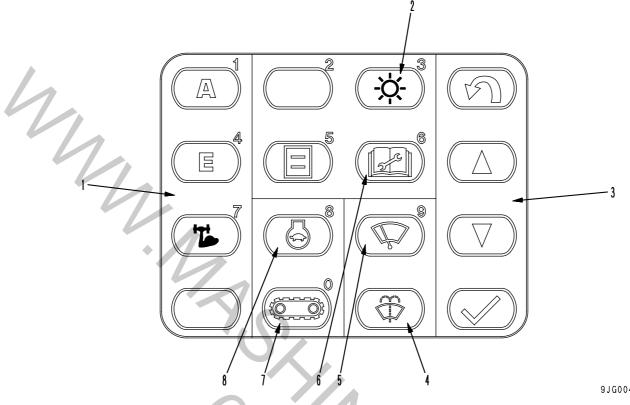
When the above cautions are displayed, if the hydraulic oil temperature is high or low, only the symbol is displayed.

Condition of hydraulic oil	Color of symbol	
Low temperature (below B6 or equivalent)	Black on white background	
Normal (B6 – B2)	No display	
High temperature (above B2)	White on red background	

STRUCTURE, FUNCTION AND MAINTENANCE STANDARD

Display category	Symbol	Display item	Display range	Display method
	SJP08781	Wiper	→ ON → INT → OFF	Displays set condition
h	A SJP08782	Working mode	A B12345 CO CO H A F F CO CO CO CO CO CO CO CO CO CO CO CO CO CO CO	Displays set mode
Monitor	© L⊚ Sjp08783	Travel speed	Lo. H i SJP09460	Displays set speed
	SJP08784	Auto-decelera- tion	$ON \Leftrightarrow OFF$	Displays actuation status
Service meter	8 1 2 3 4 5 1 SJP08785	Service meter indicator	When service meter is working	Lights up when service meter is working
				Coly

SWITCHES



9JG00428

- 1. Working mode selector switch
- 2. Display brightness, contrast adjustment switch
- 3. Control switch
- 4. Window washer switch
- 5. Wiper switch
- 6. Maintenance switch
- 7. Travel speed selector switch
- 8. Auto-deceleration switch

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Working mode selector switch

The condition of the machine changes according to the switch that is pressed (Shown in the figure at right). It is possible to check the condition on the working mode monitor display. The relationship between each working mode and the monitor display is shown in the table on the right.

Maintenance switch

Check the condition of the maintenance items. (For details, see MAINTENANCE FUNCTION.)

Auto-deceleration switch

Each time the auto-deceleration switch is pressed, the auto-deceleration function is switched ON/OFF.

Use the auto-deceleration monitor display to check the present condition.

When the working mode switch is operated to switch the working mode, it is automatically set to ON.

• Travel speed selector switch

Each time the travel speed selector switch is pressed, the travel speed changes.

 $Lo \to Hi \to Lo \ \dots \dots$

Use the travel speed monitor display to check the present condition.

The relationship between the set speed and the monitor display is shown in the table on the right.

Wiper switch

Each time the wiper switch is pressed, the wiper setting changes OFF \rightarrow INT \rightarrow ON \rightarrow OFF \rightarrow

Use the wiper monitor display to check the present condition.

The relationship between the wiper setting and the monitor display is as shown in the table on the right.

Window washer switch

While the switch is being pressed, window washer liquid is sprayed out. There is a time delay before the wiper starts.

Control switch

This is used for control when using the maintenance function or select function. (For details, see each function.)

• Display brightness, contrast adjustment switch Use this switch when adjusting the display brightness and contrast. (For details, see each function.)

Switch that is pressed	Display	Working mode status after setting
[A]	А	A mode (default)
[E]	E	E mode
SJP09461	SJP09461	Heavy-lift mode

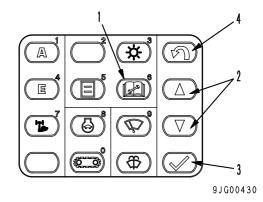
-	Display	Setting
-	Crawler symbol + Lo	Low speed (default)
	Crawler symbol + Hi	High speed

Display	Setting	Wiper actuation status				
None	OFF	Stowing stopped or now stowing				
Wiper symbol + INT	INT	Intermittent actuation				
Wiper symbol + ON	ON	Continuous actuation				

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MAINTENANCE FUNCTION

When the maintenance time for replacement, inspection, or filling has approached for the 10 maintenance items, press maintenance switch (1) and the caution display (yellow or red) appears on the monitor display for 30 seconds after the key is turned ON to remind the operator to carry out lubrication maintenance.



★ Maintenance items

ltem	Replacement interval (hours)					
Engine oil	500					
Engine oil filter	500					
Fuel filter	500					
Hydraulic filter	1,000					
Hydraulic tank breather	1,000					
Corrosion resistor	1,000					
Damper case oil	1,000					
Final case oil	2,000					
Machinery case oil	1,000					
Hydraulic oil	5,000					
	Engine oil Engine oil filter Fuel filter Hydraulic filter Hydraulic tank breather Corrosion resistor Damper case oil Final case oil Machinery case oil					

★ The above replacement intervals are set for each item, and the time remaining to maintenance is reduced as the machine is operated. The content of the caution display differs according to the ramaining time. The relationship is as shown in the table below.

Display	Condition			
None	Remaining time for mainte- nance for all items is more than 30 hours			
Notice display (black sym- bol displayed on yellow background)	There is one or more items with less than 30 hours remaining time for mainte- nance			
Warning display (wiper symbol displayed on red background)	There is one or more items with less than 0 hours remaining time for mainte- nance			

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METHOD OF CHECKING STATUS

MAINTENANCE ITEMS

- ★ Operate as follows when on the operator screen.
- 1. Press maintenance switch (1) and switch to the maintenance list display screen.
 - ★ The maintencance items are displayed as symbols on the screen.
- Press control switch (2), or use the 10-key pad to input the number (01 – 10, 30, 31) of the maintenance item to select the item.
 - ★ The cursor moves and the item is highlighted.
 - ★ The display method is the same as described on the previous page (relationship between remaining time and caution display). If the remaining time is less than 30 hours, the item is displayed in yellow, and if it is less than 0 hours, it is displayed in red.

MAINTENANCE OPERATION

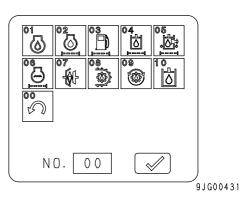
- After completing the selection, press input confirmation switch (3). The screen will change to the maintenance reset screen.
- 2. Use the maintenance reset screen to check the content, and if there is any problem, press input confirmation switch (3) to move to the check screen.

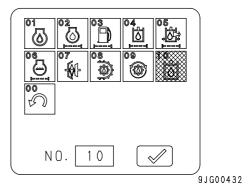
If the wrong item is selected, press return switch (4) to return to the maintenance list screen.

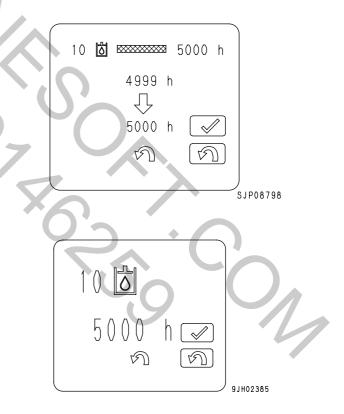
 Check the content on the check screen, and if there is no problem, press input confirmation switch (3) to reset the maintenance time. After the reset is completed, the screen returns

to the maintenance list display screen. To check the remaining time, or if the wrong item is selected, press return switch (4) to return to the maintenance list screen.

- ★ The check screen shows the symbol for the maintenance item and the set time in large letters.
- ★ The background color of the symbol for the item where the maintenance item was reset is the same as the background of the screen, so it is possible to check that it has been reset.





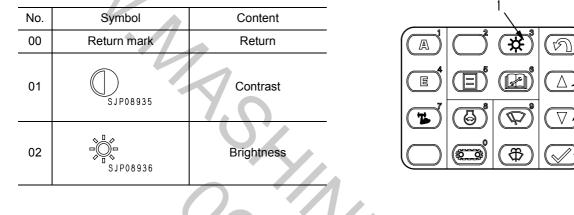


BRIGHTNESS, CONTRAST ADJUSTMENT FUNCTION

This function is used to adjust the brightness and contrast of the display.

Adjustment method

- Operate as follows when on the operator screen.
- 1. Press display brightness/contrast adjustment switch (1) and switch to the adjustment screen.
- ★ Relationship between menu symbol and content.



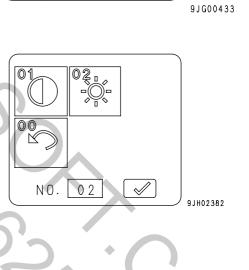
 Press control switch (2), or use the 10-key pad to input the number (00 – 02) to select either contrast or brightness.

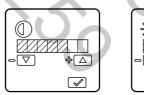
After completing the selection, press input confirmation switch (3) and return to the adjustment screen.

Then press return switch (4) or use the 10-key pad to set to [00] and press input confirmation switch (3) to return to the normal screen.

3. Press control switch (2) and adjust the brightness and contrast as desired.

Control switch	Actuation	
SJP08933	Flow level bar graph extends to the right	
SJP08934	Flow level bar graph retracts to the left	







Brightness

⊕[∆



3

SERVICE METER CHECK FUNCTION

- When the starting switch is at the OFF position, keep return switch (1) and control switch (2) of the monitor pressed at the same time, and the service meter is shown on the display.
- This display is shown only while the two switches are being pressed. When the switches are released, the display goes out.
 - Note that it takes 3 5 seconds after the switches are pressed for the service meter display to appear.

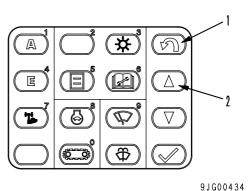
DISPLAY LCD CHECK FUNCTION

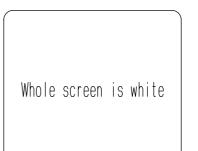
 On the password input screen or on the normal screen, if monitor return switch (1) and working mode (A) switch are kept pressed at the same time, all the LCD display will light up and the whole screen will become white, so the display can be checked.

If any part of the display is black, the LCD is broken.

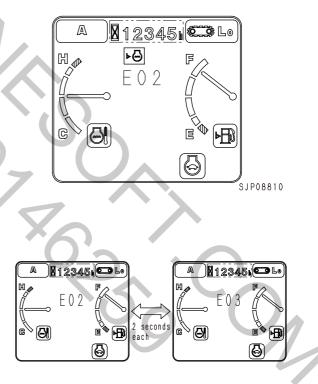
USER CODE DISPLAY FUNCTION

- If there is any problem in operating the machine, the user code is displayed on the monitor to advise the operator of the steps to take. This code display appears on the operator screen.
- On the operator screen, the user code is displayed on the portion for the hydraulic oil temperature gauge.
- If more than one user code is generated at the same time, the user codes are displayed in turn for 2 seconds each to display all the user codes.





SJP08943



SJP08945

• While the user code is being displayed, if the input cnfirmation switch is pressed, the service code and failure code can be displayed.

If there is more than one service code or failure

code, the display switchs every 2 seconds and

displays all the service codes/failure codes that

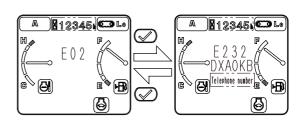
Even if service codes/failure codes have

occurred, if they did not cause the user code to

be displayed, this function does not display

caused the user code to be displayed.

them.



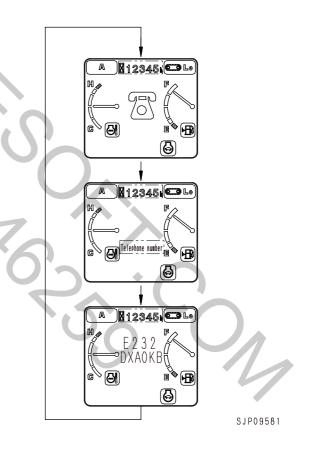
SJP09579

<u>812345</u> <u>12345</u> A A 232 233 DXAOKB DXAOKB A Telephone number Telephone number Every 2 c **H** seconds 6 6

SJP09580

 If the telephone number has been set using the telephone number input on the service menu, it is possible to switch on the service code/failure code and display the telephone symbol and telephone number.

For details of inputting and setting the telephone number, see SPECIAL FUNCTIONS OF MONI-TOR PANEL in the TESTING AND ADJUSTING section.



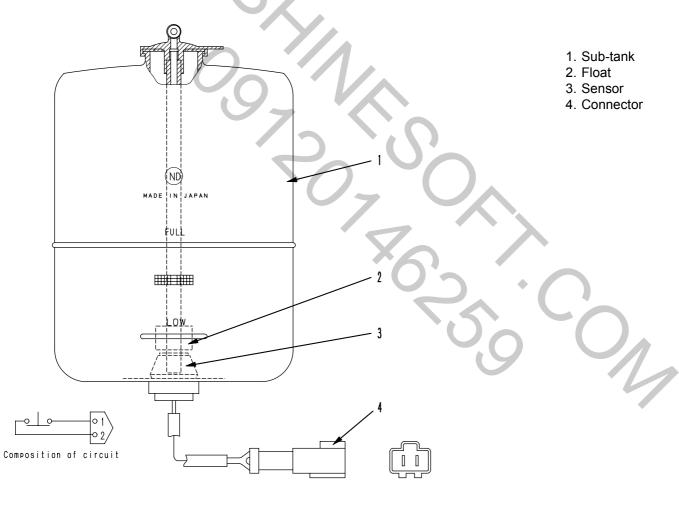
SENSORS

• The signals from the sensors are input directly to the engine controller and the pump controller monitor.

The contact type sensors are always connected at one end to the chassis GND.

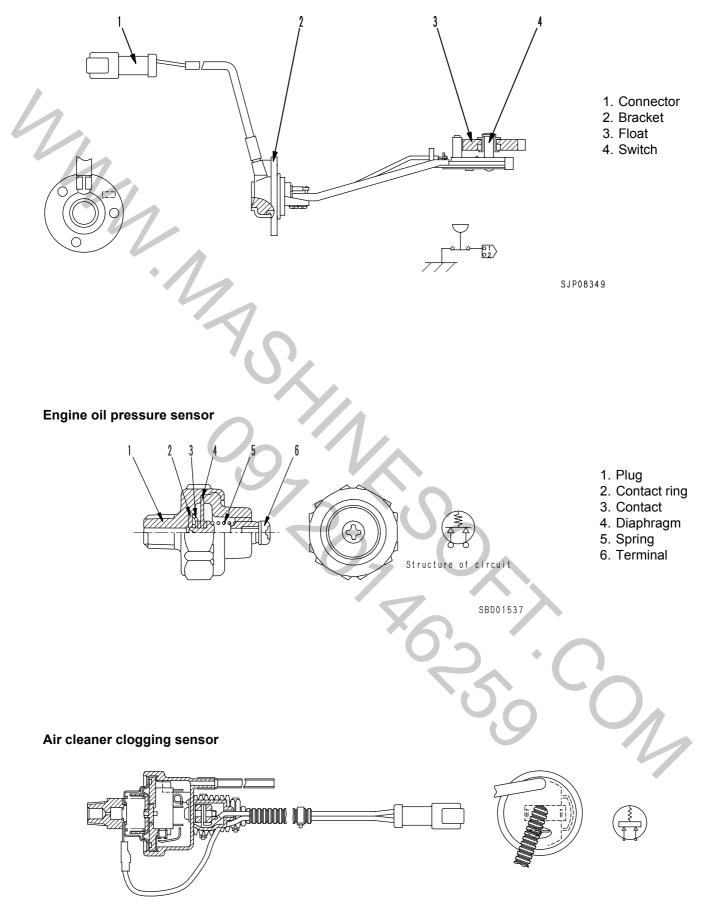
Name of sensor	Type of sensor	When normal	When abnormal	Input controller
Coolant level	Contact type	ON (closed)	OFF (open)	Monitor
Engine oil level	Contact type	ON (closed)	OFF (open)	Monitor
Engine oil pressure	Contact type	ON (closed)	OFF (open)	Engine controller
Coolant temperature	Resistance type	—	—	Engine controller
Fuel level	Resistance type	—	—	Monitor
Air cleaner clogging	Contact type	OFF (open)	ON (closed)	Monitor
Hydraulic oil temperature	Resistance type	—	—	Monitor
Main pump oil pressure	Analog	—	—	Pump controller

Coolant level sensor



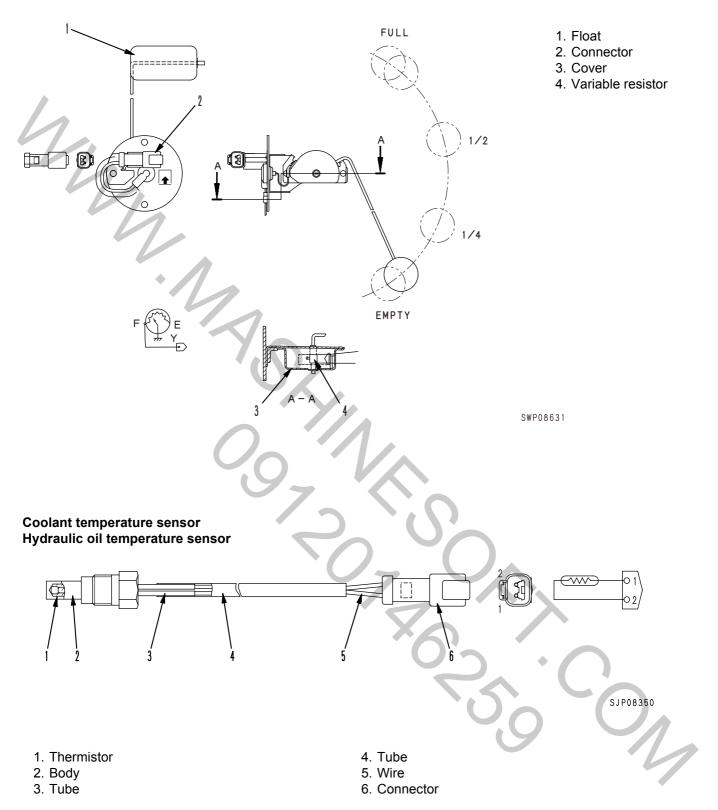
SDP04068

Engine oil level sensor



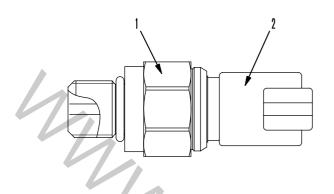
SXP08415

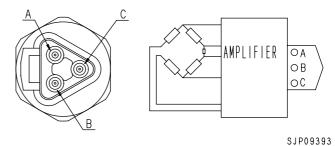
Fuel level sensor



10-186

Main pump oil pressure sensor (0 – 49.0 MPa {0 – 500 kg/cm²})





1. Sensor

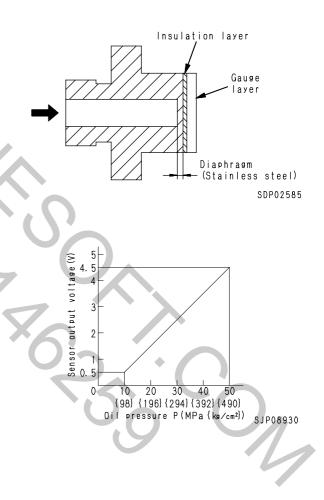
2. Connector

FUNCTION

 The pump pressure sensor is installed to the inlet circuit of the control valve. It converts the pump discharge pressure into a voltage and transmits it to the pump controller.

OPERATION

- The oil pressure applied from the pressure intake part presses the diaphragm of the oil pressure sensor, the diaphragm is deformed.
- The gauge layer facing the diaphragm measures the deformation of the diaphragm by the change of its resistance, then converts the change of the resistance into a voltage and transmits it to the amplifier (voltage amplifier).
- The amplifier amplifies the received voltage and transmits it to the and pump controller.
- Relationship between pressure P (MPa {kg/cm²}) and output voltage (V) is as follows.
 V = 0.08 {0.008} x P + 0.5



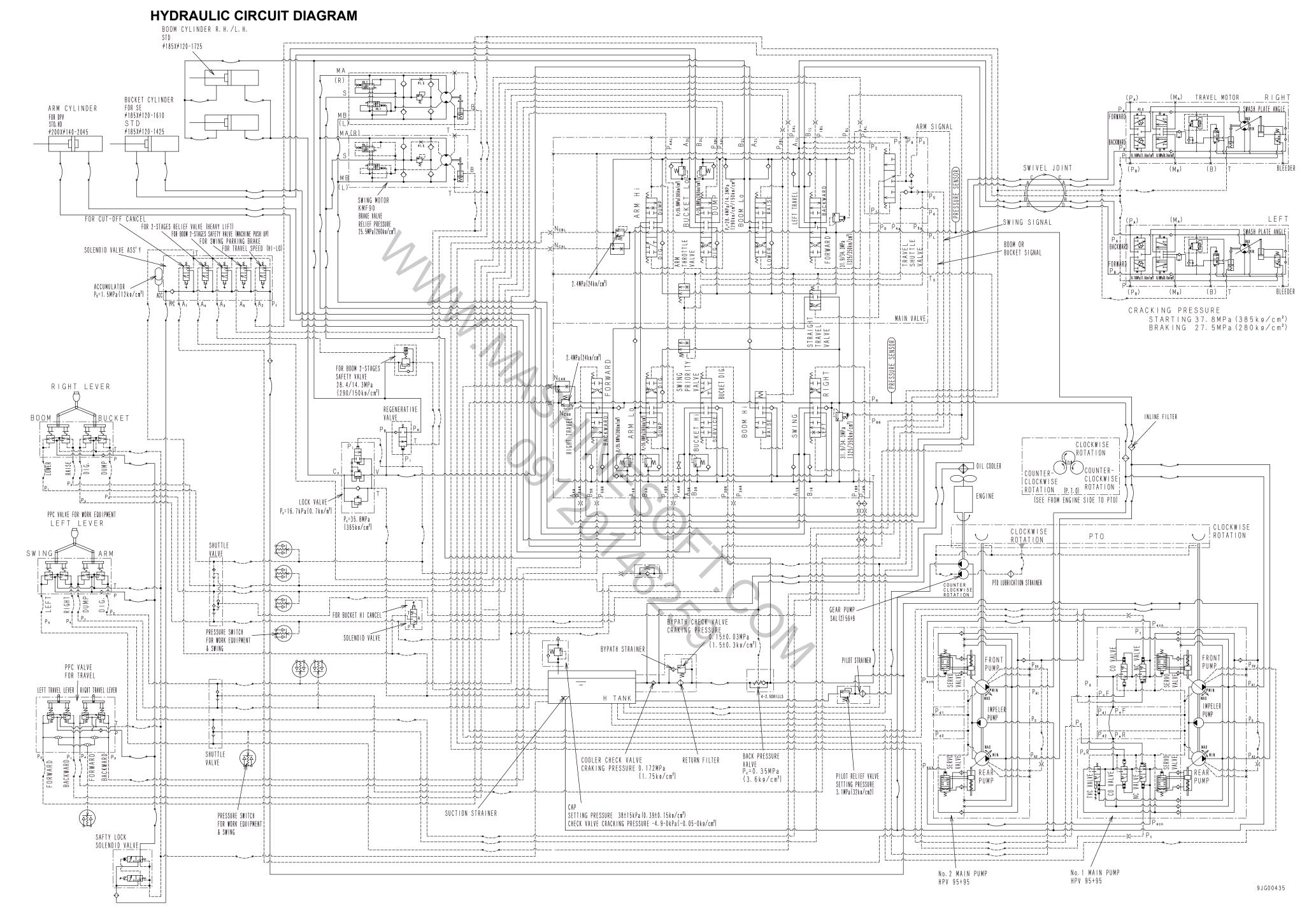
MMM MASHINGOTATION

90 OTHERS

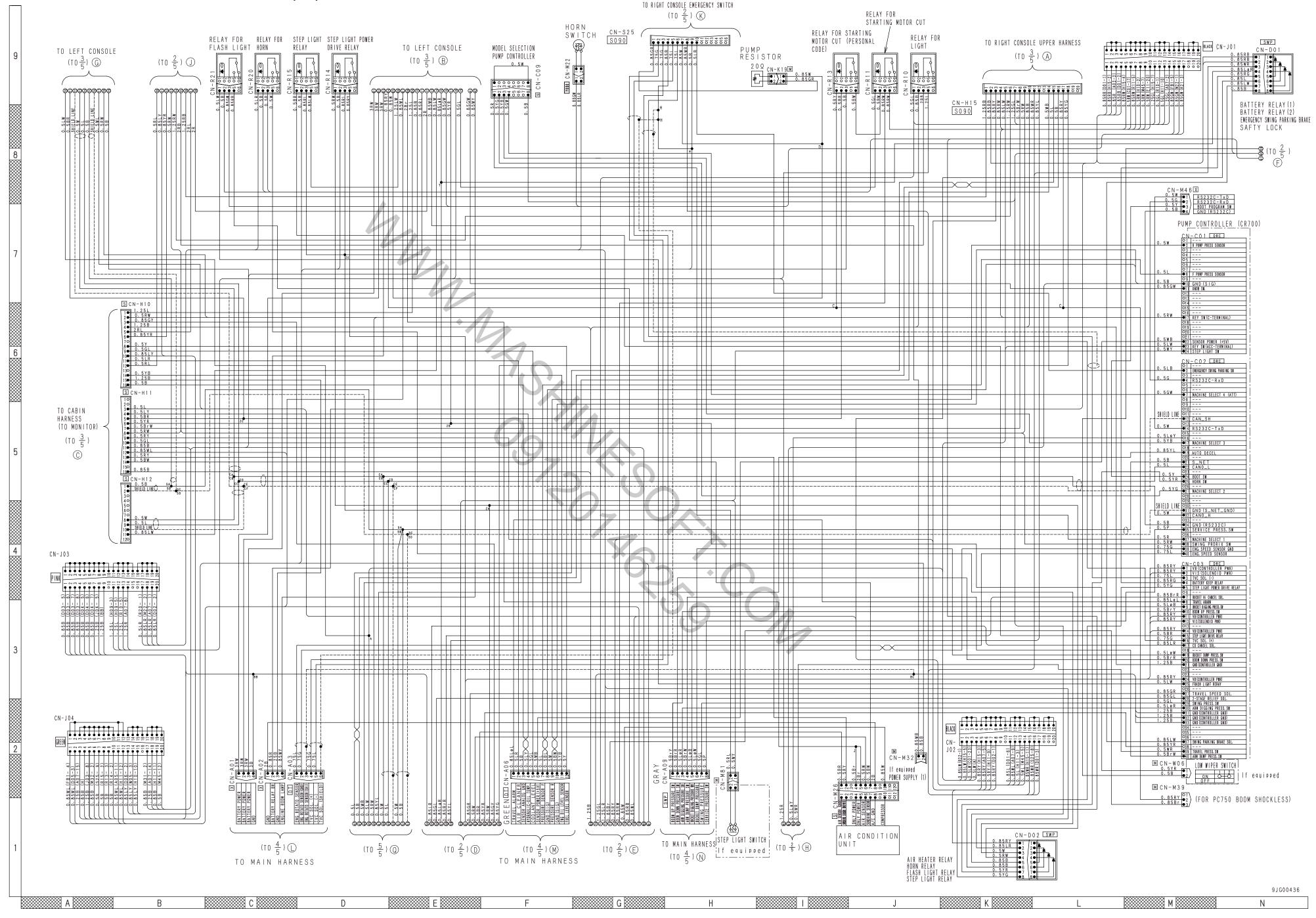
HYDRAULIC CIRCUIT DIAGRAM	
ELECTRICAL CIRCUIT DIAGRAM (1/5)	
ELECTRICAL CIRCUIT DIAGRAM (2/5)	
ELECTRICAL CIRCUIT DIAGRAM (3/5)	
ELECTRICAL CIRCUIT DIAGRAM (4/5)	90- 11
ELECTRICAL CIRCUIT DIAGRAM (5/5)	
ELECTRICAL CIRCUIT FOR AIR CONDITIONER	

4

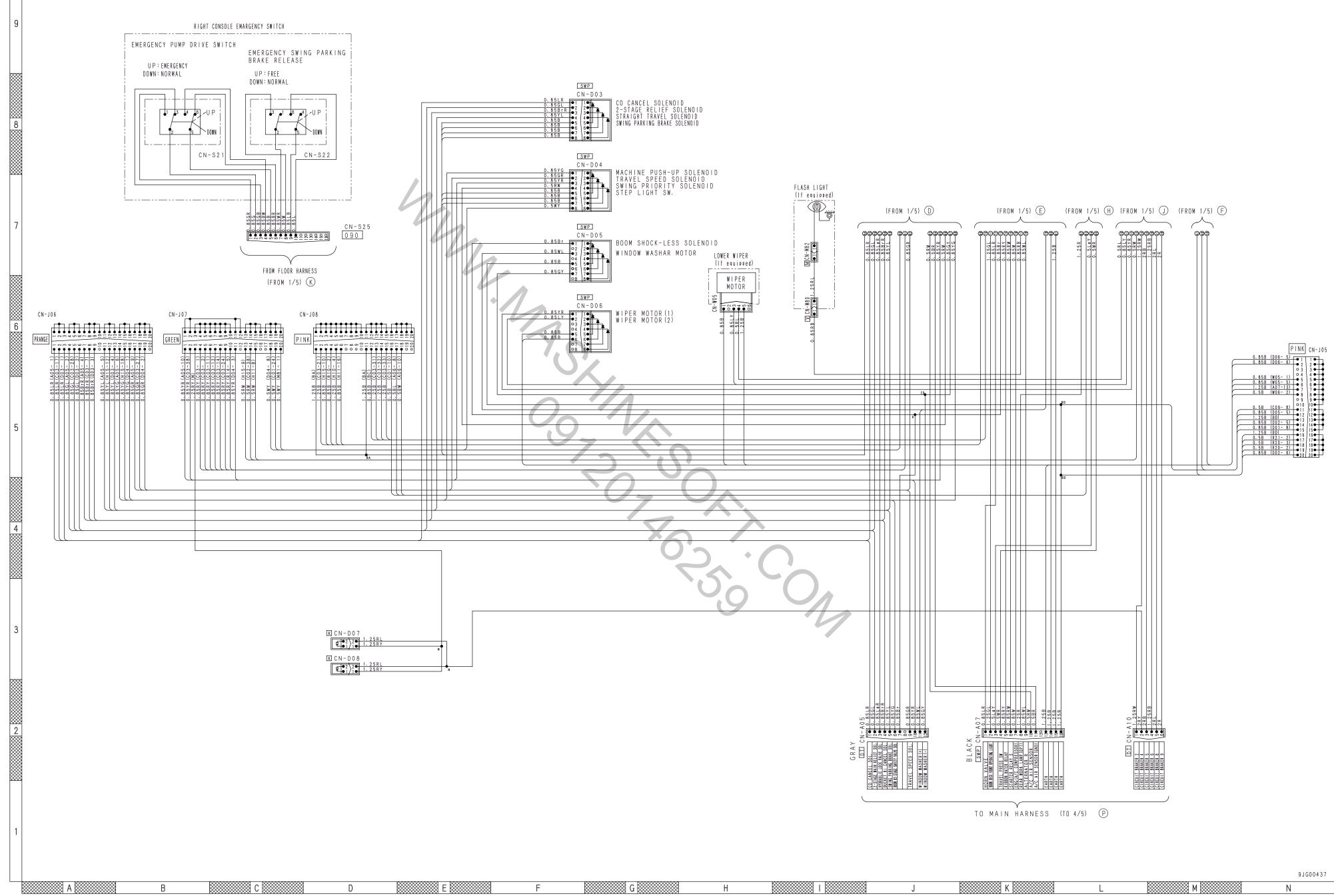
MMM MASHINGOTATION



ELECTRICAL CIRCUIT DIAGRAM (1/5)

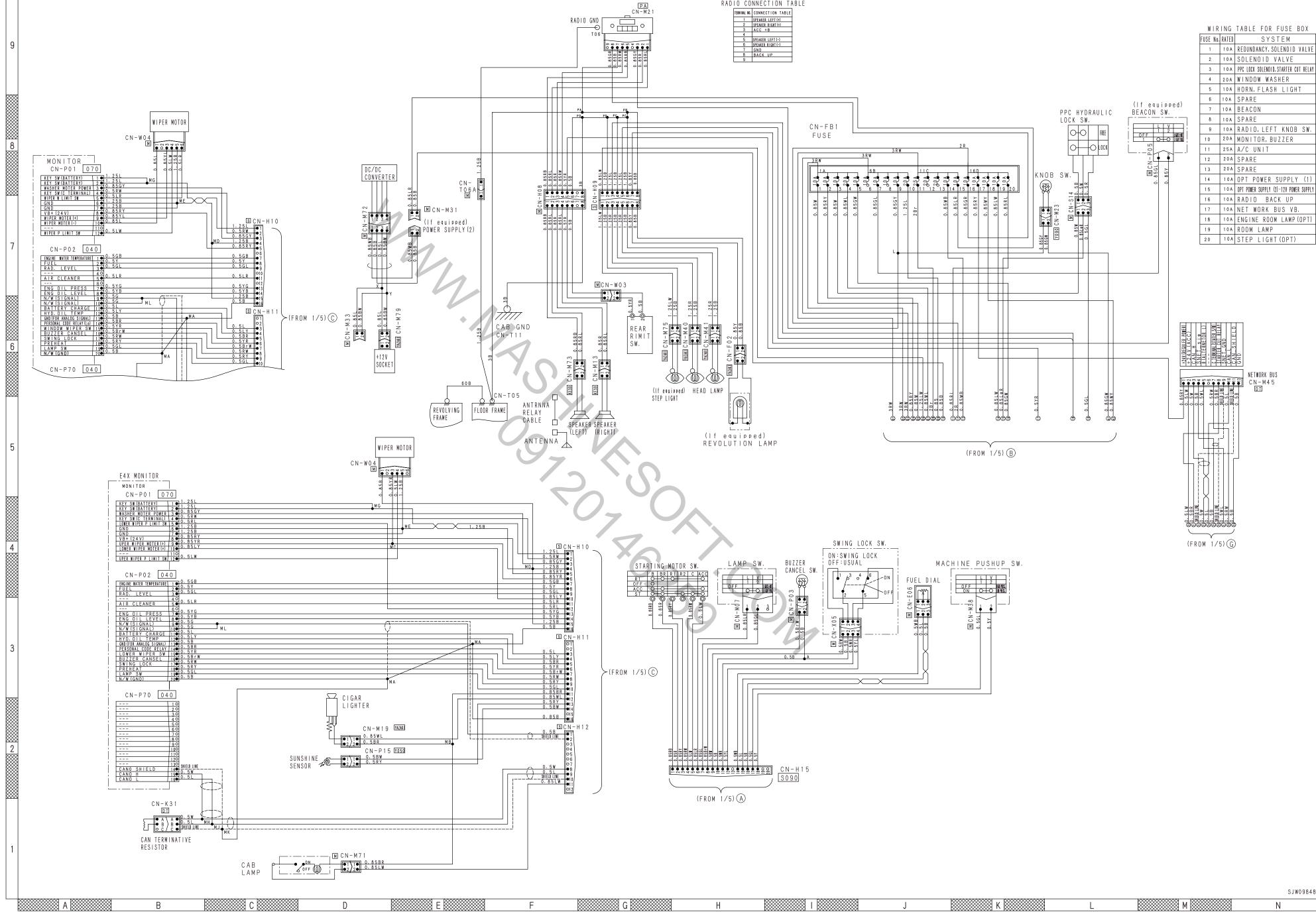


ELECTRICAL CIRCUIT DIAGRAM (2/5)





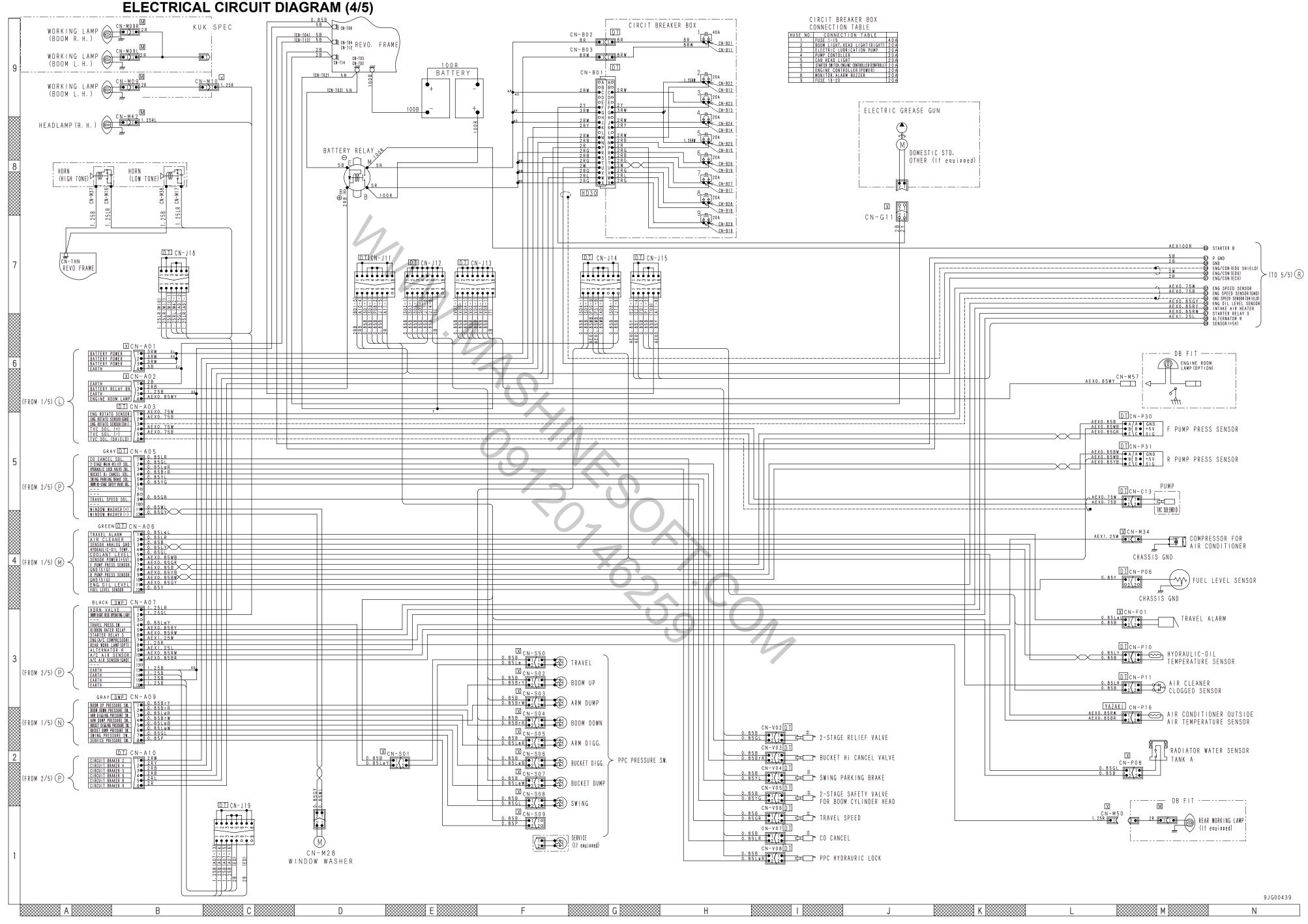
					9 J G 0 0 4 3 7
Н	J	К 🕅	L	M	Ν





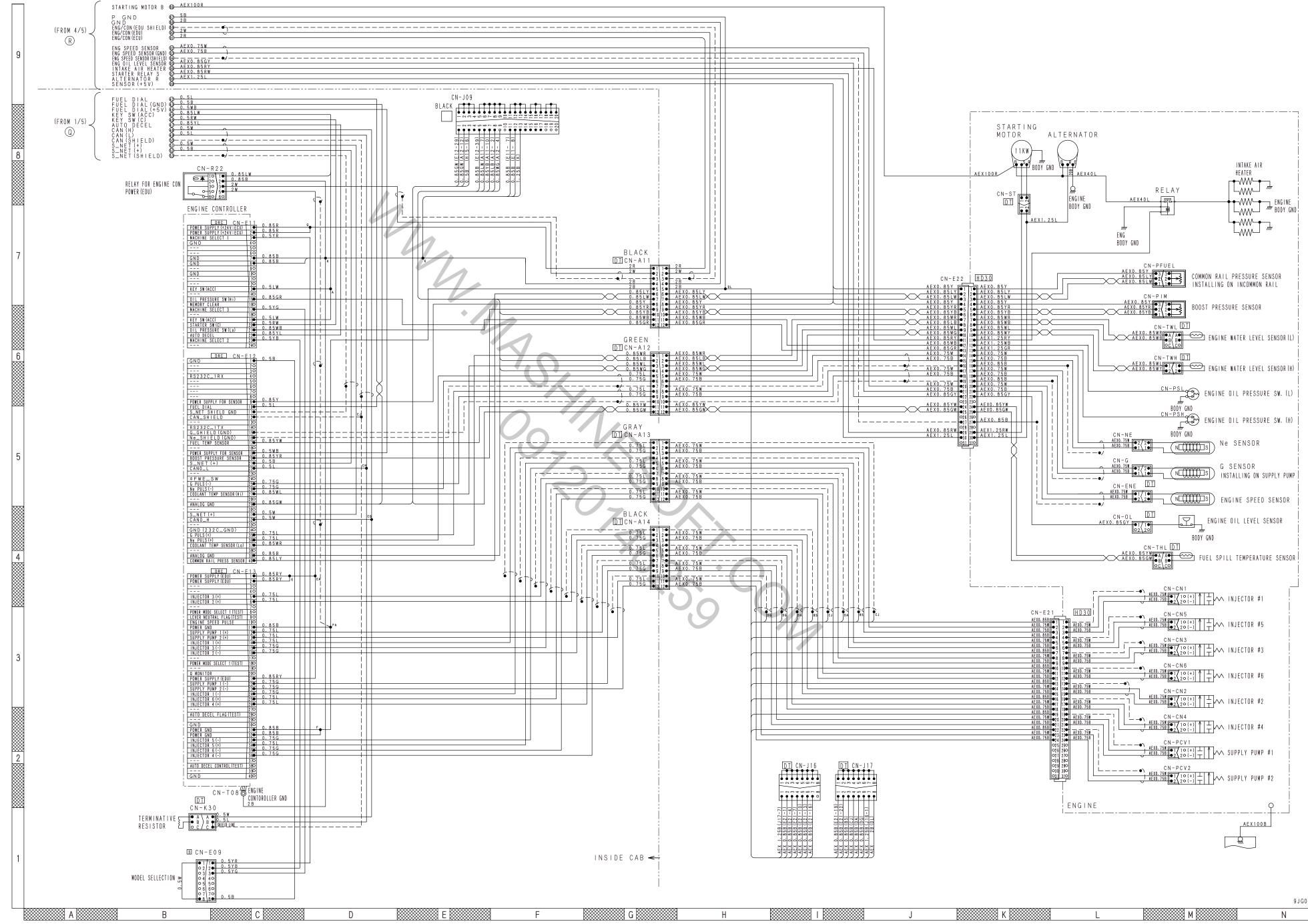
RADIO CONNECTION TABLE

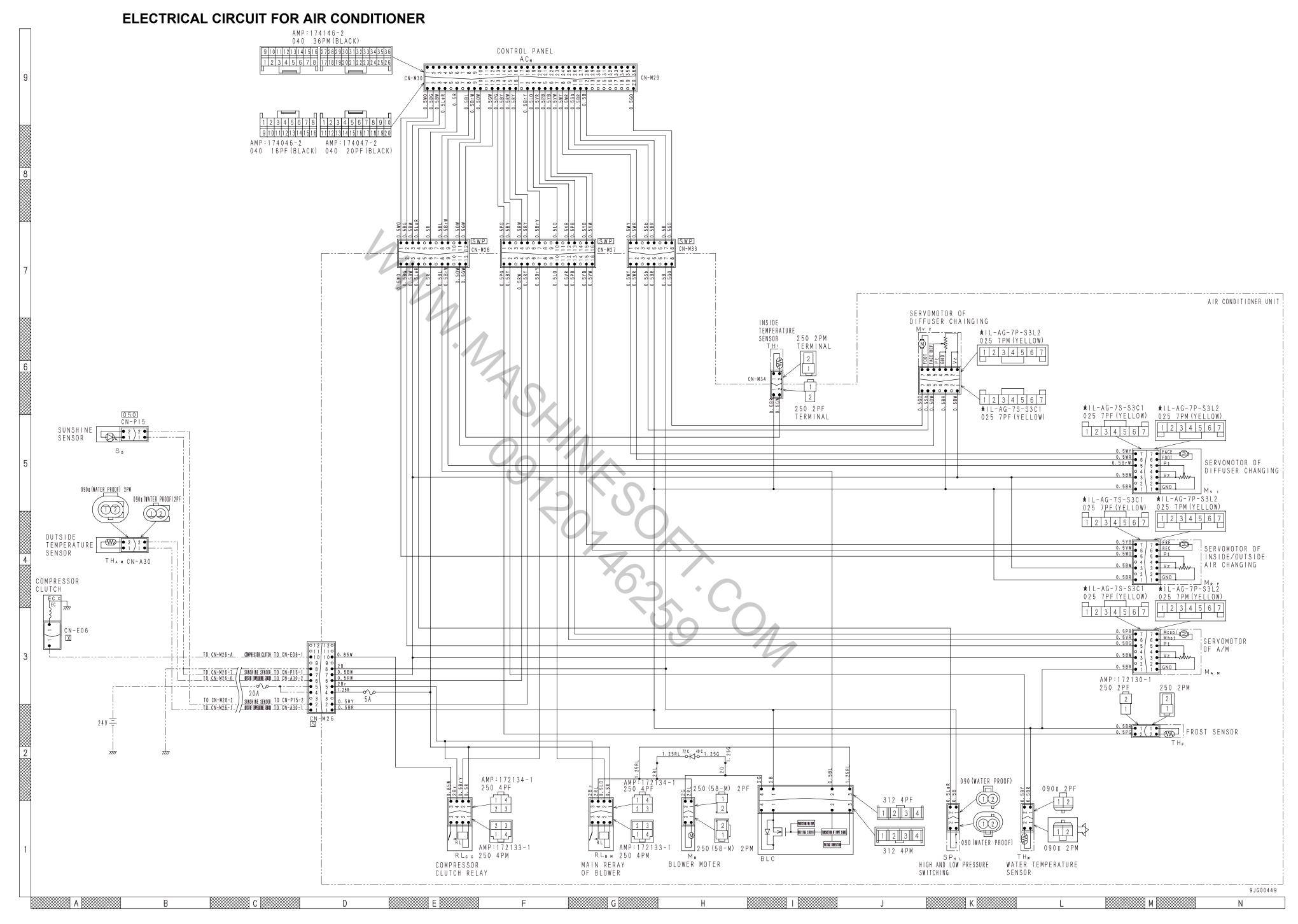
					SJW09848
Н	J	К 🕅	L	M	Ν



					91000439
Н	J	К	L	M	Ν

ELECTRICAL CIRCUIT DIAGRAM (5/5)





90-15